RoHS Compliant

Compact Flash Series Ⅲ

Industrial CF Specifications

September 10th, 2014

Version 1.5

Apacer Technology Inc.
1F, No.32, Zhongcheng Rd., Tucheng Dist., New Taipei City, Taiwan, R.O.C
Tel: +886-2-2267-8000 Fax: +886-2-2267-2261
www.apacer.com

© 2014 Apacer Technology Inc.

Compact Flash Ⅲ series

AP-CFxxxxE3NR-XXXXXXQ

Features:

- **Compact Flash Association Specification Revision 3.0 Standard Interface**
  - ATA command set compatible
  - ATA mode support for up to:
    PIO Mode-6
    Multiword DMA Mode-4
    Ultra DMA Mode-4
- **Connector Type**
  - 50 pins female
- **Power consumption (typical)***
  - Supply voltage: 3.3V & 5V
  - Active mode: 80 mA/95 mA (3.3V/5.0V)
  - Sleep mode: 700 µA/900 µA (3.3V/5.0V)
- **Performance***
  - Sustained read: up to 29 MB/sec
  - Sustained write: up to 15 MB/sec
- **Capacity**
  - 128, 256, 512 MB
    1, 2, 4, 8, 16 GB
- **NAND Flash Type: SLC**
- **Shock & Vibration****
  - Shock: 1,500 G
  - Vibration: 15 G
- **Temperature ranges**
  - Operating:
    Standard: 0℃ to 70℃
    Extended: -40℃ to 85℃
  - Storage: -40℃ to 100℃
- **Flash management**
  - Advanced wear-leveling algorithms
  - S.M.A.R.T. technology
  - Built-in hardware ECC
  - Flash block management
  - Power failure management
- **Endurance (TBW: Terabytes Written)**
  - 128 MB: 3.3 TBW
  - 256 MB: 6.7 TBW
  - 512 MB: 12.9 TBW
  - 1 GB: 25.6 TBW
  - 2 GB: 38.4 TBW
  - 4 GB: 51.9 TBW
  - 8 GB: 69.8 TBW
  - 16 GB: 115.0 TBW
- **Physical Dimensions**
  - 36.4mm x 42.8mm x 3.3mm
- **RoHS compliant**

*Varies from capacities. The values addressed for Performance and Power consumptions are typical and may vary depending on settings and platforms.
**Non-operating

© 2014 Apacer Technology Inc.

Table of Contents

1. GENERAL DESCRIPTION 3

2. FUNCTIONAL BLOCK 3

3. PIN ASSIGNMENTS 4

4. PRODUCT SPECIFICATIONS 6

4.1 CAPACITY 6
4.2 PERFORMANCE SPECIFICATION 6
4.3 ENVIRONMENTAL SPECIFICATIONS 7
4.5 ENDURANCE 7

5. FLASH MANAGEMENT 8

5.1. ADVANCED WEAR-LEVELING ALGORITHMS 8
5.2 S.M.A.R.T. TECHNOLOGY 8
5.3 BUILT-IN HARDWARE ECC 8
5.4 FLASH BLOCK MANAGEMENT 8
5.5 POWER FAILURE MANAGEMENT 8

6. SOFTWARE INTERFACE 9

6.1 COMMAND SET 9

7. ELECTRICAL SPECIFICATION 11

7.1 DC CHARACTERISTICS 12
7.2 AC CHARACTERISTICS 13
7.2.1 Attribute Memory Read Timing Specification 14
7.2.2 Configuration Register (Attribute Memory) Write Specification 15
7.2.3 Common Memory Read Timing Specification 16
7.2.4 Common Memory Write Timing Specification 17
7.2.5 I/O Input (Read) Timing Specification 18
7.2.6 I/O Output (Write) Timing Specification 19
7.2.7 True IDE I/O Read Timing 20
7.2.8 True IDE I/O Write Timing 21
7.2.9 Ultra DMA Mode Data Transfer Input/Output (Read/Write) Timing 22
7.3.0 Media Side Interface I/O Timing Specifications 34

8. PHYSICAL CHARACTERISTICS 37

8.1 DIMENSION 37

9. PRODUCT ORDERING INFORMATION 38

9.1 PRODUCT CODE DESIGNATIONS 38
9.2 VALID COMBINATIONS 39

© 2014 Apacer Technology Inc.

1. General Description

Apacer's value-added Industrial CompactFlash Card offers high performance, high reliability and power-efficient storage. Regarding standard compliance, this CompactFlash Card complies with CompactFlash specification revision 3.0, supporting transfer modes up to Programmed Input Output (PIO) Mode 6, Multi-word Direct Memory Access (DMA) Mode 4, and Ultra DMA Mode 4.

Apacer's value-added CFC provides complete PCMCIA – ATA functionality and compatibility. Apacer 's CompactFlash technology is designed for applications in Point of Sale (POS) terminals, telecom, IP-STB, medical instruments, surveillance systems, industrial PCs and handheld applications.

2. Functional Block

The Compact Flash Card (CFC) includes a controller and flash media, as well as the Compact Flash standard interface. Figure 2-1 shows the functional block diagram.

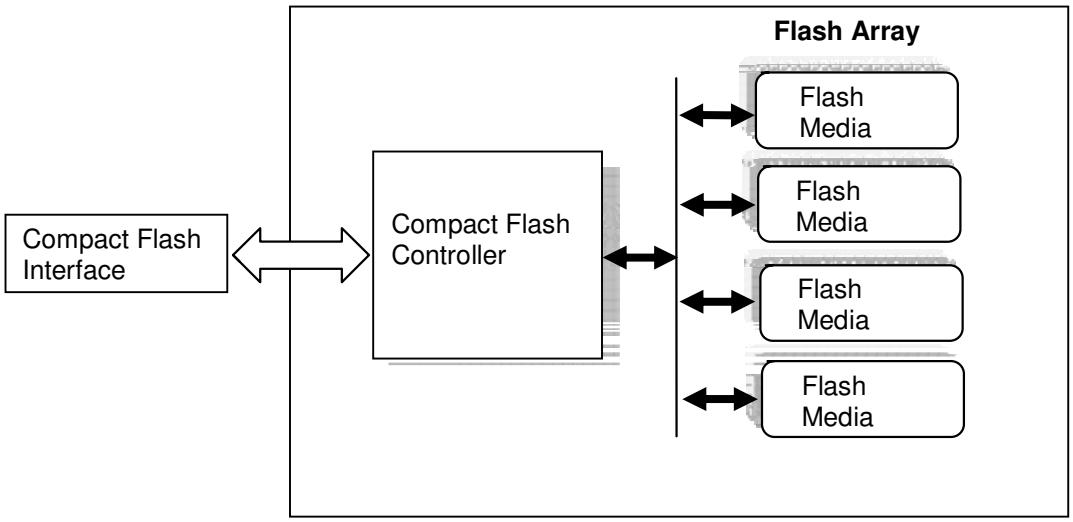


Figure 2-1: Functional block diagram

© 2014 Apacer Technology Inc.

3. Pin Assignments

Table 3-1 lists the pin assignments with respective signal names for the 50-pin configuration. A "#" suffix indicates the active low signal. The pin type can be input, output or input/output.

Table 3-1: Pin assignments (1 of 2)

Pin No.	Memory card mode		I/O card mode		True IDE mode	
	Signal name	Pin I/O type	Signal name	Pin I/O type	Signal name	Pin I/O type
1	GND	-	GND	-	GND	-
2	D3	I/O	D3	I/O	D3	I/O
3	D4	I/O	D4	I/O	D4	I/O
4	D5	I/O	D5	I/O	D5	I/O
5	D6	I/O	D6	I/O	D6	I/O
6	D7	I/O	D7	I/O	D7	I/O
7	-CE1	I	-CE1	I	-CS0	I
8	A10	I	A10	I	A10[2]	I
9	-OE	I	-OE	I	-ATA SEL	I
10	A9	I	A9	I	A9[2]	I
11	A8	I	A8	I	A8[2]	I
12	A7	I	A7	I	A7[2]	I
13	VCC	-	VCC	-	VCC	-
14	A6	I	A6	I	A6[2]	I
15	A5	I	A5	I	A5[2]	I
16	A4	I	A4	I	A4[2]	I
17	A3	I	A3	I	A3[2]	I
18	A2	I	A2	I	A2	I
19	A1	I	A1	I	A1	I
20	A0	I	A0	I	A0	I
21	D0	I/O	D0	I/O	D0	I/O
22	D1	I/O	D1	I/O	D1	I/O
23	D2	I/O	D2	I/O	D2	I/O
24	WP	O	-IOCS16	O	-IOCS16	O
25	-CD2	O	-CD2	O	-CD2	O
26	-CD1	O	-CD1	O	-CD1	O
27	D11[1]	I/O	D11[1]	I/O	D11[1]	I/O
28	D12[1]	I/O	D12[1]	I/O	D12[1]	I/O
29	D13[1]	I/O	D13[1]	I/O	D13[1]	I/O
30	D14[1]	I/O	D14[1]	I/O	D14[1]	I/O
31	D15[1]	I/O	D15[1]	I/O	D15[1]	I/O
32	-CE2[1]	I	-CE2[1]	I	-CS1[1]	I
33	-VS1	O	-VS1	O	-VS1	O
34	-IORD	I	-IORD	I	-IORD[7] HSTROBE[8] -HDMARDY[9]	I
35	-IOWR	I	-IOWR	I	-IOWR[7] STOP[8,9]	I
36	-WE	I	-WE	I	-WE[3]	I
37	READY	O	-IREQ	O	INTRQ	O
38	VCC	-	VCC	-	VCC	-
39	-CSEL[5]	I	-CSEL[5]	I	-CSEL	I
40	-VS2	O	-VS2	O	-VS2	O
41	RESET	I	RESET	I	-RESET	I

© 2014 Apacer Technology Inc.

Table 3-1: Pin assignments (2 of 2)

Pin No.	Memory card mode		I/O card mode		True IDE mode	
	Signal name	Pin I/O type	Signal name	Pin I/O type	Signal name	Pin I/O type
42	-WAIT	O	-WAIT	O	IORDY[7] -DDMARDY[8] DSTROBE[9]	O
43	-INPACK	O	-INPACK	O	DMARQ	O
44	-REG	I	-REG	I	-DMACK[6]	I
45	BVD2	O	-SPKR	O	-DASP	I/O
46	BVD1	O	-STSCHG	O	-PDIAG	I/O
47	D8[1]	I/O	D8[1]	I/O	D8[1]	I/O
48	D9[1]	I/O	D9[1]	I/O	D9[1]	I/O
49	D10[1]	I/O	D10[1]	I/O	D10[1]	I/O
50	GND	-	GND	-	GND	-

Notes:
1. These signals are required only for 16 bit accesses and not required when installed in 8 bit systems. Devices should allow for 3-state signals not to consume current.
2. The signals should be grounded by the host.
3. The signal should be tied to VCC by the host.
4. The mode is optional for CF+ cards, but required for CompactFlash storage cards
5. The –CSEL signal is ignored by the card in PC card modes. However, because it is not pulled up on the card in these modes, it should not be left floating by the host in PC card modes. In these modes, the pin should be connected by the host to PC card A25 or grounded by the host.
6. If DMA operations are not used, the signal should be held high or tied to VCC by the host. For proper operation in older hosts: while DMA operations are not active, the card shall ignore this signal, including a floating condition.
7. Signal usage in True IDE mode except when Ultra DMA mode protocol is active
8. Signal usage in True IDE mode when Ultra DMA mode protocol DMA write is active
9. Signal usage in True IDE mode when Ultra DMA mode protocol DMA read is active.

© 2014 Apacer Technology Inc.

4. Product Specifications

4.1 Capacity

Capacity specification of the Compact Flash Card series (CFC) is available as shown in Table 4-1. It lists the specific capacity and the default numbers of heads, sectors and cylinders for each product line.

Table 4-1: Capacity specifications

Capacity	Total bytes[1,2]	Cylinders	Heads	Sectors	Max LBA
128 MB	128,450,560	980	8	32	250,880
256 MB	256,901,120	980	16	32	501,760
512 MB	512,483,328	993	16	63	1,000,944
1GB	1,024,966,656	1,986	16	63	2,001,888
2GB	2,048,901,120	3,970	16	63	4,001,760
4GB	4,110,188,544	7,964	16	63	8,027,712
8GB	8,195,604,480	15,880	16	63	16,007,040
16GB	16,391,208,960	16,383[3]	16	63	32,014,080

Notes:
Display of total bytes varies from operating systems.
Cylinders, heads or sectors are not applicable for these capacities. Only LBA addressing applies
Notes: 1 GB = 1,000,000,000 bytes; 1 sector = 512 bytes.
LBA count addressed in the table above indicates total user storage capacity and will remain the same throughout the lifespan of the device. However, the total usable capacity of the SSD is most likely to be less than the total physical capacity because a small portion of the capacity is reserved for device maintenance usages.

4.2 Performance Specification

Performances of the CF cards are listed in Table 4-2

Table 4-2: Performance specifications

Capacity / Performance	128 MB	256 MB	512 MB	1 GB	2 GB	4 GB	8 GB	16 GB
Sustained read (MB/s)	17	29	19	21	20	21	21	20
Sustained write (MB/s)	4	8	7	12	11	11	13	15

Notes: performance may vary depending on flash configurations or host system settings.

© 2014 Apacer Technology Inc.

4.3 Environmental Specifications

Environmental specification of the Compact Flash Card series (CFC) follows the MIL-STD-810F standards as shown in Table 4-3.

Table 4-3: Environmental specifications

Environment		Specification
Temperature	Operation	0℃ to 70℃; -40℃ to 85℃ (Extended Temperature)
	Storage	-40℃ to 100℃
Humidity		5% to 95% RH (Non-condensing)
Vibration (Non-Operation)		Sine wave : 10~2000Hz, 15G (X, Y, Z axes)
Shock (Non-Operation)		Half sine wave 1,500G (X, Y, Z ; All 6 axes)

4.4 Certification & Compliance

The CompactFlash card complies with the following global standards:

- CE
- FCC
- RoHS

4.5 Endurance

The endurance of a storage device is predicted by TeraBytes Written based on several factors related to usage, such as the amount of data written into the drive, block management conditions, and daily workload for the drive. Thus, key factors, such as Write Amplifications and the number of P/E cycles, can influence the lifespan of the drive.

Capacity	TeraBytes Written
128 MB	3.3
256 MB	6.7
512 MB	12.9
1 GB	25.6
2 GB	38.4
4 GB	51.9
8 GB	69.8
16 GB	115.0

Notes:

- The measurement assumes the data written to the SSD for test is under a typical and constant rate.
- The measurement follows the standard metric: 1 TB (Terabyte) = 1000 GB.

