TJA1042

High-speed CAN transceiver with Standby mode

Rev. 11 — 16 January 2023 Product data sheet

1 General description

The TJA1042 high-speed CAN transceiver provides an interface between a Controller Area Network (CAN) protocol controller and the physical two-wire CAN bus. The transceiver is designed for high-speed CAN applications in the automotive industry, providing the differential transmit and receive capability to (a microcontroller with) a CAN protocol controller.

The TJA1042 belongs to the third generation of high-speed CAN transceivers from NXP Semiconductors, offering significant improvements over first- and second-generation devices such as the TJA1040. It offers improved ElectroMagnetic Compatibility (EMC) and ElectroStatic Discharge (ESD) performance, and also features:

- Ideal passive behavior to the CAN bus when the supply voltage is off
- A very low-current Standby mode with bus wake-up capability
- Variants with a V_{IO} pin can be interfaced directly with microcontrollers with supply voltages from 3.3 V to 5 V

The TJA1042 implements the CAN physical layer as defined in ISO 11898-2:2016 and SAE J2284-1 to SAE J2284-5. This implementation enables reliable communication in the CAN FD fast phase at data rates up to 5 Mbit/s. The TJA1042B and TJA1042C feature shorter propagation delay, supporting larger network topologies.

These features make the TJA1042 an excellent choice for all types of HS-CAN networks, in nodes that require a low-power mode with wake-up capability via the CAN bus.

2 Features and benefits

2.1 General

- Fully ISO 11898-2:2016, SAE J2284-1 to SAE J2284-5 and SAE J1939-14 compliant
- Timing guaranteed for data rates up to 5 Mbit/s in the CAN FD fast phase
- Suitable for 12 V and 24 V systems
- Low Electromagnetic Emission (EME) and high Electromagnetic Immunity (EMI), according to proposed EMC Standards IEC 62228-3 and SAE J2962-2
- Variants with a V_{IO} pin allow for direct interfacing with 3.3 V to 5 V microcontrollers
- Shorter propagation delay on the TJA1042B and TJA1042C variants supports larger network topologies (see Table 8)
- SPLIT voltage output on TJA1042T and TJA1042CT for stabilizing the recessive bus level
- Both V_{IO} and non-V_{IO} variants are available in SO8 and leadless HVSON8 (3.0 mm × 3.0 mm) packages; HVSON8 with improved Automated Optical Inspection (AOI) capability.

- Dark green product (halogen free and Restriction of Hazardous Substances (RoHS) compliant)
- AEC-Q100 qualified

2.2 Predictable and fail-safe behavior

- Very low-current Standby mode with host and bus wake-up capability
- Functional behavior predictable under all supply conditions
- Transceiver disengages from the bus (high-ohmic) when the supply voltage drops below the switch-off undervoltage threshold
- Transmit Data (TXD) dominant time-out function
- Bus-dominant time-out function in Standby mode
- Undervoltage detection on pins V_{CC} and V_{IO}

2.3 Protections

- High ESD handling capability on the bus pins (±8 kV)
- High voltage robustness on CAN pins (±58 V)
- Bus pins protected against transients in automotive environments
- Thermally protected

3 Quick reference data

Table 1. Quick reference data

Symbol	Parameter	Conditions	Min	Typ	Max	Unit
V_{CC}	supply voltage		4.5	-	5.5	V
V_{IO}	supply voltage on pin V_{IO}		2.8	-	5.5	V
$V_{uvd(VCC)}$	undervoltage detection voltage on pin V_{CC}		3.5	-	4.5	V
$V_{uvd(VIO)}$	undervoltage detection voltage on pin V_{IO}		1.3	2.0	2.7	V
I_{CC}	supply current	Standby mode	-	10	15	µA
		Normal mode; bus recessive	2.5	5	10	mA
		Normal mode; bus dominant	20	45	70	mA
I_{IO}	supply current on pin V_{IO}	Standby mode; $V_{TXD} = V_{IO}$	5	-	14	µA
		Normal mode				
		recessive; $V_{TXD} = V_{IO}$	15	80	200	µA
		dominant; $V_{TXD} = 0$ V	-	350	1000	µA
V_{ESD}	electrostatic discharge voltage	IEC 61000-4-2 at pins CANH and CANL	-8	-	+8	kV
V_{CANH}	voltage on pin CANH		-58	-	+58	V
V_{CANL}	voltage on pin CANL		-58	-	+58	V
T_{vj}	virtual junction temperature		-40	-	+150	°C

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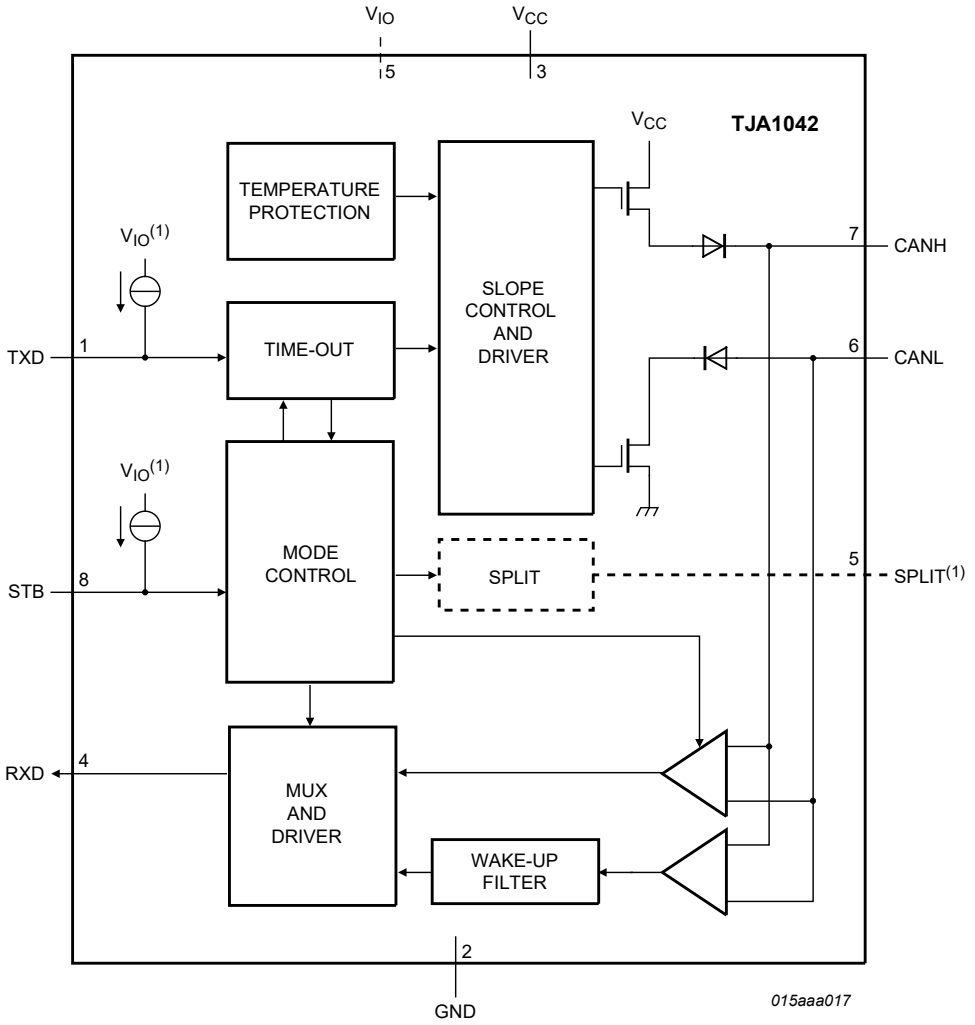
4 Ordering information

Table 2. Ordering information

Type number[1]	Package		
	Name	Description	Version
TJA1042T TJA1042BT TJA1042CT TJA1042T/3	SO8	plastic small outline package; 8 leads; body width 3.9 mm	SOT96-1
TJA1042BTK TJA1042TK/3	HVSON8	plastic thermal enhanced very thin small outline package; no leads; 8 terminals; body 3 × 3 × 0.85 mm	SOT782-1

[1] TJA1042T and TJA1042CT with SPLIT pin; other variants with V_{IO} pin.