© 2014 Apacer Technology Inc.

5. Flash Management

5.1. Advanced wear-leveling algorithms

Flash memory devices differ from Hard Disk Drives (HDDs) in terms of how blocks are utilized. For HDDs, when a change is made to stored data, like erase or update, the controller mechanism on HDDs will perform overwrites on blocks. Unlike HDDs, flash blocks cannot be overwritten and each P/E cycle wears down the lifespan of blocks gradually. Repeatedly program/erase cycles performed on the same memory cells will eventually cause some blocks to age faster than others. This would bring flash storages to their end of service term sooner. Wear leveling is an important mechanism that level out the wearing of blocks so that the wearing-down of blocks can be almost evenly distributed. This will increase the lifespan of SSDs. Commonly used wear leveling types are Static and Dynamic.

5.2 S.M.A.R.T. technology

S.M.A.R.T. is an acronym for Self-Monitoring, Analysis and Reporting Technology, an open standard allowing disk drives to automatically monitor their own health and report potential problems. It protects the user from unscheduled downtime by monitoring and storing critical drive performance and calibration parameters. Ideally, this should allow taking proactive actions to prevent impending drive failure. Apacer SMART feature adopts the standard SMART command B0h to read data from the drive. When the Apacer SMART Utility running on the host, it analyzes and reports the disk status to the host before the device is in critical condition.

5.3 Built-in hardware ECC

The ATA-Disk Module uses BCH Error Detection Code (EDC) and Error Correction Code (ECC) algorithms which correct up to eight random single-bit errors for each 512-byte block of data. High performance is fulfilled through hardware-based error detection and correction.

5.4 Flash block management

Current production technology is unable to guarantee total reliability of NAND flash memory array. When a flash memory device leaves factory, it comes with a minimal number of initial bad blocks during production or out-of-factory as there is no currently known technology that produce flash chips free of bad blocks. In addition, bad blocks may develop during program/erase cycles. When host performs program/erase command on a block, bad block may appear in Status Register. Since bad blocks are inevitable, the solution is to keep them in control. Apacer flash devices are programmed with ECC, block mapping technique and S.M.A.R.T to reduce invalidity or error. Once bad blocks are detected, data in those blocks will be transferred to free blocks and error will be corrected by designated algorithms.

5.5 Power Failure Management

Power Failure Management plays a crucial role when experiencing unstable power supply. Power disruption may occur when users are storing data into the SSD. In this urgent situation, the controller would run multiple write-to-flash cycles to store the metadata for later block rebuilding. This urgent operation requires about several milliseconds to get it done. At the next power up, the firmware will perform a status tracking to retrieve the mapping table and resume previously programmed NAND blocks to check if there is any incompleteness of transmission.

© 2014 Apacer Technology Inc.

6. Software Interface

6.1 Command Set

Table 6-1 summarizes the command set with the paragraphs that follow describing the individual commands and the task file for each.

Table 6-1: Command set

Command	Code	FR[1]	SC[2]	SN[3]	CY[4]	DH[5]	LBA[6]
Check-Power-Mode	E5h or 98h	-	-	-	-	D[8]	-
Execute-Drive-Diagnostic	90h	-	-	-	-	D	-
Erase Sector(s)	C0h	-	Y	Y	Y	Y	Y
Flush-Cache	E7h	-	-	-	-	D	-
Format Track	50h	-	Y[7]	-	Y	Y[8]	Y
Identify-Drive	ECh	-	-	-	-	D	-
Idle	E3h or 97h	-	Y	-	-	D	-
Idle-Immediate	E1h or 95h	-	-	-	-	D	-
Initialize-Drive-Parameters	91h	-	Y	-	-	Y	-
NOP	00h	-	-	-	-	D	-
Read-Buffer	E4h	-	-	-	-	D	-
Read-DMA	C8h or C9h	-	Y	Y	Y	Y	Y
Read-Multiple	C4h	-	Y	Y	Y	Y	Y
Read-Sector(s)	20h or 21h	-	Y	Y	Y	Y	Y
Read-Verify-Sector(s)	40h or 41h	-	Y	Y	Y	Y	Y
Recalibrate	1Xh	-	-	-	-	D	-
Request-Sense	03h	-	-	-	-	D	-
Seek	7Xh	-	-	Y	Y	Y	Y
Set-Features	EFh	Y[7]	-	-	-	D	-
SMART	B0h	Y	Y	Y	Y	D	
Set-Multiple-Mode	C6h	-	Y	-	-	D	-
Set-Sleep-Mode	E6h or 99h	-	-	-	-	D	-
Standby	E2h or 96h	-	-	-	-	D	-
Standby-Immediate	E0h or 94h	-	-	-	-	D	-
Translate-Sector	87h	-	Y	Y	Y	Y	Y
Write-Buffer	E8h	-	-	-	-	D	-
Write-DMA	CAh or CBh	-	Y	Y	Y	Y	Y
Write-Multiple	C5h	-	Y	Y	Y	Y	Y
Write-Multiple-Without-Erase	CDh	-	Y	Y	Y	Y	Y

© 2014 Apacer Technology Inc.

Write-Sector(s)	30h or 31h	-	Y	Y	Y	Y	Y
Write-Sector-Without-Erase	38h	-	Y	Y	Y	Y	Y
Write-Verify	3Ch	-	Y	Y	Y	Y	Y

1. FR - Features register
2. SC - Sector Count register
3. SN - Sector Number register
4. CY - Cylinder registers
5. DH - Drive/Head register
6. LBA - Logical Block Address mode supported (see command descriptions for use)
7. Y - The register contains a valid parameter for this command
8. For the Drive/Head register:
Y means both the CFC and Head parameters are used
D means only the CFC parameter is valid and not the Head parameter

© 2014 Apacer Technology Inc.

7. Electrical Specification

Caution: **Absolute Maximum Stress Ratings –** Applied conditions greater than those listed under "Absolute Maximum Stress Ratings" may cause permanent damage to the device. This is a stress rating only and functional operation of the device at these conditions or conditions greater than those defined in the operational sections of this data sheet is not implied. Exposure to absolute maximum stress rating conditions may affect device reliability.

Table 7-1: Operating range

Standard Operating Temperature	0℃ to +70℃
Extended Operating Temperature	-40℃ to +85℃
Supply voltage	5 (4.75-5.25V)
	3.3V (3.135-3.465V)

Table 7-2: Absolute maximum power pin stress ratings

Parameter	Symbol	Conditions
Input Power	V_{DD}	-0.3V min. to 6.5V max.
Voltage on any pin except V_{DD} with respect to GND	V	-0.5V min. to VDD + 0.5V max.

Table 7-3: Recommended system power-up timing

Symbol	Parameter	Typical	Maximum	Units
$T_{PU-READY}$[1]	Power-up to Ready Operation	200	1000	ms
$T_{PU-WRITE}$[1]	Power-up to Write Operation	200	1000	ms

1. This parameter is measured only for initial qualification and after a design or process change that could affect this parameter.

© 2014 Apacer Technology Inc.

7.1 DC Characteristics

Table 7-4: DC Characteristics

Symbol	Type	Parameter	Min	Max	Units	Conditions
V_{IH1} V_{IL1}	I1	Input Voltage	2.0V	 0.8V	V	V_{DDQ}=V_{DDQ} Max V_{DDQ}=V_{DDQ} Min
I_{IL1}	I1Z	Input Leakage Current	-10	10	μA	V_{IN}=GND to V_{DDQ} V_{DDQ}= V_{DDQ} Max
I_{U1}	I1U	Input Pull-Up Current	-110	-1	μA	V_{OUT}=GND, V_{DDQ}= V_{DDQ} Max
V_{T+2} V_{T-2}	I2	Input Voltage Schmitt Trigger	 0.8	2.0	V	V_{DDQ}=V_{DDQ} Max V_{DDQ}=V_{DDQ} Min
I_{IL2}	I2Z	Input Leakage Current	-10	10	μA	V_{IN}=GND to V_{DDQ} V_{DDQ}= V_{DDQ} Max
I_{U2}	I2U	Input Pull-Up Current	-110	-1	μA	V_{OUT}=GND, V_{DDQ}= V_{DDQ} Max
V_{OH1} V_{OL1}	O1	Output Voltage	2.4	 0.4	V	I_{OH1}=I_{OH1} Min I_{OL1}=I_{OL1} Max
I_{OH1}		Output Current	-4		mA	V_{DDQ}=V_{DDQ} Min
I_{OL1}		Output Current		4	mA	V_{DDQ}=V_{DDQ} Min
V_{OH2} V_{OL2}	O2	Output Voltage	2.4	 0.4	V	I_{OH2}=I_{OH2} Min I_{OL2}=I_{OL2} Max
I_{OH2}		Output Current	-6		mA	V_{DDQ}=3.135V-3.465V
I_{OL2}		Output Current		6	mA	V_{DDQ}=3.135V-3.465V
I_{OH2}		Output Current	-8		mA	V_{DDQ}=4.5V-5.5V
I_{OL2}		Output Current		8	mA	V_{DDQ}=4.5V-5.5V
V_{OH6} V_{OL6}	O6	Output Voltage for DASP# pin	2.4	 0.4	V	I_{OH6}=I_{OH6} Min I_{OL6}=I_{OL6} Max
I_{OH6}		Output Current for DASP# pin	-3		mA	V_{DDQ}=3.135V-3.465V
I_{OL6}		Output Current for DASP# pin		8	mA	V_{DDQ}=3.135V-3.465V
I_{OH6}		Output Current for DASP# pin	-3		mA	V_{DDQ}=4.5V-5.5V
I_{OL6}		Output Current for DASP# pin		12	mA	V_{DDQ}=4.5V-5.5V
I_{DD}[1,2]	PWR	Power supply current (T_a = 0℃ to +70℃)		50	mA	V_{DD}=V_{DD} Max V_{DDQ}=V_{DDQ} Max
I_{DD}[1,2]	PWR	Power supply current (T_a= -40℃ to +85℃)		100	mA	V_{DD}=V_{DD} Max V_{DDQ}=V_{DDQ} Max
I_{SP}	PWR	Sleep/Standby/Idle current (T_a = 0℃ to +70℃)		100	μA	V_{DD}=V_{DD} Max V_{DDQ}=V_{DDQ} Max
I_{SP}	PWR	Sleep/Standby/Idle current (T_a = -40℃ to +85℃)		200	μA	V_{DD}=V_{DD} Max V_{DDQ}=V_{DDQ} Max

© 2014 Apacer Technology Inc.

7.2 AC Characteristics

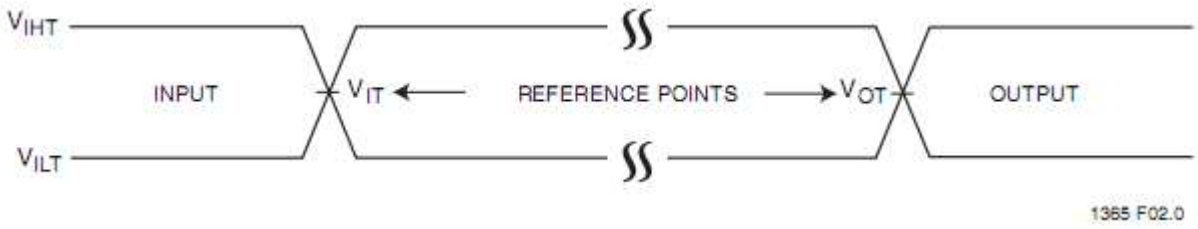


Figure 7-1: AC Input/Output Reference Waveforms

AC test inputs are driven at VIHT (0.9 VDD) for a logic “1” and VILT (0.1 VDD) for a logic “0”. Measurement reference points for inputs and outputs are VIT (0.5 VDD) and VOT (0.5 VDD). Input rise and fall times (10% ↔ 90%) are <10 ns.

Note: V_{IT} - V_{INPUT} Test
V_{OT} - V_{OUTPUT} Test
V_{IHT} - $V_{INPUT\ HIGH}$ Test
V_{ILT}- $V_{INPUT\ LOW}$ Test

© 2014 Apacer Technology Inc.

7.2.1 Attribute Memory Read Timing Specification

The Attribute Memory access time is defined as 100 ns. Detailed timing specifications are shown in the table below.

Table 7-5 Attribute Memory Read Timing Specification

Speed Version			100 ns		
Item	**Symbol**	**IEEE Symbol**	**Min[1]**	**Min[1]**	**Units**
Read Cycle Time	$T_{C(R)}$	tAVAV	100		ns
Address Access Time	$T_{A(A)}$	tAVQV		100	ns
Card Enable Access Time	$T_{A(CE)}$	tELQV		100	ns
Output Enable Access Time	$T_{A(OE)}$	tGLQV		50	ns
Output Disable Time from CE#	$T_{DIS(CE)}$	tEHQZ		50	ns
Output Disable Time from OE#	$T_{DIS(OE)}$	tGHQZ		50	ns
Address Setup Time	$T_{SU(A)}$	tAVGL	10		ns
Output Enable Time from CE#	$T_{EN(CE)}$	tELQNZ	5		ns
Output Enable Time from OE#	$T_{EN(OE)}$	tGLQNZ	5		ns
Data Valid from Address Change	$T_{V(A)}$	tAXQZ	0		ns

1. D_{OUT} signifies data provided by the Compact Flash card to the system. The CE# signal or both the OE# signal and the WE# signal must be de-asserted between consecutive cycle operations. All AC specifications are guaranteed by design.