5 Block diagram



1. In a transceiver with a SPLIT pin, the V_{IO} input is internally connected to V_{CC}.

Figure 1. Block diagram

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6 Pinning information

6.1 Pinning

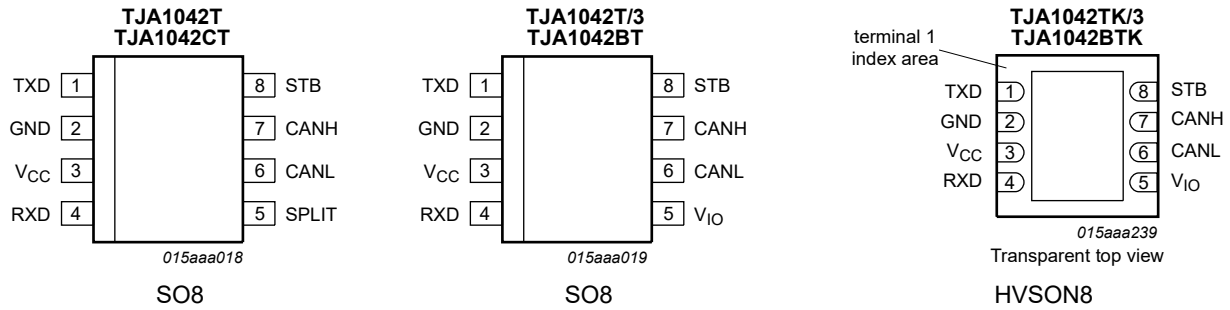


Figure 2. Pin configuration diagrams

6.2 Pin description

Table 3. Pin description

Symbol	Pin	Type[1]	Description
TXD	1	I	transmit data input
GND	2[2]	G	ground supply
V_{CC}	3	P	supply voltage
RXD	4	O	receive data output; reads out data from the bus lines
SPLIT	5	O	common-mode stabilization output; TJA1042T and TJA1042CT variants only
V_{IO}	5	P	supply voltage for I/O level adapter; TJA1042T(K)/3 and TJA1042BT(K) variants only
CANL	6	AIO	LOW-level CAN bus line
CANH	7	AIO	HIGH-level CAN bus line
STB	8	I	Standby mode control input

[1] I: digital input; O: digital output; AIO: analog input/output; P: power supply; G: ground.

[2] HVSON8 package die supply ground is connected to both the GND pin and the exposed center pad. The GND pin must be soldered to board ground. For enhanced thermal and electrical performance, it is recommended that the exposed center pad also be soldered to board ground.

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7 Functional description

The TJA1042 is a HS-CAN stand-alone transceiver with Standby mode. It combines the functionality of the PCA82C250, PCA82C251 and TJA1040 transceivers with improved EMC and ESD handling capability and quiescent current performance. Improved slope control and high DC handling capability on the bus pins provide additional application flexibility.

The TJA1042 is available in two versions, distinguished only by the function of pin 5:

- The TJA1042T and TJA1042CT are backwards compatible with the TJA1040 when used with a 5 V microcontroller, and also cover existing PCA82C250 and PCA82C251 applications
- The TJA1042T(K)/3 and TJA1042BT(K) allow for direct interfacing to microcontrollers with supply voltages down to 3 V

7.1 Operating modes

The TJA1042 supports two operating modes, Normal and Standby, which are selected via pin STB. See Table 4 for a description of the operating modes under normal supply conditions.

Table 4. Operating modes

Mode	Pin STB	Pin RXD	
		LOW	HIGH
Normal	LOW	bus dominant	bus recessive
Standby	HIGH	wake-up request detected	no wake-up request detected

7.1.1 Normal mode

A LOW level on pin STB selects Normal mode. In this mode, the transceiver can transmit and receive data via the bus lines CANH and CANL (see Figure 1 for the block diagram). The differential receiver converts the analog data on the bus lines into digital data which is output to pin RXD. The slopes of the output signals on the bus lines are controlled internally and are optimized in a way that guarantees the lowest possible EME.

7.1.2 Standby mode

A HIGH level on pin STB selects Standby mode. In Standby mode, the transceiver is not able to transmit or correctly receive data via the bus lines. The transmitter and Normal-mode receiver blocks are switched off to reduce supply current, and only a low-power differential receiver monitors the bus lines for activity. The wake-up filter on the output of the low-power receiver does not latch bus dominant states, but ensures that only bus dominant and bus recessive states that persist longer than $t_{fltr(wake)bus}$ are reflected on pin RXD.

In Standby mode, the bus lines are biased to ground to minimize the system supply current. The low-power receiver is supplied by V_{IO}, and is capable of detecting CAN bus activity even if V_{IO} is the only supply voltage available. When pin RXD goes LOW to signal a wake-up request, a transition to Normal mode will not be triggered until STB is forced LOW.

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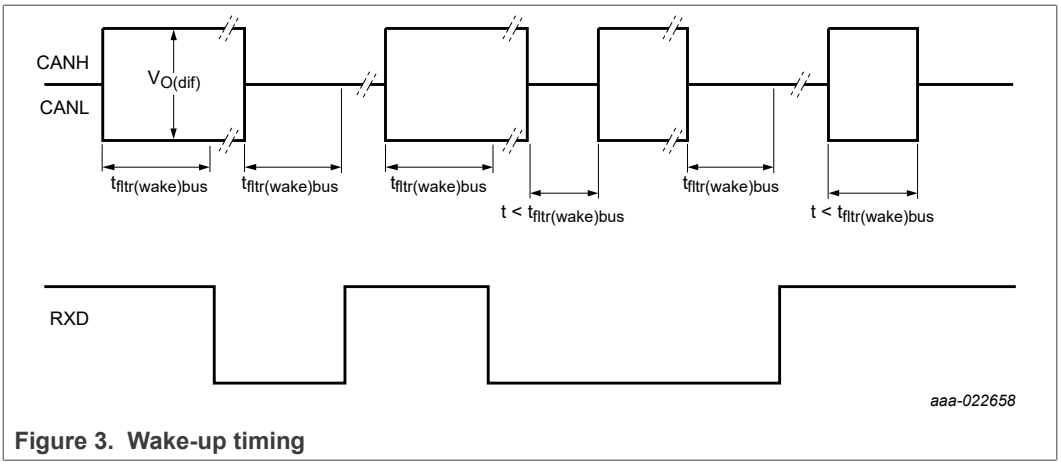


Figure 3. Wake-up timing

7.2 Fail-safe features

7.2.1 TXD dominant time-out function

A ‘TXD dominant time-out’ timer is started when pin TXD is set LOW. If the LOW state on pin TXD persists for longer than $t_{to(dom)TXD}$, the transmitter is disabled, releasing the bus lines to recessive state. This function prevents a hardware and/or software application failure from driving the bus lines to a permanent dominant state (blocking all network communications). The TXD dominant time-out timer is reset when pin TXD is set to HIGH. The TXD dominant time-out time also defines the minimum possible bit rate of 40 kbit/s.