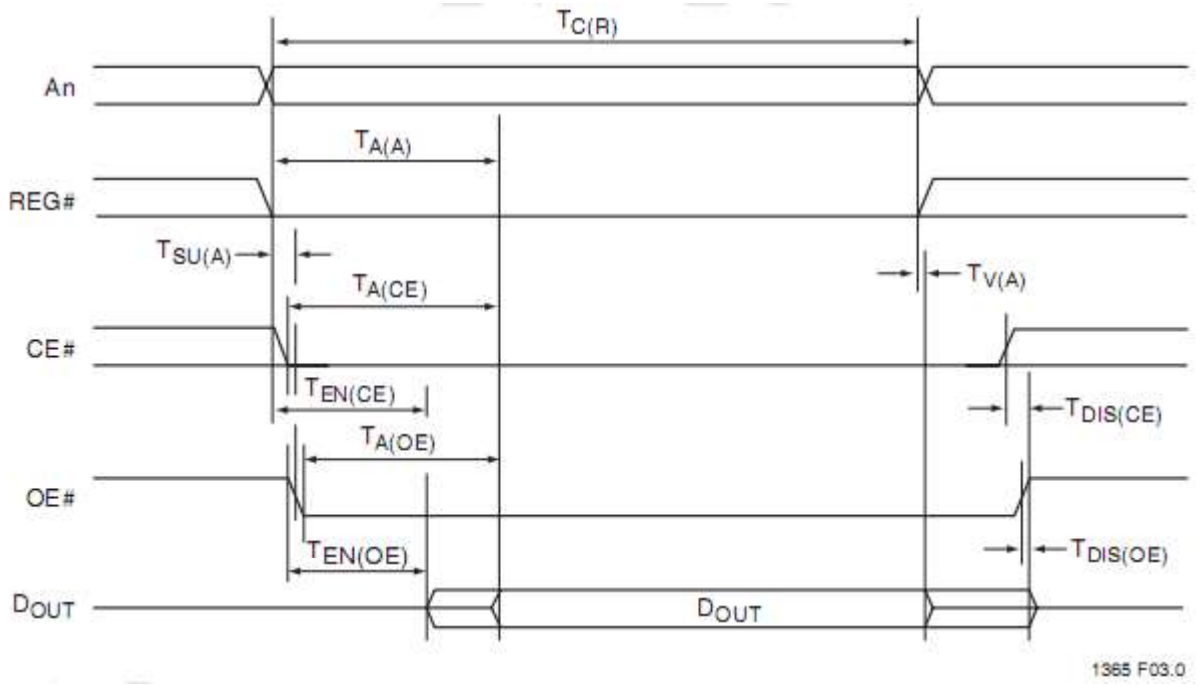


Figure 7-2: Attribute Memory Read Timing Diagram

© 2014 Apacer Technology Inc.

7.2.2 Configuration Register (Attribute Memory) Write Specification

The card configuration write access time is defined as 100 ns. Detailed timing specifications are shown in the table below.

Table 7-6 Configuration Register (Attribute Memory) Write Timing

Speed Version			**100 ns**		
Item	**Symbol**	**IEEE Symbol**	**Min**[1]	**Min**[1]	**Units**
Write Cycle Time	$T_{C(W)}$	tAVAV	100		ns
Write Pulse Width	$T_{W(WE)}$	tWLWH	60		ns
Address Setup Time	$T_{SU(A)}$	tAVWL	10		ns
Write Recover Time	$T_{REC(WE)}$	tWMAX	15		ns
Data Setup Time for WE	$T_{SU(DWE\#H)}$	tDVWH	40		ns
Data Hold Time	$T_{H(D)}$	tWMDX	15		ns

1. D_{IN} signifies data provided by the system to the Compact Flash card. All AC specifications are guaranteed by design.

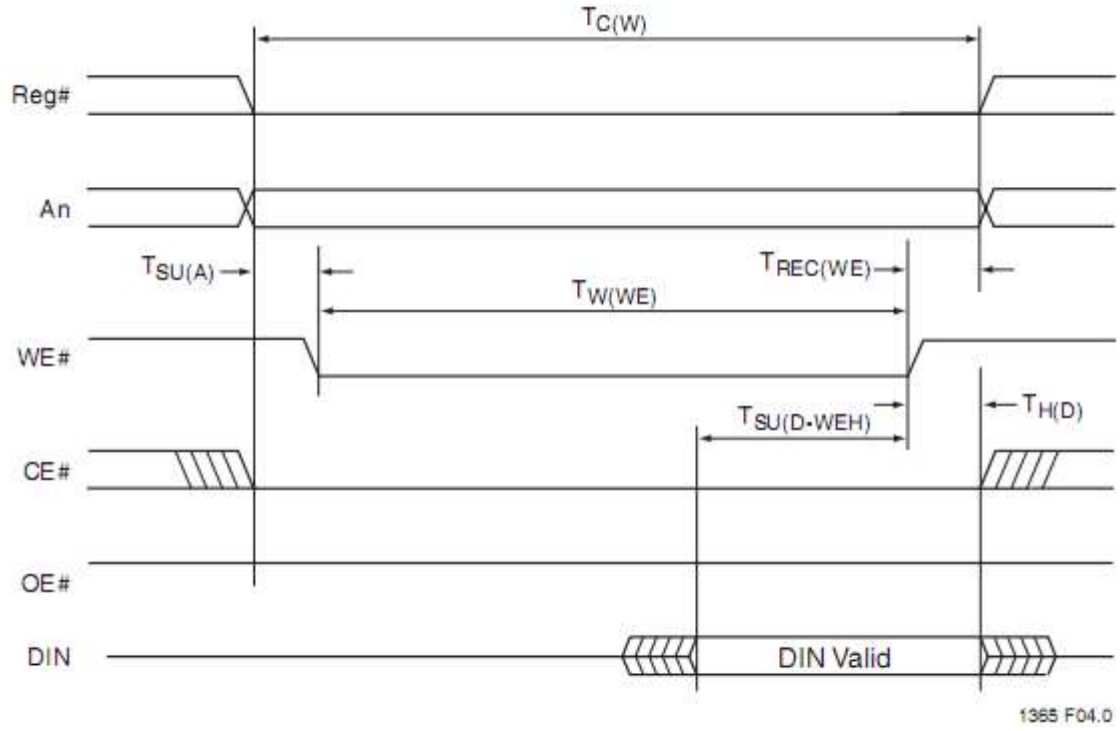


Figure 7-3: Configuration Register (Attribute Memory) Write Timing Diagram

© 2014 Apacer Technology Inc.

7.2.3 Common Memory Read Timing Specification

Table 7-7 Common Memory Read Timing

Item	Symbol	IEEE Symbol	Min[1]	Min[1]	Units
Output Enable Access Time	$T_{A(OE)}$	tGLQV		50	ns
Output Disable Time from OE	$T_{DIS(OE)}$	tGHQZ		50	ns
Address Setup Time	$T_{SU(A)}$	tAVGL	10		ns
Address Hold Time	$T_{REC(WE)}$	tGHAX	15		ns
CE Setup before OE	$T_{SU(CE)}$	tELGL	0		ns
CE Hold following OE	$T_{H(CE)}$	tGHEH	15		ns

1. All AC specifications are guaranteed by design.

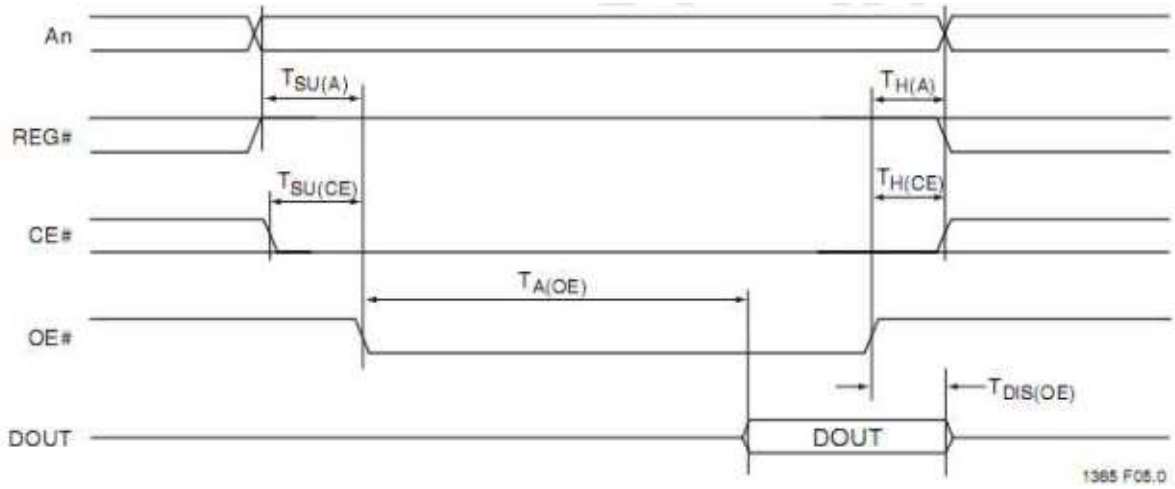


Figure 7-4: Common Memory Read Timing Diagram

© 2014 Apacer Technology Inc.

7.2.4 Common Memory Write Timing Specification

Table 7-8 Common Memory Write Timing

Item	Symbol	IEEE Symbol	Min[1]	Min[1]	Units
Data Setup before WE	$T_{SU(DWE\#H)}$	tDVWH	40		ns
Data Hold following WE	$T_{H(D)}$	tWMDX	15		ns
WE Pulse Width	$T_{W(WE)}$	tWLWH	60		ns
Address Setup Time	$T_{SU(A)}$	tAVWL	10		ns
CE Setup before WE	$T_{SU(CE)}$	tELWL	0		ns
Write Recovery Time	$T_{REC(WE)}$	tWMAX	15		ns
Address Hold Time	$T_{H(A)}$	tGHAX	15		ns
CE Hold following WE	$T_{H(CE)}$	tGHEH	15		ns

1. All AC specifications are guaranteed by design.

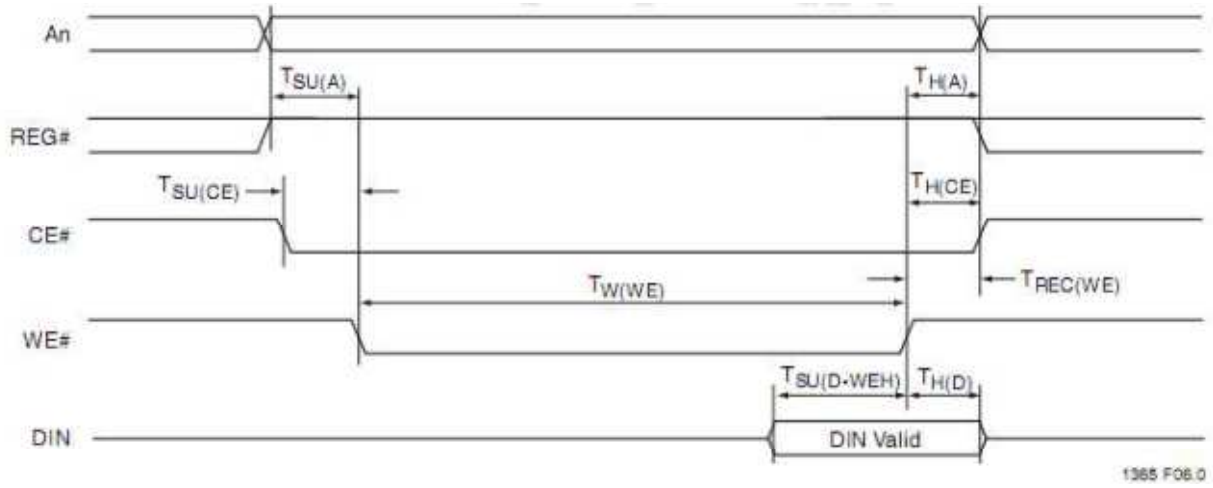


Figure 7-5: Common Memory Write Timing Diagram

© 2014 Apacer Technology Inc.

7.2.5 I/O Input (Read) Timing Specification

Table 7-9 I/O Read Timing

Item	Symbol	IEEE Symbol	Min[1]	Min[1]	Units
Data Delay after IORD	$T_{D(IORD)}$	tIGLQV		100	ns
Data Hold following IORD	$T_{H(IORD)}$	tIGHQX	0		ns
IORD Width Time	$T_{W(IORD)}$	tIGLIGH	165		ns
Address Setup before IORD	$T_{SUA(IORD)}$	tAVIGL	70		ns
Address Hold following IORD	$T_{HA(IORD)}$	tIGHAX	20		ns
CE Setup before IORD	$T_{SUCE(IORD)}$	tELIGL	5		ns
CE Hold following IORD	$T_{HCE(IORD)}$	tIGHEH	20		ns
REG Setup before IORD	$T_{SUREG(IORD)}$	tRGLIGL	5		ns
REG Hold following IORD	$T_{HREG(IORD)}$	tIGHRGH	0		ns
INPACK Delay Falling from IORD	$T_{DFINPACK(IORD)}$	tIGLIAL	0	45	ns
INPACK Delay Rising from IORD	$T_{DRINPACK(IORD)}$	tIGHIAH		45	ns
IOIS16 Delay Falling from Address	$T_{DFIOIS16(ARD)}$	tAVISL		35	ns
IOIS16 Delay Rising from Address	$T_{DRIOIS16(ADR)}$	tAVISH		35	ns

1. All AC specifications are guaranteed by design.
Note: The maximum load on –INPACK and IOIS16# is 1 LSTTL with 50pF total load.

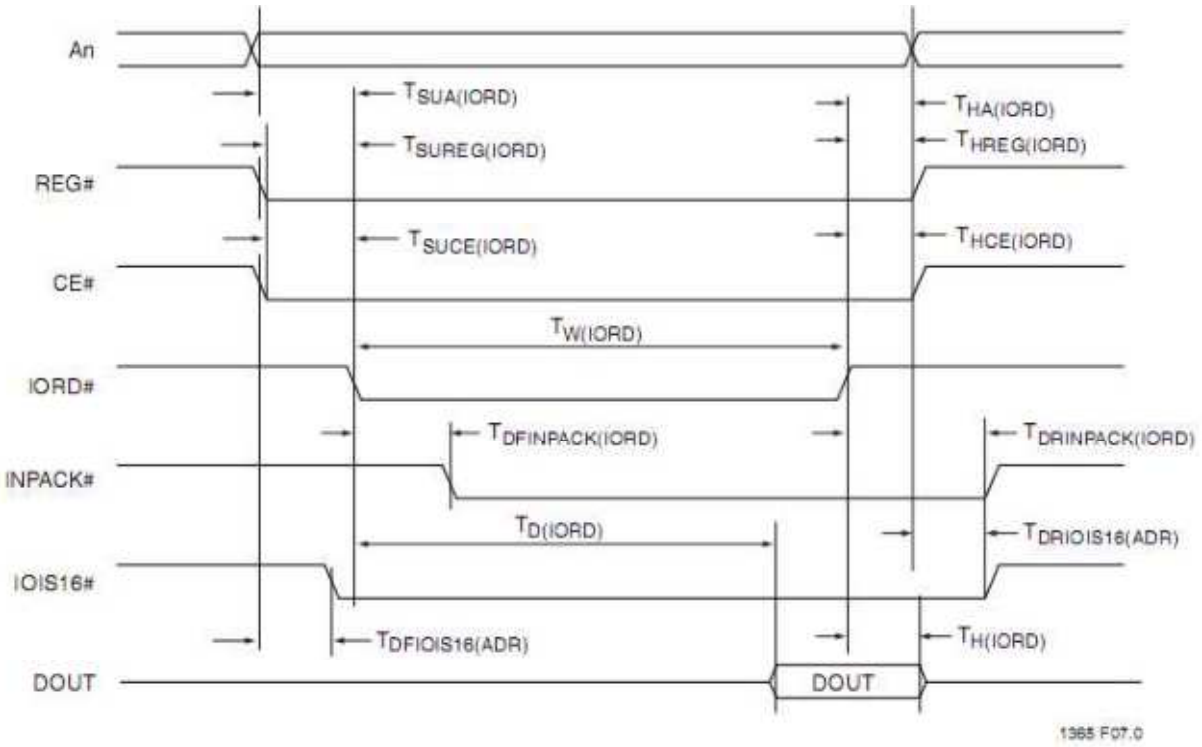


Figure 7-6: I/O Read Timing Diagram

© 2014 Apacer Technology Inc.