7.2.2 Bus dominant time-out function

In Standby mode a 'bus dominant time-out' timer is started when the CAN bus changes from recessive to dominant state. If the dominant state on the bus persists for longer than $t_{to(dom)bus}$, the RXD pin is reset to HIGH. This function prevents a clamped dominant bus (due to a bus short-circuit or a failure in one of the other nodes on the network) from generating a permanent wake-up request. The bus dominant time-out timer is reset when the CAN bus changes from dominant to recessive state.

7.2.3 Internal biasing of TXD and STB input pins

Pins TXD and STB have internal pull-ups to V_{IO} to ensure a safe, defined state in case one or both of these pins are left floating. Pull-up currents flow in these pins in all states; both pins should be held HIGH in Standby mode to minimize standby current.

7.2.4 Undervoltage detection on pins V_{CC} and V_{IO}

Should V_{CC} drop below the V_{CC} undervoltage detection level, $V_{uvd(VCC)}$, the transceiver will switch to Standby mode. The logic state of pin STB will be ignored until V_{CC} has recovered.

Should V_{IO} drop below the V_{IO} undervoltage detection level, $V_{uvd(VIO)}$, the transceiver will switch off and disengage from the bus (zero load) until V_{IO} has recovered.

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7.2.5 Overtemperature protection

The output drivers are protected against overtemperature conditions. If the virtual junction temperature exceeds the shutdown junction temperature, $T_{j(sd)}$, the output drivers will be disabled until the virtual junction temperature falls below $T_{j(sd)}$ and TXD becomes recessive again. Including the TXD condition ensures that output driver oscillation due to temperature drift is avoided.

7.3 SPLIT output pin and V_{IO} supply pin

Two versions of the TJA1042 are available, only differing in the function of a single pin. Pin 5 is either a SPLIT output pin or a V_{IO} supply pin.

7.3.1 SPLIT pin

Using the SPLIT pin on the TJA1042T and TJA1042CT in conjunction with a split termination network (see Figure 4 and Figure 7) can help to stabilize the recessive voltage level on the bus. This will reduce EME in networks with DC leakage to ground (e.g. from deactivated nodes with poor bus leakage performance). In Normal mode, pin SPLIT delivers a DC output voltage of $0.5V_{CC}$. In Standby mode or when V_{CC} is off, pin SPLIT is floating. When not used, the SPLIT pin should be left open.

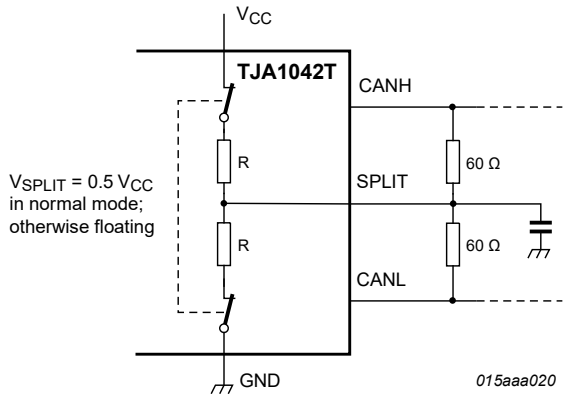


Figure 4. Stabilization circuitry and application for version with SPLIT pin

7.3.2 V_{IO} supply pin

Pin V_{IO} on the TJA1042T(K)/3 and TJA1042BT(K) variants should be connected to the microcontroller supply voltage (see Figure 8). This will adjust the signal levels of pins TXD, RXD and STB to the I/O levels of the microcontroller. Pin V_{IO} also provides the internal supply voltage for the low-power differential receiver of the transceiver. For applications running in low-power mode, this allows the bus lines to be monitored for activity even if there is no supply voltage on pin V_{CC}.

For versions of the TJA1042 without a V_{IO} pin, the V_{IO} input is internally connected to V_{CC}. This sets the signal levels of pins TXD, RXD and STB to levels compatible with 5 V microcontrollers.

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8 Limiting values

Table 5. Limiting values

In accordance with the Absolute Maximum Rating System (IEC 60134); all voltages are referenced to ground.

Symbol	Parameter	Conditions	Min	Max	Unit
V_x	voltage on pin x[1]	on pins CANH, CANL and SPLIT	-58	+58	V
		on any other pin	-0.3	+7	V
$V_{(CANH-CANL)}$	voltage between pin CANH and pin CANL		-27	+27	V
V_{trt}	transient voltage	on pins CANH, CANL [2]			
		pulse 1	-100	-	V
		pulse 2a	-	75	V
		pulse 3a	-150	-	V
		pulse 3b	-	100	V
V_{ESD}	electrostatic discharge voltage	IEC 61000-4-2 (150 pF, 330 Ω discharge circuit) [3]			
		at pins CANH and CANL	-8	+8	kV
		Human Body Model (HBM)			
		on any pin [4]	-4	+4	kV
		at pins CANH and CANL [5]	-8	+8	kV
		Machine Model (MM); 200 pF, 0.75 µH, 10 Ω [6]			
		at any pin	-300	+300	V
		Charged Device Model (CDM) [7]			
		at corner pins	-750	+750	V
		at any pin	-500	+500	V
T_{vj}	virtual junction temperature	[8]	-40	+150	°C
T_{stg}	storage temperature	[9]	-55	+150	°C

[1] The device can sustain voltages up to the specified values over the product lifetime, provided applied voltages (including transients) never exceed these values.
[2] Verified by an external test house according to IEC TS 62228, Section 4.2.4; parameters for standard pulses defined in ISO 7637.
[3] Verified by an external test house according to IEC TS 62228, Section 4.3.
[4] According to AEC-Q100-002.
[5] Pins stressed to reference group containing all ground and supply pins, emulating the application circuits (Figure 7 and Figure 8). HBM pulse as specified in AEC-Q100-002 used.
[6] According to AEC-Q100-003.
[7] According to AEC-Q100-011.
[8] In accordance with IEC 60747-1. An alternative definition of virtual junction temperature is: $T_{vj} = T_{amb} + P \times R_{th(vj-a)}$, where $R_{th(vj-a)}$ is a fixed value to be used for the calculation of T_{vj}. The rating for T_{vj} limits the allowable combinations of power dissipation (P) and ambient temperature (T_{amb}).
[9] T_{stg} in application according to IEC61360-4. For component transport and storage conditions, see instead IEC61760-2.

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9 Thermal characteristics

Table 6. Thermal characteristics

Value determined for free convection conditions on a JEDEC 2S2P board.

Symbol	Parameter	Conditions[1]	Typ	Unit
$R_{th(j-a)}$	thermal resistance from junction to ambient	SO8 package; in free air	92	K/W
		HVSON8 package; in free air	53	K/W
$R_{th(j-c)}$	thermal resistance from junction to case	HVSON8 package; in free air	14	K/W
Ψ_{j-top}	thermal characterization parameter from junction to top of package	SO8 package; in free air	12	K/W
		HVSON8 package; in free air	6	K/W

[1] According to JEDEC JESD51-2, JESD51-5 and JESD51-7 at natural convection on 2s2p board. Board with two inner copper layers (thickness: 35 µm) and thermal via array under the exposed pad connected to the first inner copper layer (thickness: 70 µm).

10 Static characteristics

Table 7. Static characteristics

T_{vj} = -40 °C to +150 °C; V_{CC} = 4.5 V to 5.5 V; V_{IO} = 2.8 V to 5.5 V[1]; R_L = 60 Ω; C_L = 100 pF unless otherwise specified; all voltages are defined with respect to ground; positive currents flow into the IC.[2]

Symbol	Parameter	Conditions	Min	Typ	Max	Unit
Supply; pin V_{CC}						
V_{CC}	supply voltage		4.5	-	5.5	V
$V_{uvd(VCC)}$	undervoltage detection voltage on pin V_{CC}	[3]	3.5	-	4.5	V
I_{CC}	supply current	Standby mode				
		TJA1042(C)T; $V_{TXD} = V_{CC}$	-	10	15	µA
		TJA1042T(K)/3, TJA1042BT(K); $V_{TXD} = V_{IO}$	-	-	5	µA
		Normal mode				
		recessive; $V_{TXD} = V_{IO}$[4]	2.5	5	10	mA
		dominant; V_{TXD} = 0 V	20	45	70	mA
		dominant; V_{TXD} = 0 V; short circuit on bus lines; -3 V < ($V_{CANH} = V_{CANL}$) < +18 V	2.5	80	110	mA
I/O level adapter supply; pin V_{IO}[1]						
V_{IO}	supply voltage on pin V_{IO}		2.8	-	5.5	V
$V_{uvd(VIO)}$	undervoltage detection voltage on pin V_{IO}	[3]	1.3	2.0	2.7	V
I_{IO}	supply current on pin V_{IO}	Standby mode; $V_{TXD} = V_{IO}$	5	-	14	µA
		Normal mode				
		recessive; $V_{TXD} = V_{IO}$	15	80	200	µA
		dominant; V_{TXD} = 0 V	-	350	1000	µA

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Table 7. Static characteristics*...continued*

T_{vj} = -40 °C to +150 °C; V_{CC} = 4.5 V to 5.5 V; V_{IO} = 2.8 V to 5.5 V[1]; R_L = 60 Ω; C_L = 100 pF unless otherwise specified; all voltages are defined with respect to ground; positive currents flow into the IC.[2]

Symbol	Parameter	Conditions	Min	Typ	Max	Unit
Standby mode control input; pin STB						
V_{IH}	HIGH-level input voltage	[5]	$0.7V_{IO}$[4]	-	V_{IO}[4] + 0.3	V
V_{IL}	LOW-level input voltage		-0.3	-	$0.3V_{IO}$[4]	V
I_{IH}	HIGH-level input current	$V_{STB} = V_{IO}$[4]	-1	-	+1	µA
I_{IL}	LOW-level input current	V_{STB} = 0 V	-15	-	-1	µA
CAN transmit data input; pin TXD						
V_{IH}	HIGH-level input voltage	[5]	$0.7V_{IO}$[4]	-	V_{IO}[4] + 0.3	V
V_{IL}	LOW-level input voltage		-0.3	-	$0.3V_{IO}$[4]	V
I_{IH}	HIGH-level input current	$V_{TXD} = V_{IO}$[4]	-5	-	+5	µA
I_{IL}	LOW-level input current	V_{TXD} = 0 V	-260	-150	-30	µA
C_i	input capacitance	[6]	-	5	10	pF
CAN receive data output; pin RXD						
I_{OH}	HIGH-level output current	$V_{RXD} = V_{IO}$ - 0.4 V [4]	-9	-3	-1	mA
I_{OL}	LOW-level output current	V_{RXD} = 0.4 V; bus dominant	2	5	12	mA
Bus lines; pins CANH and CANL						
$V_{O(dom)}$	dominant output voltage	V_{TXD} = 0 V; t < $t_{to(dom)TXD}$				
		pin CANH; R_L = 50 Ω to 65 Ω	2.75	3.5	4.5	V
		pin CANL; R_L = 50 Ω to 65 Ω	0.5	1.5	2.25	V
$V_{dom(TX)sym}$	transmitter dominant voltage symmetry	$V_{dom(TX)sym} = V_{CC} - V_{CANH} - V_{CANL}$	-400	-	+400	mV
V_{TXsym}	transmitter voltage symmetry	$V_{TXsym} = V_{CANH} + V_{CANL}$; f_{TXD} = 250 kHz, 1 MHz and 2.5 MHz; C_{SPLIT} = 4.7 nF; V_{CC} = 4.75 V to 5.25 V [6] [7]	$0.9V_{CC}$	-	$1.1V_{CC}$	V
$V_{O(dif)}$	differential output voltage	dominant: Normal mode; V_{TXD} = 0 V; t < $t_{to(dom)TXD}$; V_{CC} = 4.75 V to 5.25 V				
		R_L = 45 Ω to 65 Ω	1.5	-	3	V
		R_L = 45 Ω to 70 Ω	1.5	-	3.3	V
		R_L = 2 240 Ω	1.5	-	5	V
		recessive; no load				
		Normal mode: $V_{TXD} = V_{IO}$[4]	-50	-	+50	mV
		Standby mode	-0.2	-	+0.2	V
$V_{O(rec)}$	recessive output voltage	Normal mode; $V_{TXD} = V_{IO}$[4]; no load	2	$0.5V_{CC}$	3	V
		Standby mode; no load	-0.1	-	+0.1	V

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Table 7. Static characteristics...*continued*

T_{vj} = -40 °C to +150 °C; V_{CC} = 4.5 V to 5.5 V; V_{IO} = 2.8 V to 5.5 V[1]; R_L = 60 Ω; C_L = 100 pF unless otherwise specified; all voltages are defined with respect to ground; positive currents flow into the IC.[2]