7.2.6 I/O Output (Write) Timing Specification

Table 7-10 I/O Write Timing

Item	Symbol	IEEE Symbol	Min[1]	Min[1]	Units
Data Setup before IOWR	$T_{SU(IOWR)}$	tDVIWH	60		ns
Data Hold following IOWR	$T_{H(IOWR)}$	tIWHDX	30		ns
IOWR Width Time	$T_{W(IOWR)}$	tIWLIWH	165		ns
Address Setup before IOWR	$T_{SUA(IOWR)}$	tAVIWL	70		ns
Address Hold following IOWR	$T_{HA(IOWR)}$	tIWHAX	20		ns
CE Setup before IOWR	$T_{SUCE(IOWR)}$	tELIWL	5		ns
CE Hold following IOWR	$T_{HCE(IOWR)}$	tIWHEH	20		ns
REG Setup before IOWR	$T_{SUREG(IOWR)}$	tRGLIWL	5		ns
REG Hold following IOWR	$T_{HREG(IOWR)}$	tIWHRGH	0		ns
IOIS16 Delay Falling from Address	$T_{DFIOIS16(ARD)}$	tAVISL		35	ns
IOIS16 Delay Rising from Address	$T_{DRIOIS16(ADR)}$	tAVISH		35	ns

1. All AC specifications are guaranteed by design.
Note: The maximum load on –INPACK and IOIS16# is 1 LSTTL with 50pF total load.

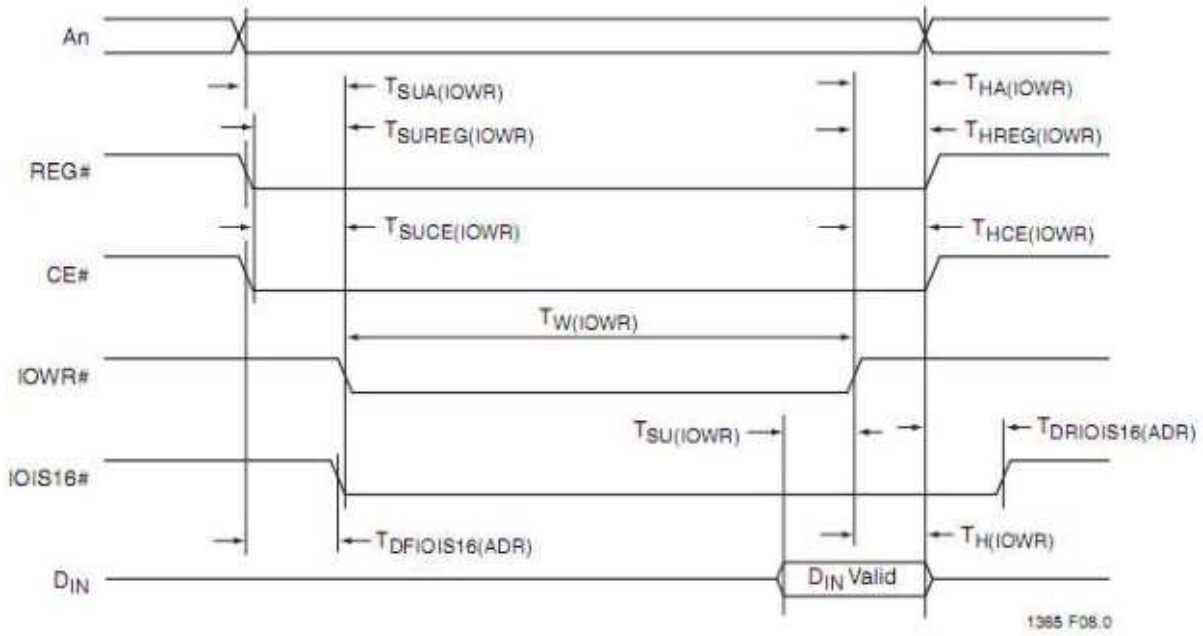


Figure 7-7: I/O Write Timing Diagram

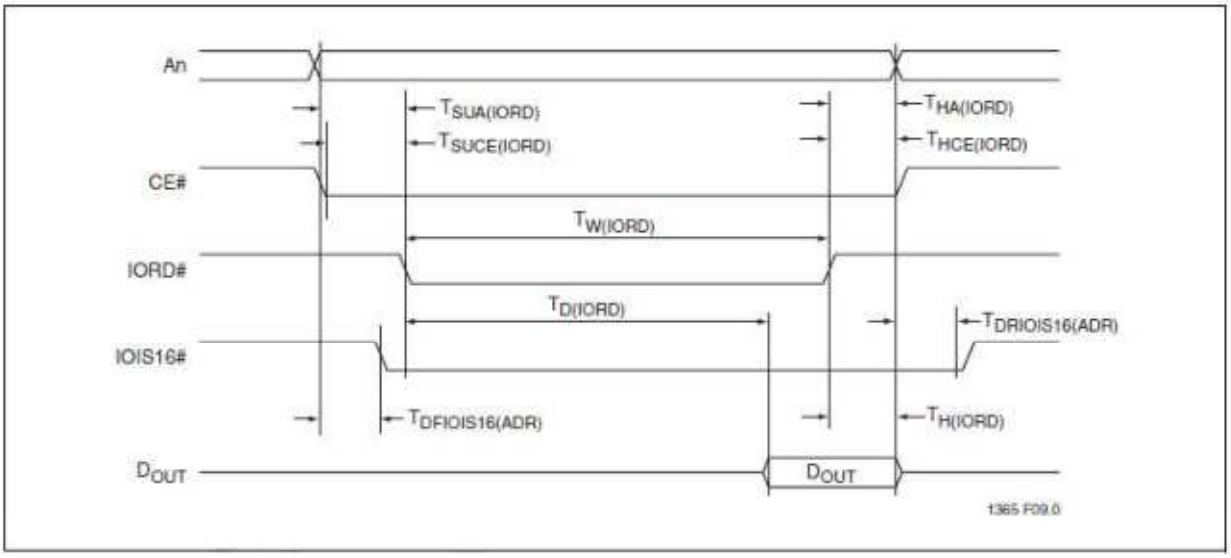
© 2014 Apacer Technology Inc.

7.2.7 True IDE I/O Read Timing

Item	Symbol	IEEE Symbol	Min	Max	Units
Data Delay after IORD	$T_{D(IORD)}$	tIGLQV		50	ns
Data Hold following IORD	$T_{H(IORD)}$	tIGHQX	5		ns
IORD Width Time	$T_{W(IORD)}$	tIGLIGH	70		ns
Address Setup before IORD	$T_{SUA(IORD)}$	tAVIGL	25		ns
Address Hold following IORD	$T_{HA(IORD)}$	tIGHAX	10		ns
CE Setup before IORD	$T_{SUCE(IORD)}$	tELIGL	10		ns
CE Hold following IORD	$T_{HCE(IORD)}$	tIGHEH	5		ns
IOIS16 Delay Falling from Address	$T_{DFIOIS16(ADR)}$	tAVISL		20	ns
IOIS16 Delay Rising from Address	$T_{DRIOIS16(ADR)}$	tAVISH		20	ns

Note: The maximum load on IOIS16# is 1 LSTTL with 50pF total load.

All AC specifications are guaranteed by design.



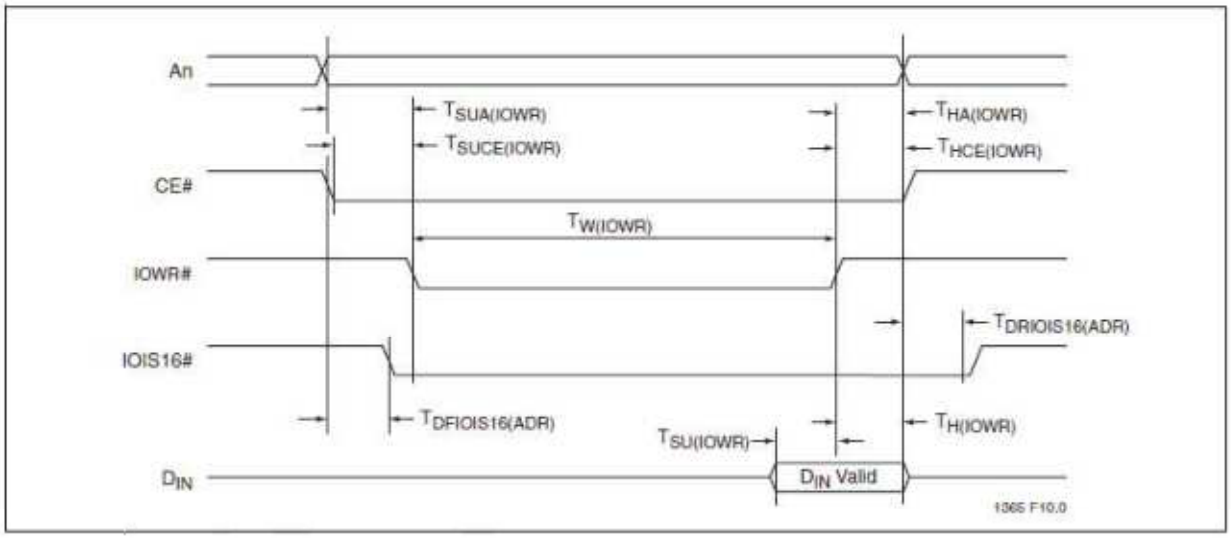
© 2014 Apacer Technology Inc.

7.2.8 True IDE I/O Write Timing

Item	Symbol	IEEE Symbol	Min	Max	Units
Data Setup before IOWR	$T_{SU(IOWR)}$	tDVIWH	20		ns
Data Hold following IOWR	$T_{H(IOWR)}$	tIWHDX	10		ns
IOWR Width Time	$T_{W(IOWR)}$	tIWLIWH	70		ns
Address Setup before IOWR	$T_{SUA(IOWR)}$	tAVIWL	25		ns
Address Hold following IOWR	$T_{HA(IOWR)}$	tIWHAX	10		ns
CE Setup before IOWR	$T_{SUCE(IOWR)}$	tELIWL	10		ns
CE Hold following IOWR	$T_{HCE(IOWR)}$	tIWHEH	5		ns
IOIS16 Delay Falling from Address	$T_{DFIOIS16(ADR)}$	tAVISL		20	ns
IOIS16 Delay Rising from Address	$T_{DRIOIS16(ADR)}$	tAVISH		20	ns

Note: The maximum load on IOIS16# is 1 LSTTL with 50pF total load.

All AC specifications are guaranteed by design.



© 2014 Apacer Technology Inc.

7.2.9 Ultra DMA Mode Data Transfer Input/Output (Read/Write) Timing

Table 7-11 Ultra DMA Data Burst Timing Specifications[1]

Name	Descriptions	Mode 4		Unit	Measurement Location[2]
		Min	Max		
$T_{2CYCTYP}$	Typical sustained average two cycle time	60		ns	Sender
T_{CYC}	Cycle time allowing for asymmetry and clock variations (from STROBE edge to STROBE edge)	25		ns	Note[3]
T_{2CYC}	Two cycle time allowing for clock variations (from rising edge to next rising edge or from falling edge to next falling edge of STROBE)	57		ns	Sender
T_{DS}	Data setup time at recipient (from data valid until STROBE edge)[4,5]	5.0		ns	Recipient
T_{DH}	Data hold time at Recipient (from STROBE edge until data becomes invalid)[1,2]	5.0		ns	Recipient
T_{DVS}	Data valid setup time for Sender (from data valid until STROBE edge)[6]	6.0		ns	Sender
T_{DVH}	Data valid hold time at Sender (from STROBE edge until data becomes invalid)[3]	6.0		ns	Sender
T_{CS}	CRC word setup time at device[1]	5.0		ns	Device
T_{CH}	CRC word hold time at device[1]	5.0		ns	Device
T_{CVS}	CRC word valid setup time at host (from CRC valid until DMACK negation)[3]	6.7		ns	Host
T_{CVH}	CRC word valid hold time at Sender (from DMACK negation until CRC becomes invalid)[3]	6.2		ns	Host
T_{ZFS}	Time from STROBE output released-to-driving until the first transition of critical timing	0		ns	Device
T_{DZFS}	Time from data output released-to-driving until the first transition of critical timing	6.7		ns	Sender
T_{FS}	First STROBE time (for device to first negate DSTROBE from STOP during a data in burst)		120	ns	Device
T_{LI}	Limited interlock time[7]	0	100	ns	Note[8]
T_{MLI}	Interlock time with minimum[4]	20		ns	Host
T_{UI}	Unlimited interlock time[4]	0		ns	Host
T_{AZ}	Maximum time allowed for output drivers to release (from asserted to negated)		10	ns	Note[9]
T_{ZAH}	Minimum delay time required for output	20		ns	Host
T_{ZAD}	Drivers to assert or negate (from released)	0		ns	Device
T_{ENV}	Envelope time (from DMACK# to STOP and HDMARDY# during data in burst initiation and from DMACK to STOP during data our burst initiation)	20	55	ns	Host
T_{RFS}	Ready-to-final STROBE time (no STROBE edge are sent this long after negation of DMARDY)		60	ns	Sender
T_{RP}	Ready-to-pause time (Recipient waits to pause until after negating DMARDY)	100		ns	Recipient
T_{IORDYZ}	Maximum time before releasing IORDY		20	ns	Device
T_{ZIORDY}	Minimum time before driving IORDY[10]	0		ns	Device
T_{ACK}		20		ns	Host
T_{SS}		50		ns	Sender

© 2014 Apacer Technology Inc.