Symbol	Parameter	Conditions	Min	Typ	Max	Unit
$V_{th(RX)dif}$	differential receiver threshold voltage	-30 V ≤ V_{CANL} ≤ +30 V; -30 V ≤ V_{CANH} ≤ +30 V				
		Normal mode	0.5	0.7	0.9	V
		Standby mode [8]	0.4	0.7	1.15	V
$V_{rec(RX)}$	receiver recessive voltage	-30 V ≤ V_{CANL} ≤ +30 V; -30 V ≤ V_{CANH} ≤ +30 V [6]				
		Normal mode	-4	-	0.5	V
		Standby mode	-4	-	0.4	V
$V_{dom(RX)}$	receiver dominant voltage	-30 V ≤ V_{CANL} ≤ +30 V; -30 V ≤ V_{CANH} ≤ +30 V [6]				
		Normal mode	0.9	-	9.0	V
		Standby mode	1.15	-	9.0	V
$V_{hys(RX)dif}$	differential receiver hysteresis voltage	-30 V ≤ V_{CANL} ≤ +30 V; -30 V ≤ V_{CANH} ≤ +30 V	50	120	200	mV
$I_{O(sc)dom}$	dominant short-circuit output current	V_{TXD} = 0 V; t < $t_{to(dom)TXD}$; V_{CC} = 5 V				
		pin CANH; V_{CANH} = -15 V to +40 V	-100	-70	-	mA
		pin CANL; V_{CANL} = -15 V to +40 V	-	70	100	mA
$I_{O(sc)rec}$	recessive short-circuit output current	Normal mode; V_{TXD} = V_{IO}[4] V_{CANH} = V_{CANL} = -27 V to +32 V	-5	-	+5	mA
I_L	leakage current	V_{CC} = V_{IO} = 0 V or V_{CC} = V_{IO} = shorted to ground via 47 kΩ; V_{CANH} = V_{CANL} = 5 V	-5	-	+5	µA
R_i	input resistance	-2 V ≤ V_{CANL} ≤ +7 V; -2 V ≤ V_{CANH} ≤ +7 V [6]	9	15	28	kΩ
ΔR_i	input resistance deviation	0 V ≤ V_{CANL} ≤ +5 V; 0 V ≤ V_{CANH} ≤ +5 V [6]	-1	-	+1	%
$R_{i(dif)}$	differential input resistance	-2 V ≤ V_{CANL} ≤ +7 V; -2 V ≤ V_{CANH} ≤ +7 V [6]	19	30	52	kΩ
$C_{i(cm)}$	common-mode input capacitance	[6]	-	-	20	pF
$C_{i(dif)}$	differential input capacitance	[6]	-	-	10	pF
Common mode stabilization output; pin SPLIT; only for TJA1042T and TJA1042CT						
V_O	output voltage	Normal mode I_{SPLIT} = -500 µA to +500 µA	0.3V_{CC}	0.5V_{CC}	0.7V_{CC}	V
		Normal mode; R_L = 1 MΩ	0.45V_{CC}	0.5V_{CC}	0.55V_{CC}	V
I_L	leakage current	Standby mode V_{SPLIT} = -58 V to +58 V	-5	-	+5	µA

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Table 7. Static characteristics...*continued*

T_{vj} = -40 °C to +150 °C; V_{CC} = 4.5 V to 5.5 V; V_{IO} = 2.8 V to 5.5 V[1]; R_L = 60 Ω; C_L = 100 pF unless otherwise specified; all voltages are defined with respect to ground; positive currents flow into the IC.[2]

Symbol	Parameter	Conditions	Min	Typ	Max	Unit
Temperature detection						
$T_{j(sd)}$	shutdown junction temperature	[6]	-	190	-	°C

[1] Only the TJA1042T(K)/3 and TJA1042BT(K) variants have a V_{IO} pin; for the TJA1042T and TJA1042CT variants, the V_{IO} input is internally connected to V_{CC}.
[2] All parameters are guaranteed over the virtual junction temperature range by design. Factory testing uses correlated test conditions to cover the specified temperature and power supply voltage range.
[3] Undervoltage is detected between min and max values. Undervoltage is guaranteed to be detected below min value and guaranteed not to be detected above max value.
[4] V_{IO} = V_{CC} for the non-V_{IO} product variants.
[5] Maximum value assumes V_{CC} < V_{IO}; if V_{CC} > V_{IO}, the maximum value will be V_{CC} + 0.3 V.
[6] Not tested in production; guaranteed by design.
[7] The test circuit used to measure the bus output voltage symmetry (which includes CSPLIT) is shown in Figure 10.
[8] Variants with a a V_{IO} pin: values valid when -12 V ≤ V_{CANL} ≤ +12 V and -12 V ≤ V_{CANH} ≤ +12 V.

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11 Dynamic characteristics

Table 8. Dynamic characteristics

T_{vj} = -40 °C to +150 °C; V_{CC} = 4.5 V to 5.5 V; V_{IO} = 2.8 V to 5.5 V[1]; R_L = 60 Ω unless specified otherwise; all voltages are defined with respect to ground.[2]

Symbol	Parameter	Conditions	Min	Typ	Max	Unit
Transceiver timing; pins CANH, CANL, TXD and RXD; seeFigure 5, Figure 6 and Figure 9						
$t_{d(TXD-busdom)}$	delay time from TXD to bus dominant	TJA1042B/C; Normal mode	-	60	100	ns
		TJA1042T, T(K)/3	-	65	100	ns
$t_{d(TXD-busrec)}$	delay time from TXD to bus recessive	TJA1042B/C; Normal mode	-	70	115	ns
		TJA1042T, T(K)/3	-	90	125	ns
$t_{d(busdom-RXD)}$	delay time from bus dominant to RXD	TJA1042B/C; Normal mode	-	55	100	ns
		TJA1042T, T(K)/3	-	60	110	ns
$t_{d(busrec-RXD)}$	delay time from bus recessive to RXD	TJA1042B/C; Normal mode	-	60	145	ns
		TJA1042T, T(K)/3	-	65	155	ns
$t_{d(TXDL-RXDL)}$	delay time from TXD LOW to RXD LOW	TJA1042B; Normal mode	60	-	225	ns
		TJA1042C; Normal mode	60	-	195	ns
		TJA1042T(K)/3; Normal mode	60	-	250	ns
		TJA1042T; Normal mode	60	-	220	ns
$t_{d(TXDH-RXDH)}$	delay time from TXD HIGH to RXD HIGH	TJA1042B; Normal mode	60	-	225	ns
		TJA1042C; Normal mode	60	-	195	ns
		TJA1042T(K)/3; Normal mode	60	-	250	ns
		TJA1042T; Normal mode	60	-	220	ns
$t_{bit(bus)}$	transmitted recessive bit width	$t_{bit(TXD)}$ = 500 ns [3]	435	-	530	ns
		$t_{bit(TXD)}$ = 200 ns [3]	155	-	210	ns
$t_{bit(RXD)}$	bit time on pin RXD	$t_{bit(TXD)}$ = 500 ns [3]	400	-	550	ns
		$t_{bit(TXD)}$ = 200 ns [3]	120	-	220	ns
Δt_{rec}	receiver timing symmetry	$t_{bit(TXD)}$ = 500 ns	-65	-	+40	ns
		$t_{bit(TXD)}$ = 200 ns	-45	-	+15	ns
$t_{to(dom)TXD}$	TXD dominant time-out time	V_{TXD} = 0 V; Normal mode [4]	0.3	2	5	ms
$t_{to(dom)bus}$	bus dominant time-out time	Standby mode [5]	0.3	2	5	ms
$t_{fltr(wake)bus}$	bus wake-up filter time	version with SPLIT pin; Standby mode	0.5	1	3	µs
		versions with V_{IO} pin; Standby mode	0.5	1.5	5	µs
$t_{d(stb-norm)}$	standby to normal mode delay time		7	25	47	µs

[1] Only the TJA1042T(K)/3 and TJA1042BT(K) variants have a V_{IO} pin; for the TJA1042T and TJA1042CT variants, the V_{IO} input is internally connected to V_{CC}.

[2] All parameters are guaranteed over the virtual junction temperature range by design. Factory testing uses correlated test conditions to cover the specified temperature and power supply voltage range.

[3] See Figure 6.

[4] Minimum value of 0.8 ms required according to SAE J2284; 0.3 ms is allowed according to ISO11898-2:2016 for legacy devices. Time-out occurs between the min and max values. Time-out is guaranteed not to occur below the min value; time-out is guaranteed to occur above the max value.

[5] Time-out occurs between the min and max values. Time-out is guaranteed not to occur below the min value; time-out is guaranteed to occur above the max value.

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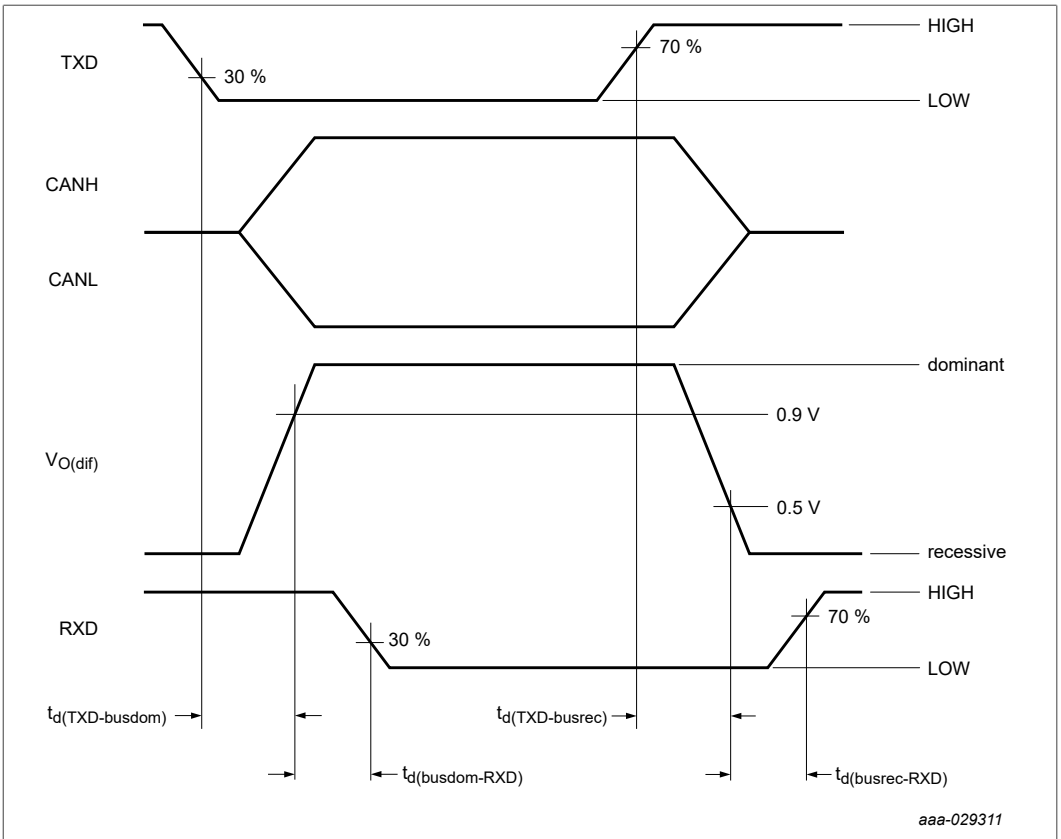


Figure 5. CAN transceiver timing diagram

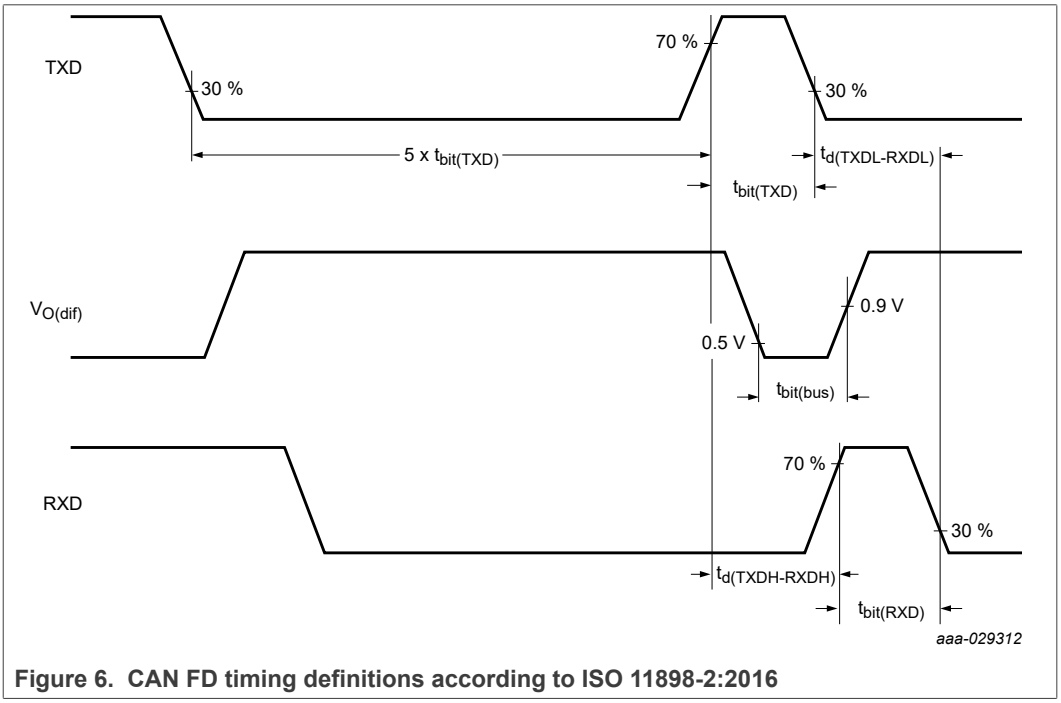


Figure 6. CAN FD timing definitions according to ISO 11898-2:2016

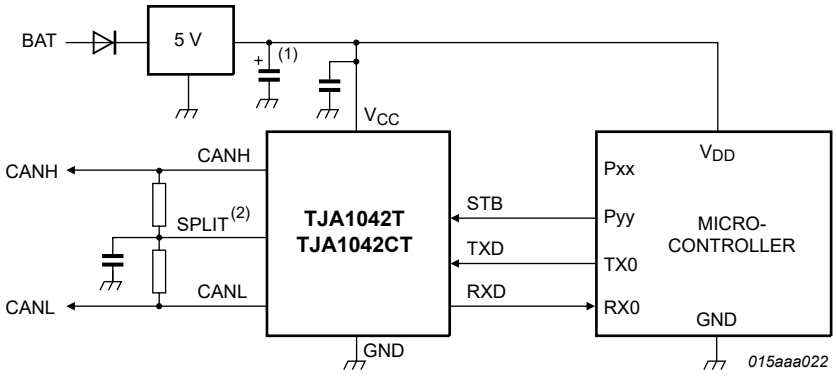
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12 Application information