1. All timing measurement switching points (low-to-high and high-to-low) are taken at 1.5V.
2. All signal transitions for a timing parameter are measured at the connector specified in the measurement location column. For example, in the case of TRFS, both STROBE and DMARDY Transitions are measured at the Sender connector.
3. The parameter TCYC is measured at the recipient's connector farthest from the Sender.
4. 80-Conductor cabling is required in order to meet sup (TDS, TCS) and hold (TDH, TCH) times in modes greater than two.
5. The parameters TDS and TDH for Mode 5 are defined for a Recipient at the end of the cable only in a configuration with a single device located at the end of the cable. This could result in the minimum values for TDS and TDH for mode 5 at the middle connector being 3.0 and 3.9 ns respectively.
6. Timing for TDVS, TDVH, TCVS, and TCVH are met for lumped capacitive loads of 15 and 50 pf at the connector where the Data and STROBE signals have the same capacitive load value. Due to reflections on the cable, these timing measurements are not valid in a normally functioning system.
7. The parameters TUI, TMLI, and TLI indicate Sender-to-Recipient or Recipient-to-Sender interlocks. For example, one agent (either Sender or Recipient) is waiting for the other agent to respond with a signal before proceeding; TUI is an unlimited interlock that has no maximum time value, TMLI is a limited time-out that has a defined minimum, and TLI is a limited time-out that has a defined maximum.
8. The parameter TLI is measured at the connector of the Sender or Recipient that is responding to an incoming transition from the Recipient or Sender respectively. Both the incoming signal and the outgoing response are measured at the same connector.
9. The parameter TAZ is measured at the connector of the Sender or Recipient that is driving the bus but must release the bus that allow for a bus turnaround.
10. For all modes the parameter TZIORDY may be greater than TENV because the host has a pull-on IORDY giving it a known state when released.

© 2014 Apacer Technology Inc.

Table 7-12 Ultra DMA Sender and Recipient IC Timing Specifications[1]

Name	Descriptions	Mode 4		Unit
		Min	Max	
T_{DSIC}	Recipient IC data setup time (from data valid until STROBE edge)[2]	4.8		ns
T_{DHIC}	Recipient IC data hold time (from STROBE edge until data becomes invalid)[1]	4.8		ns
T_{DVSIC}	Sender IC data valid setup time (from data valid until STROBE edge)[3]	9.5		ns
T_{DVHIC}		9.0		ns

1. All timing measurement switching point (low-to-high and high-to-low)
2. The correct data value is captured by the Recipient given input data with a slew rate of 0.4 V/ns rising and falling and the input STROBE with a slew rate of 0.4 V/ns rising and falling at TDSIC and TDHIC timing (as measured through 1.5 V).
3. The parameters TDVSIC and TDVHIC are met for lumped capacitive loads of 15 and 40 pf at the IC where all signals have the same capacitive load value. Noise that may couple onto the output signals from external sources has not been included in these values.

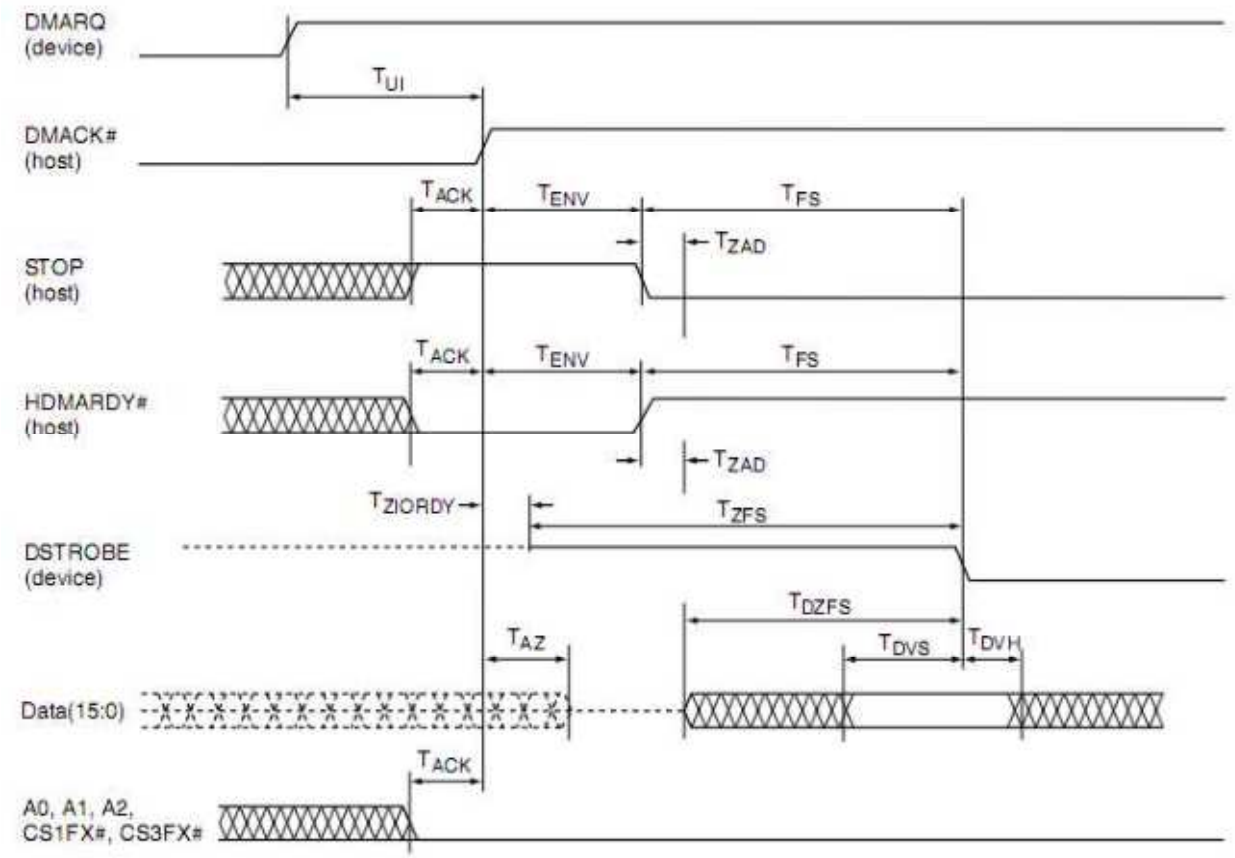


Figure 7-8: Initiating an Ultra DMA Data-In Burst

Notes:
1. The definitions for the DIOW-:STOP, DIOR-:HDMARDY-:HSTROBE, and IORDY:DDRARDY-: DSTROBE signal lines are not in effect until DMARQ and DMACK are asserted.

© 2014 Apacer Technology Inc.

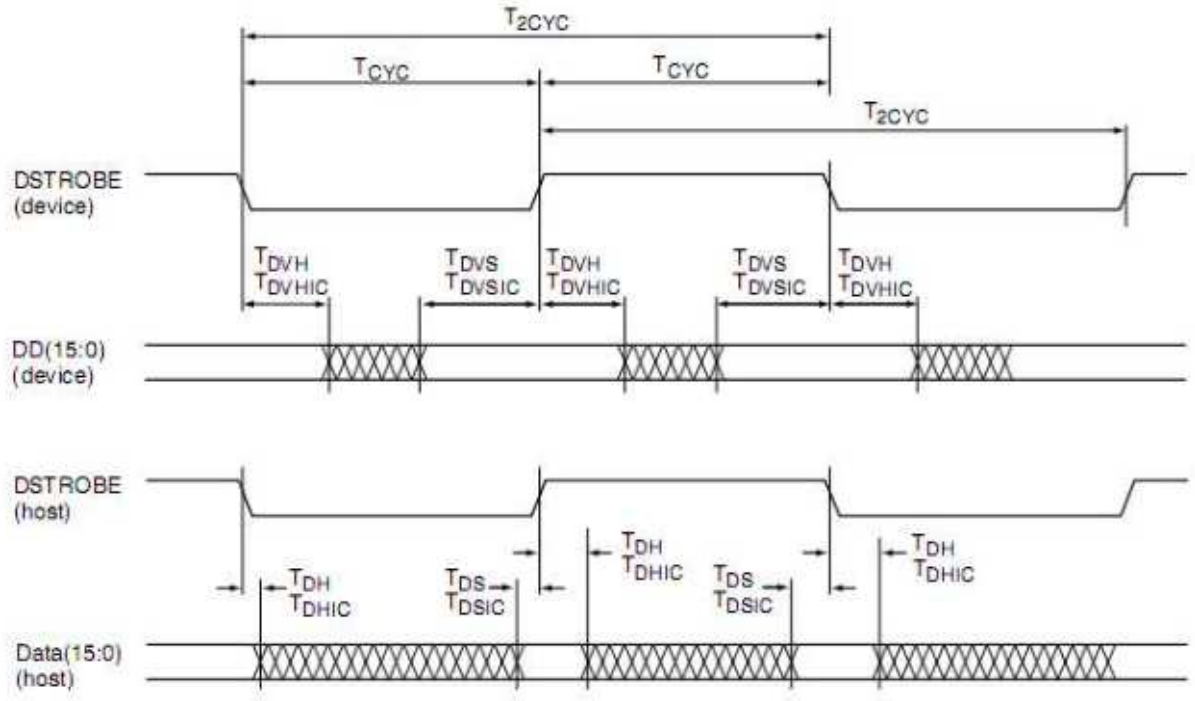


Figure 7-9: Sustained Ultra DMA Data-In Burst

Notes:

1. DD(15:0) and DSTROBE signals are shown at both the host and the device to emphasize that cable settling time as well as cable propagation delay will not allow the data signals to be considered stable at the host until some time after they are driven by the device.

© 2014 Apacer Technology Inc.

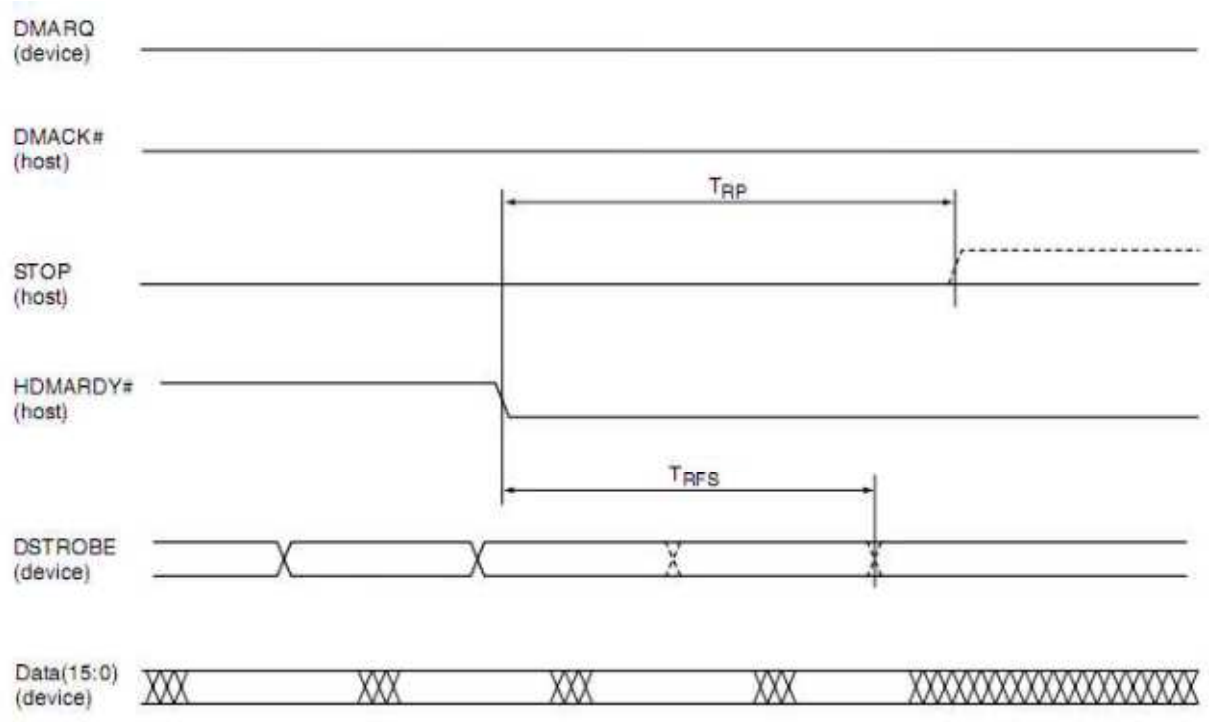


Figure 7-10: Sustained Ultra DMA Data-In Burst

Notes:
1. The host may assert STOP to request termination of the Ultra DMA burst no sooner than TRP after HDMARDY# is negated.
2. After negating HDMARDY#, the host may receive zero, one, two, or three more data words from the device.

© 2014 Apacer Technology Inc.

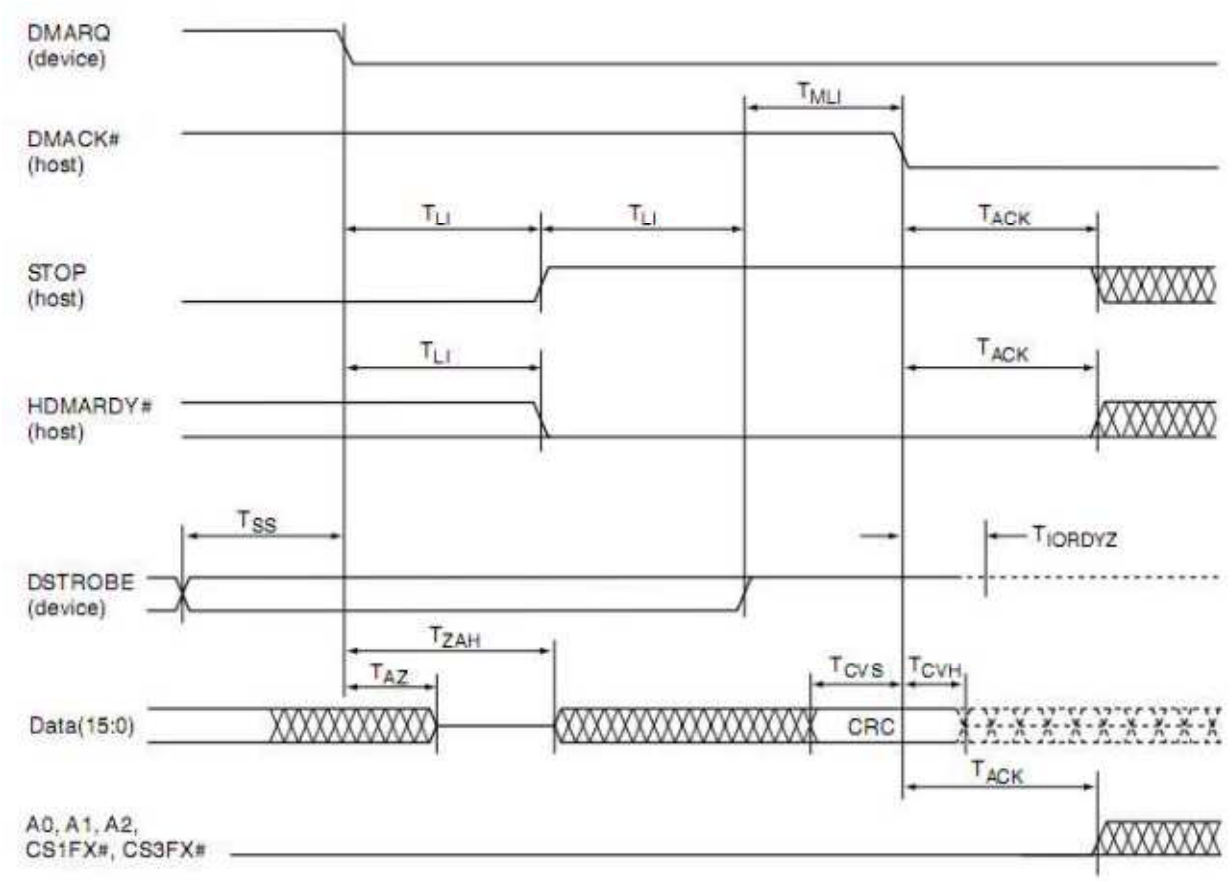


Figure 7-11: Device Terminating and Ultra DMA Data-In Burst

Notes:
1. The definitions for the STOP, HDMARDY, and DSTROBE signal lines are no longer in effect after DMARQ and DMACK are negated.

© 2014 Apacer Technology Inc.

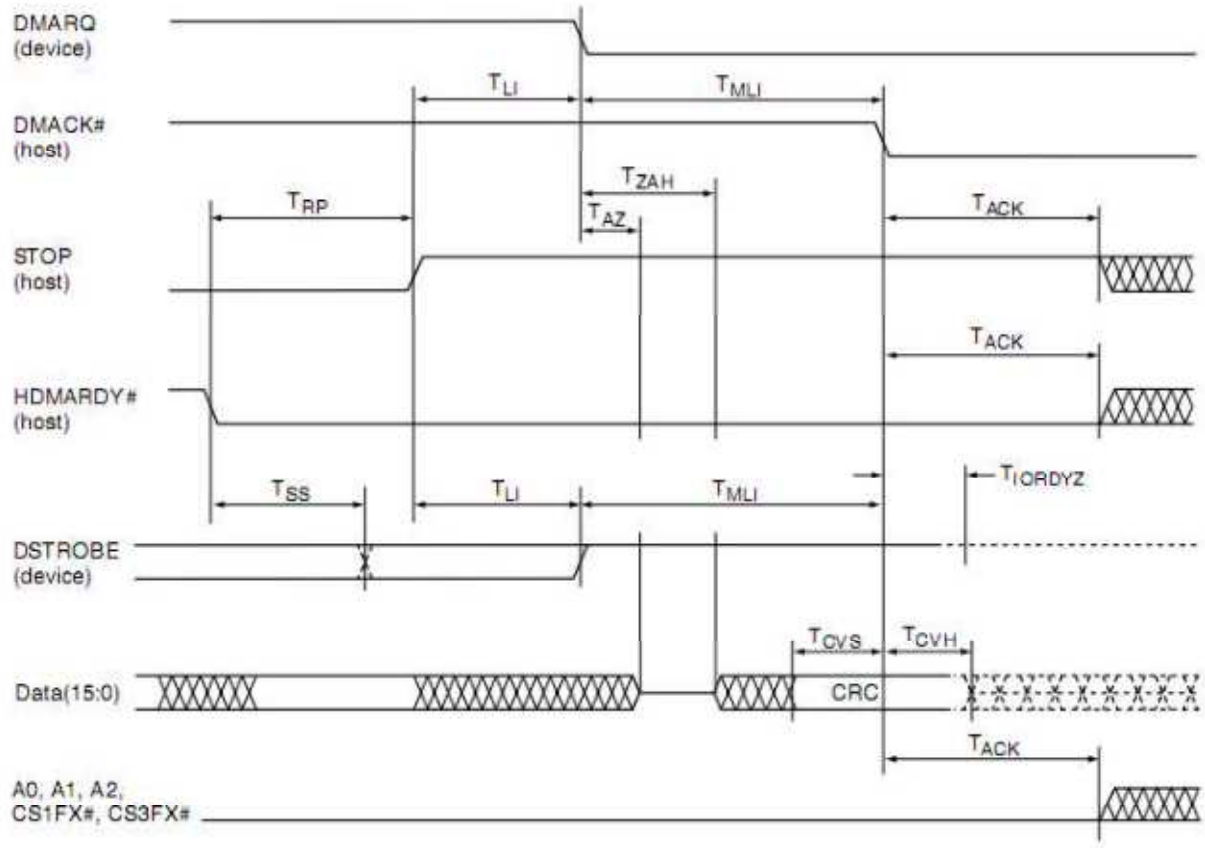


Figure 7-12: Host Terminating and Ultra DMA Data-In Burst

Notes:
1. The definitions for the STOP, HDMARDY, and DSTROBE signal lines are no longer in effect after DMARQ and DMACK are negated.

© 2014 Apacer Technology Inc.

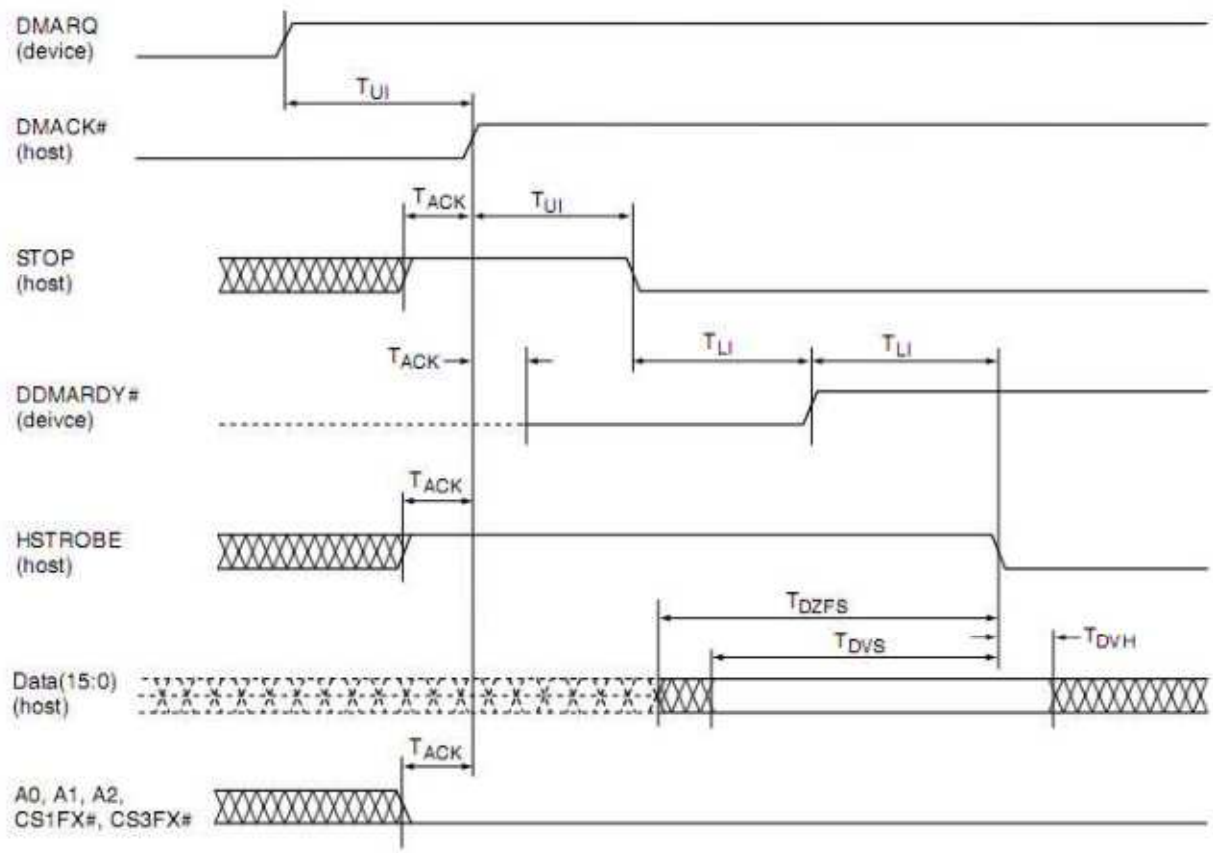


Figure 7-13: Initiating an Ultra DMA Data-Out Burst

Notes:
1. The definitions for the STOP, DDMARDY, and HSTROBE signal lines are no longer in effect after DMARQ and DMACK are negated.

© 2014 Apacer Technology Inc.

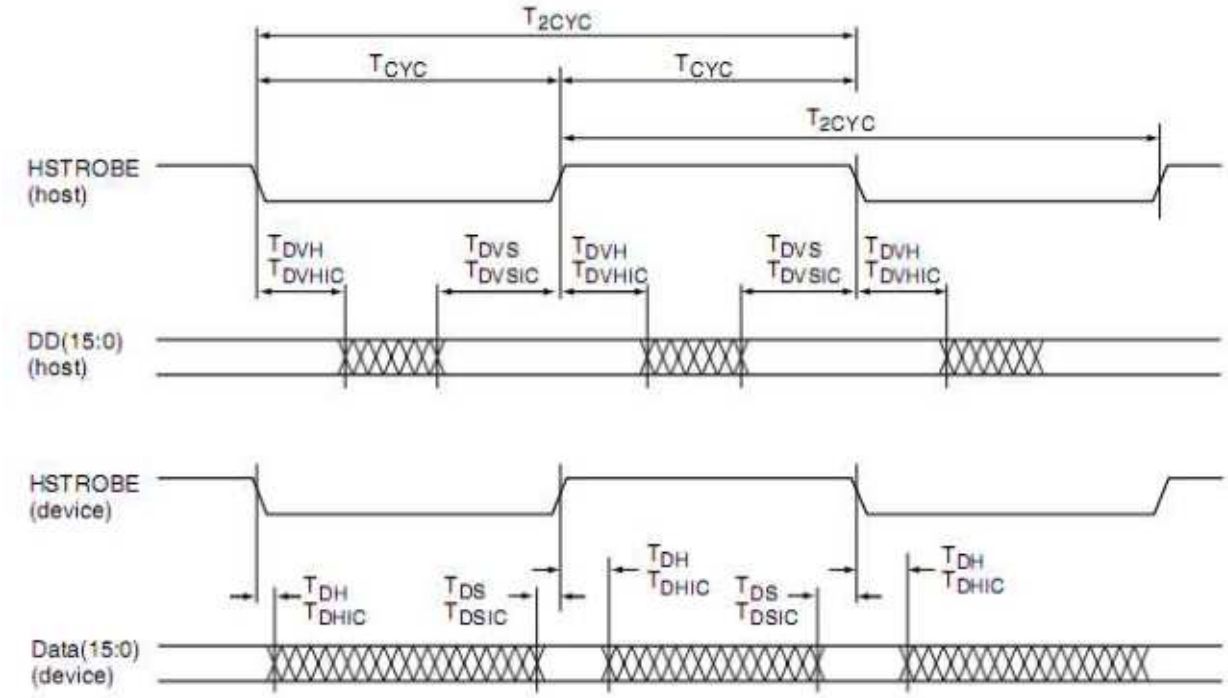


Figure 7-14: Sustained Ultra DMA Data-Out Burst

Notes:

1. DD(15:0) and HSTROBE signals are shown at both the host and the device to emphasize that cable settling time as well as cable propagation delay will not allow the data signals to be considered stable at the host until some time after they are driven by the host.

© 2014 Apacer Technology Inc.

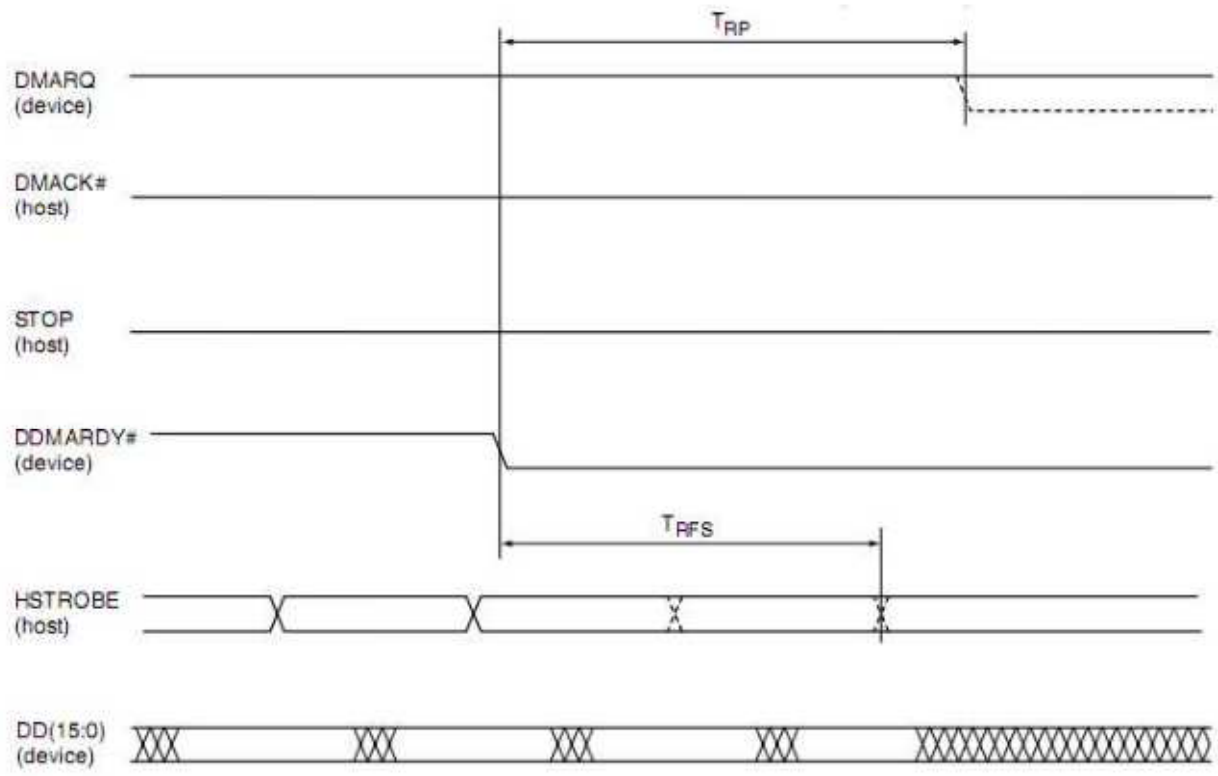


Figure 7-15: Device Pausing and Ultra DMA Data-Out Burst

Notes:
1. The host may negate DMARQ to request termination of the Ultra DMA burst no sooner than TRP after DDMARDY# is negated.
2. After negating DDMARDY#, the host may receive zero, one, two, or three more data words from the host.