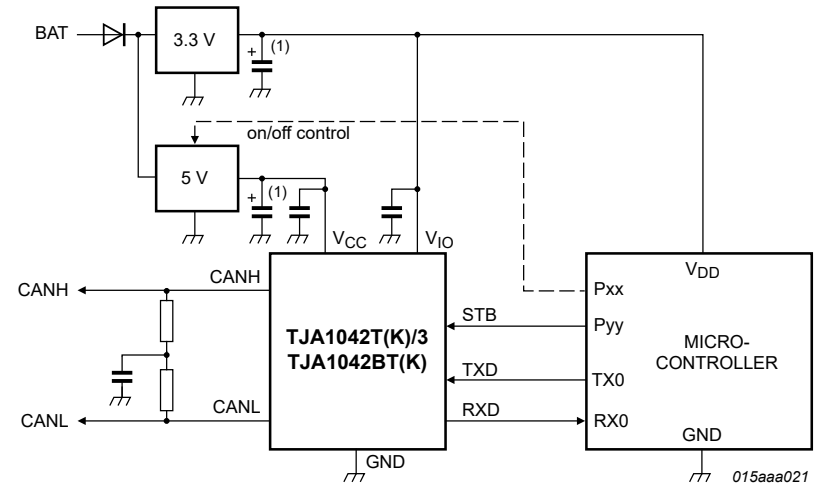
The minimum external circuitry needed with the TJA1042 is shown in Figure 7 and Figure 8. See the Application Hints (Section 12.2) for further information about external components and PCB layout requirements.

12.1 Application diagrams



1. Optional, depends on regulator.
2. Optional common mode stabilization by a voltage source of $V_{CC}/2$ at pin SPLIT.

Figure 7. Typical TJA1042 application with a 5 V microcontroller (non-V_{IO} variants)



1. Optional, depends on regulator.

Figure 8. Typical TJA1042 application with a 3.3 V microcontroller (V_{IO} variants).

12.2 Application hints

Further information on the application of the TJA1042 can be found in NXP application hints *AH1014 'Application Hints - Standalone high speed CAN transceiver TJA1042/ TJA1043/TJA1048/TJA1051'.*

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13 Test information

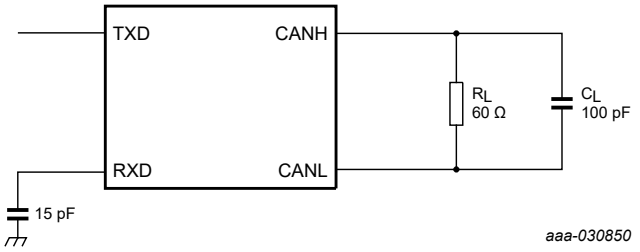


Figure 9. CAN transceiver timing test circuit

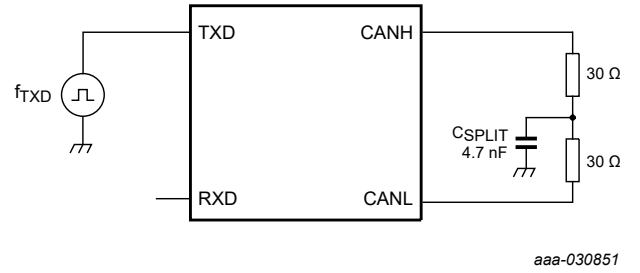


Figure 10. Test circuit for measuring transceiver driver symmetry

13.1 Quality information

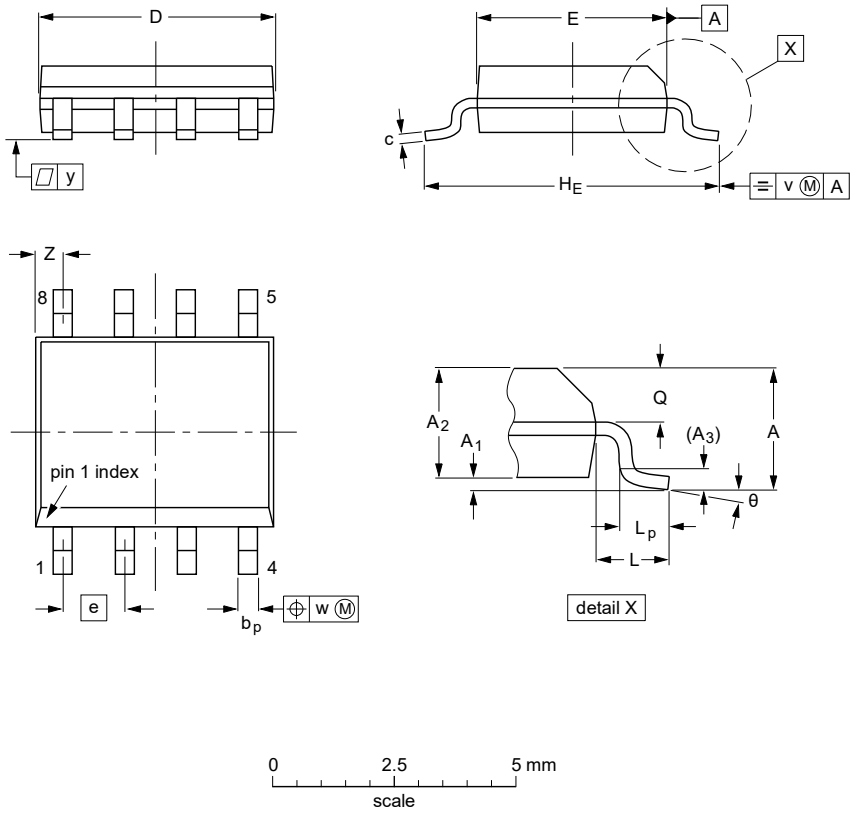
This product has been qualified in accordance with the Automotive Electronics Council (AEC) standard *Q100 Rev-G - Failure mechanism based stress test qualification for integrated circuits*, and is suitable for use in automotive applications.

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14 Package outline

SO8: plastic small outline package; 8 leads; body width 3.9 mm **SOT96-1**



DIMENSIONS (inch dimensions are derived from the original mm dimensions)

UNIT	A max.	A_1	A_2	A_3	b_p	c	$D^{(1)}$	$E^{(2)}$	e	H_E	L	L_p	Q	v	w	y	$Z^{(1)}$	θ
mm	1.75	0.25 0.10	1.45 1.25	0.25	0.49 0.36	0.25 0.19	5.0 4.8	4.0 3.8	1.27	6.2 5.8	1.05	1.0 0.4	0.7 0.6	0.25	0.25	0.1	0.7 0.3	8° 0°
inches	0.069	0.010 0.004	0.057 0.049	0.01	0.019 0.014	0.0100 0.0075	0.20 0.19	0.16 0.15	0.05	0.244 0.228	0.041	0.039 0.016	0.028 0.024	0.01	0.01	0.004	0.028 0.012	

Notes

1. Plastic or metal protrusions of 0.15 mm (0.006 inch) maximum per side are not included.
2. Plastic or metal protrusions of 0.25 mm (0.01 inch) maximum per side are not included.