© 2014 Apacer Technology Inc.

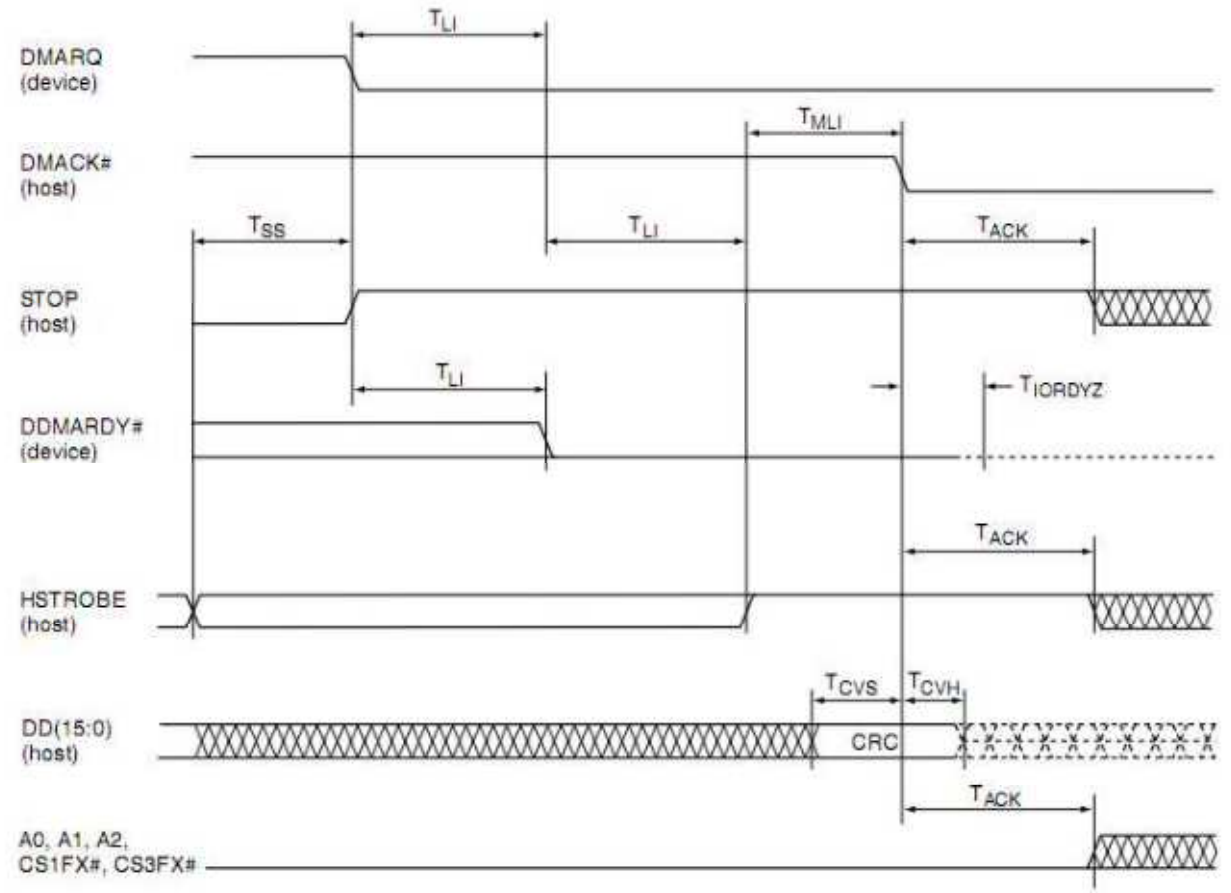


Figure 7-16: Host Terminating and Ultra DMA Data-Out Burst

Notes:

1. The definitions for the STOP, DDMARDY, and HSTROBE signal lines are no longer in effect after DMARQ and DMACK are negated.

© 2014 Apacer Technology Inc.

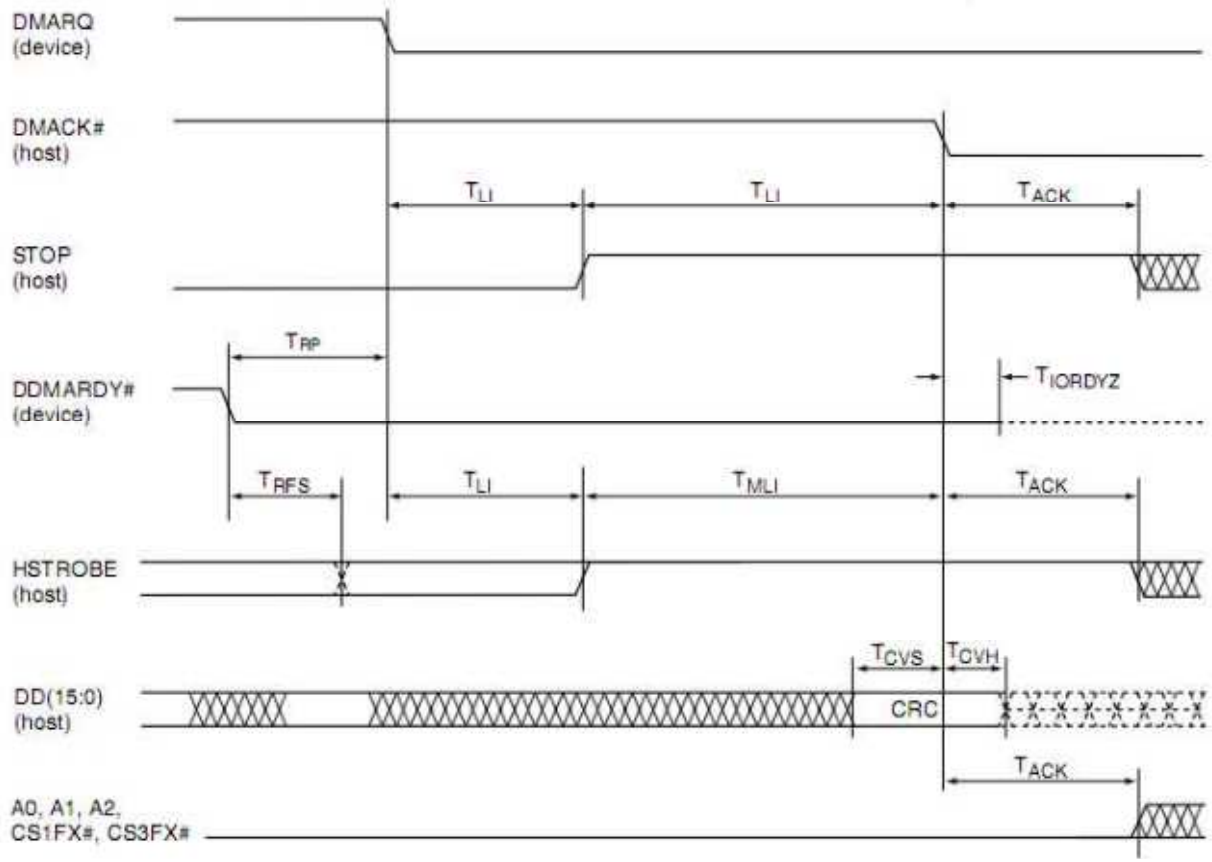


Figure 7-17: Device Terminating and Ultra DMA Data-Out Burst

Notes:
1. The definitions for the STOP, DDMARDY, and HSTROBE signal lines are no longer in effect after DMARQ and DMACK are negated.

© 2014 Apacer Technology Inc.

7.3.0 Media Side Interface I/O Timing Specifications

Table 7-13: Timing Parameter

Symbol	Parameter	Min	Max	Units
T_{CLS}	FCLE Setup Time	20	-	ns
T_{CLH}	FCLE Hold Time	40	-	ns
T_{CS}	FCE# Setup Time	40	-	ns
T_{CH}	FCE# Hold Time for Command/Data Write Cycle	40	-	ns
T_{CHR}	FCE# Hold Time for Sequential Read Last Cycle	-	40	ns
T_{WP}	FWE# Pulse Width	20	-	ns
T_{WH}	FWE# High Hold Time	20	-	ns
T_{WC}	Write Cycle Time	40	-	ns
T_{ALS}	FALE Setup Time	20	-	ns
T_{ALH}	FALE Hold Time	40	-	ns
T_{DS}	FAD[15:0] Setup Time	20	-	ns
T_{DH}	FAD[15:0] Hold Time	20	-	ns
T_{RP}	FRE# Pulse Width	20	-	ns
T_{RR}	Ready to FRE# Low	40	-	ns
T_{RES}	FRE# Data Setup Access Time	20	-	ns
T_{RC}	Read Cycle Time	40	-	ns
T_{REH}	FRE# High Hold Time	20	-	ns
T_{RHZ}	FRE# High to Data Hi-Z	5	-	ns

Note: All AC specifications are guaranteed by design.

© 2014 Apacer Technology Inc.

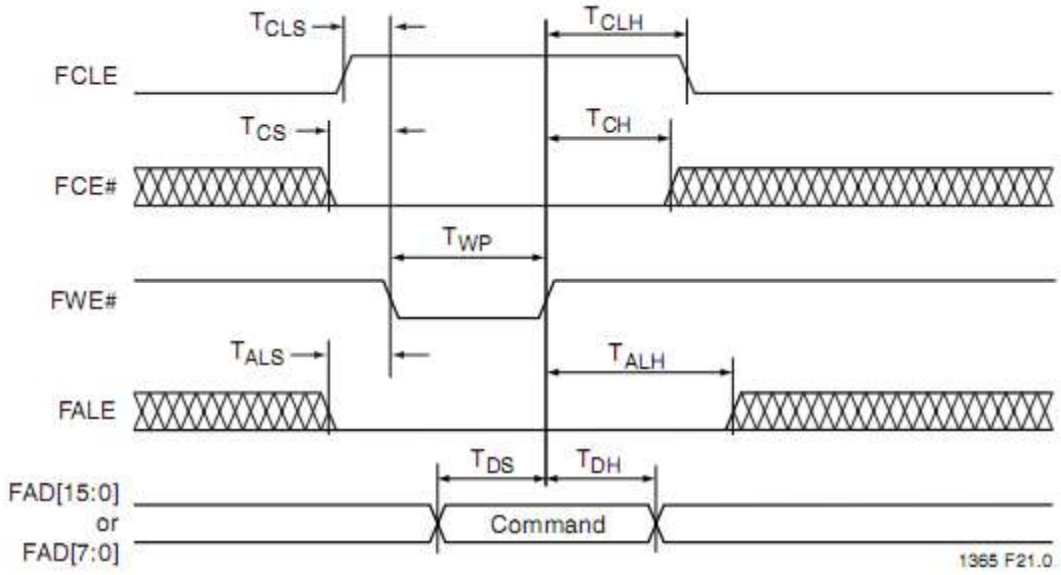


Figure 7-18: Media Command Latch Cycle

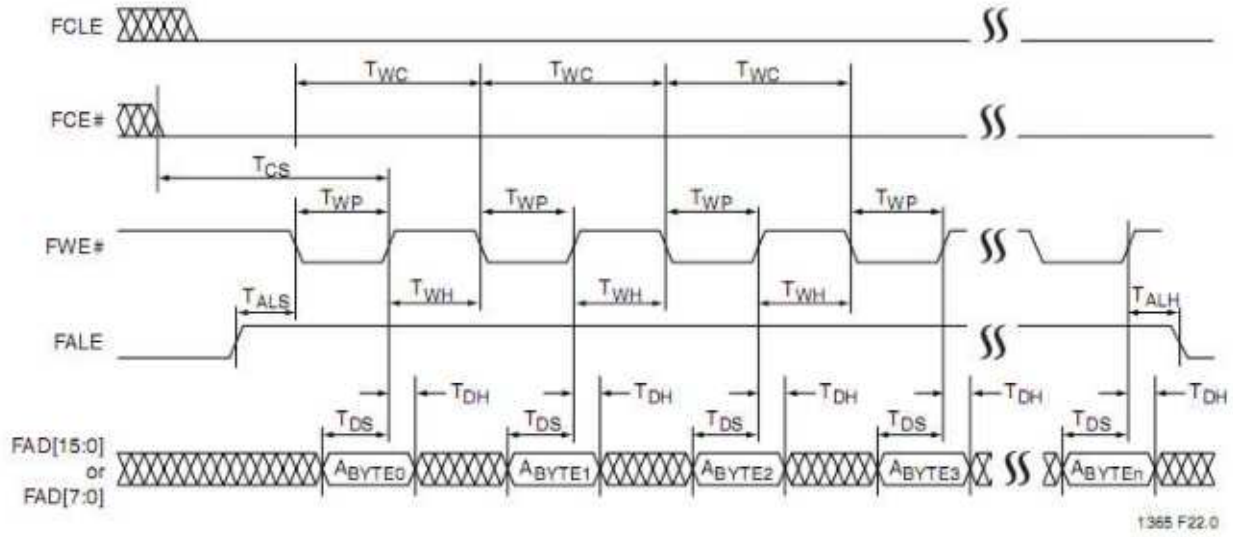


Figure 7-19: Media Access Latch Cycle

© 2014 Apacer Technology Inc.

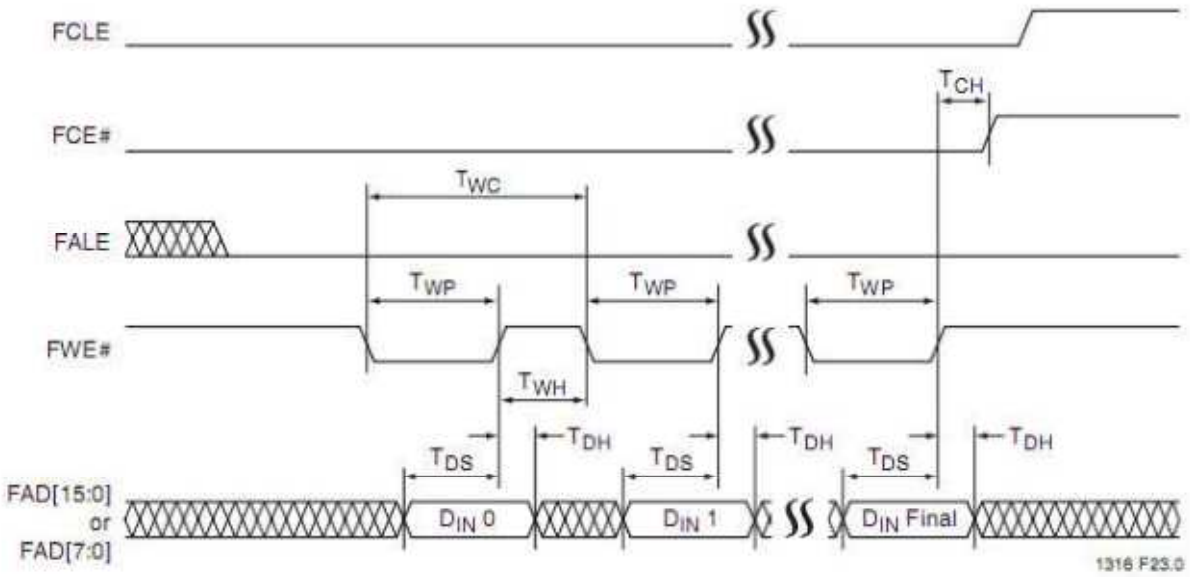


Figure 7-20: Media Data Loading Latch Cycle

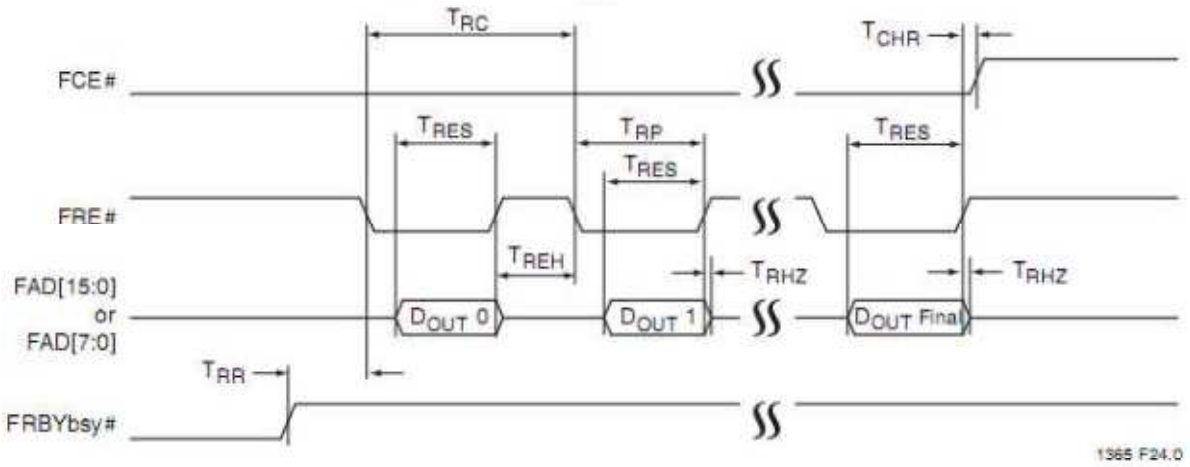


Figure 7-21: Media Data Read Cycle

© 2014 Apacer Technology Inc.

8. Physical Characteristics

8.1 Dimension

TABLE 8-1: Type I CFC physical specification

Length:	36.40 +/- 0.15mm (1.433+/- 0.06 in.)
Width:	42.80 +/- 0.10mm (1.685+/- 0.04 in.)
Thickness (Including Label Area):	3.3mm+/-0.10mm (0.130+/-0.04in.)

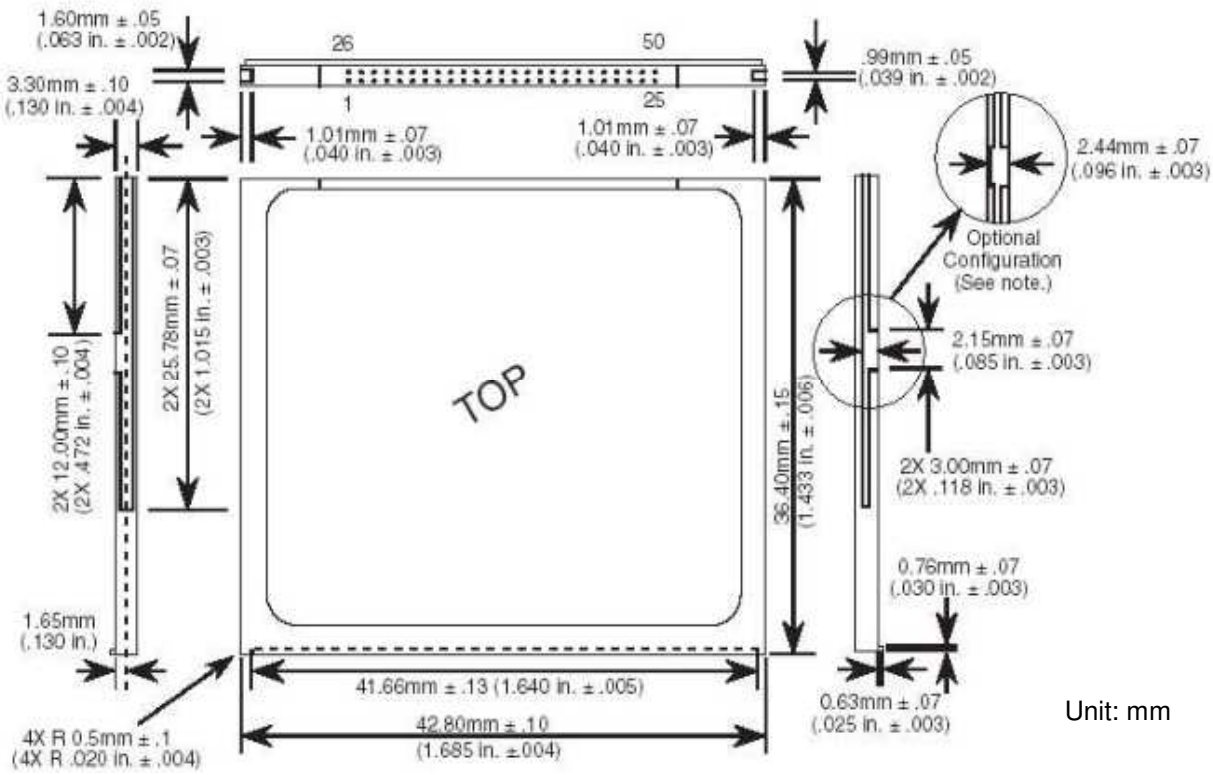
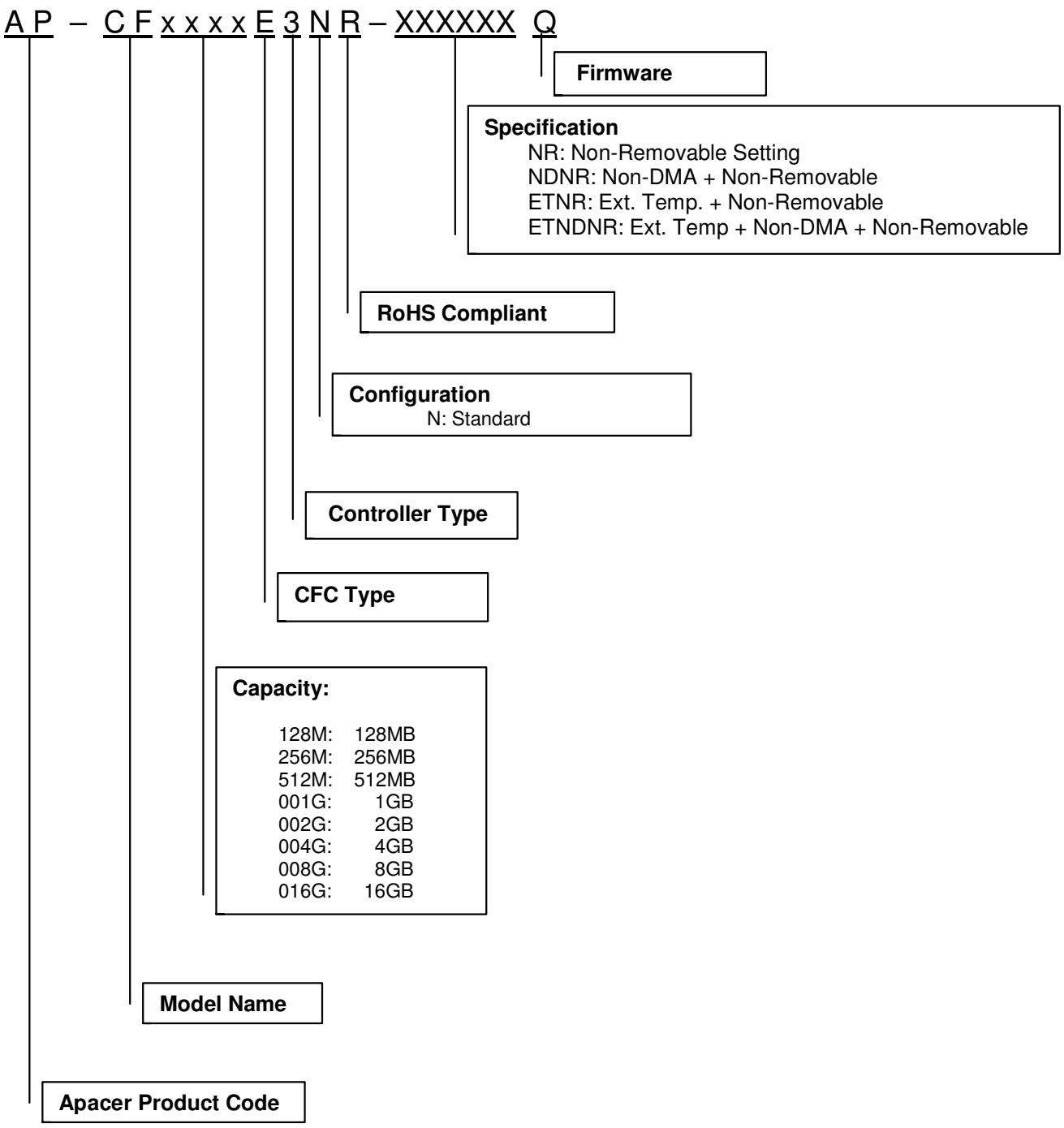


FIGURE 8-1: Physical dimension

© 2014 Apacer Technology Inc.

9. Product Ordering Information

9.1 Product Code Designations



© 2014 Apacer Technology Inc.

9.2 Valid Combinations

Standard Temperature

Non-Removable

Capacity	Model Number
128MB	AP-CF128ME3NR-NRQ
256MB	AP-CF256ME3NR-NRQ
512MB	AP-CF512ME3NR-NRQ
1GB	AP-CF001GE3NR-NRQ
2GB	AP-CF002GE3NR-NRQ
4GB	AP-CF004GE3NR-NRQ
8GB	AP-CF008GE3NR-NRQ
16GB	AP-CF016GE3NR-NRQ

Non-DMA & Non-Removable

Capacity	Model Number
128MB	AP-CF128ME3NR-NDNRQ
256MB	AP-CF256ME3NR-NDNRQ
512MB	AP-CF512ME3NR-NDNRQ
1GB	AP-CF001GE3NR-NDNRQ
2GB	AP-CF002GE3NR-NDNRQ
4GB	AP-CF004GE3NR-NDNRQ
8GB	AP-CF008GE3NR-NDNRQ
16GB	AP-CF016GE3NR-NDNRQ

© 2014 Apacer Technology Inc.

Extended Temperature

Non-Removable

Capacity	Model Number
128MB	AP-CF128ME3NR-ETNRQ
256MB	AP-CF256ME3NR-ETNRQ
512MB	AP-CF512ME3NR-ETNRQ
1GB	AP-CF001GE3NR-ETNRQ
2GB	AP-CF002GE3NR-ETNRQ
4GB	AP-CF004GE3NR-ETNRQ
8GB	AP-CF008GE3NR-ETNRQ
16GB	AP-CF016GE3NR-ETNRQ

Non-DMA & Non-Removable

Capacity	Model Number
128MB	AP-CF128ME3NR-ETNDNRQ
256MB	AP-CF256ME3NR-ETNDNRQ
512MB	AP-CF512ME3NR-ETNDNRQ
1GB	AP-CF001GE3NR-ETNDNRQ
2GB	AP-CF002GE3NR-ETNDNRQ
4GB	AP-CF004GE3NR-ETNDNRQ
8GB	AP-CF008GE3NR-ETNDNRQ
16GB	AP-CF016GE3NR-ETNDNRQ

© 2014 Apacer Technology Inc.

Revision History

Revision	Date	Description	Remark
1.0	05/19/2011	Official release	
1.1	08/11/2013	Updated performance and product ordering information due to change in NAND flash use Updated the address of Taiwan headquarter Added endurance TBW section to replace MTBF	
1.2	11/08/2013	Added AC/DC characteristics Revised True IDE mode pin assignments	
1.3	01/15/2014	Revised DC characteristic table	
1.4	03/27/2014	Updated command set table	
1.5	09/10/2014	Updated pin assignments	

© 2014 Apacer Technology Inc.

Global Presence

Taiwan (Headquarters)

Apacer Technology Inc.
Apacer Technology Inc.
1F., No.32, Zhongcheng Rd., Tucheng Dist.,
New Taipei City 236, Taiwan R.O.C.
Tel: 886-2-2267-8000
Fax: 886-2-2267-2261
amtsales@apacer.com

U.S.A.

Apacer Memory America, Inc.
386 Fairview Way, Suite102,
Milpitas, CA 95035
Tel: 1-408-518-8699
Fax: 1-408-935-9611
sa@apacerus.com

Japan

Apacer Technology Corp.
5F, Matsura Bldg., Shiba, Minato-Ku
Tokyo, 105-0014, Japan
Tel: 81-3-5419-2668
Fax: 81-3-5419-0018
jpservices@apacer.com

Europe

Apacer Technology B.V.
Science Park Eindhoven 5051 5692 EB Son,
The Netherlands
Tel: 31-40-267-0000
Fax: 31-40-267-0000#6199
sales@apacer.nl

China

Apacer Electronic (Shanghai) Co., Ltd
1301, No.251,Xiaomuqiao Road, Shanghai,
200032, China
Tel: 86-21-5529-0222
Fax: 86-21-5206-6939
sales@apacer.com.cn

India

Apacer Technologies Pvt. Ltd.
535, 1st Floor, 8th cross, JP Nagar 3rd Phase,
Bangalore – 560078, India
Tel: 91-80-4152-9061
sales_india@apacer.com

© 2014 Apacer Technology Inc.