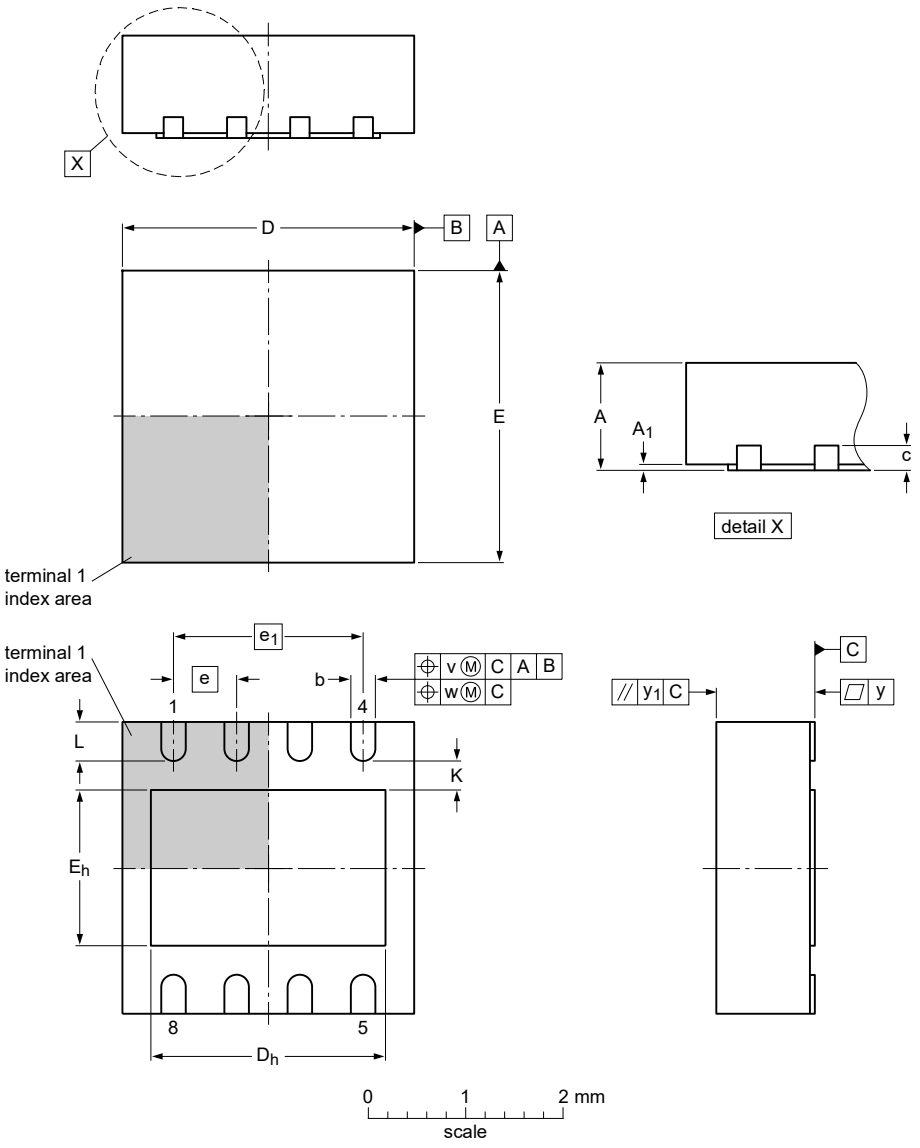
OUTLINE VERSION	REFERENCES				EUROPEAN PROJECTION	ISSUE DATE
	IEC	JEDEC	JEITA			
SOT96-1	076E03	MS-012				~~99-12-27~~ 03-02-18

Figure 11. Package outline SOT96-1 (SO8)

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HVSON8: plastic thermal enhanced very thin small outline package; no leads; 8 terminals; body 3 x 3 x 0.85 mm **SOT782-1**



Dimensions

Unit(1)		A	A_1	b	c	D	D_h	E	E_h	e	e_1	K	L	v	w	y	y_1
mm	max	1.00	0.05	0.35		3.10	2.45	3.10	1.65			0.35	0.45				
	nom	0.85	0.03	0.30	0.2	3.00	2.40	3.00	1.60	0.65	1.95	0.30	0.40	0.1	0.05	0.05	0.1
	min	0.80	0.00	0.25		2.90	2.35	2.90	1.55			0.25	0.35				

Note
1. Plastic or metal protrusions of 0.075 maximum per side are not included.

sot782-1_po

Outline version	References				European projection	Issue date
	IEC	JEDEC	JEITA			
SOT782-1	- - -	MO-229	- - -			~~09-08-25~~ 09-08-28

Figure 12. Package outline SOT782-1 (HVSON8)

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15 Handling information

All input and output pins are protected against ElectroStatic Discharge (ESD) under normal handling. When handling ensure that the appropriate precautions are taken as described in *JESD625-A* or equivalent standards.

16 Soldering of SMD packages

This text provides a very brief insight into a complex technology. A more in-depth account of soldering ICs can be found in Application Note *AN10365 "Surface mount reflow soldering description"*.

16.1 Introduction to soldering

Soldering is one of the most common methods through which packages are attached to Printed Circuit Boards (PCBs), to form electrical circuits. The soldered joint provides both the mechanical and the electrical connection. There is no single soldering method that is ideal for all IC packages. Wave soldering is often preferred when through-hole and Surface Mount Devices (SMDs) are mixed on one printed wiring board; however, it is not suitable for fine pitch SMDs. Reflow soldering is ideal for the small pitches and high densities that come with increased miniaturization.

16.2 Wave and reflow soldering

Wave soldering is a joining technology in which the joints are made by solder coming from a standing wave of liquid solder. The wave soldering process is suitable for the following:

- Through-hole components
- Leaded or leadless SMDs, which are glued to the surface of the printed circuit board

Not all SMDs can be wave soldered. Packages with solder balls, and some leadless packages which have solder lands underneath the body, cannot be wave soldered. Also, leaded SMDs with leads having a pitch smaller than ~0.6 mm cannot be wave soldered, due to an increased probability of bridging.

The reflow soldering process involves applying solder paste to a board, followed by component placement and exposure to a temperature profile. Leaded packages, packages with solder balls, and leadless packages are all reflow solderable.

Key characteristics in both wave and reflow soldering are:

- Board specifications, including the board finish, solder masks and vias
- Package footprints, including solder thieves and orientation
- The moisture sensitivity level of the packages
- Package placement
- Inspection and repair
- Lead-free soldering versus SnPb soldering

16.3 Wave soldering

Key characteristics in wave soldering are:

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- Process issues, such as application of adhesive and flux, clinching of leads, board transport, the solder wave parameters, and the time during which components are exposed to the wave
- Solder bath specifications, including temperature and impurities

16.4 Reflow soldering

Key characteristics in reflow soldering are:

- Lead-free versus SnPb soldering; note that a lead-free reflow process usually leads to higher minimum peak temperatures (see Figure 13) than a SnPb process, thus reducing the process window
- Solder paste printing issues including smearing, release, and adjusting the process window for a mix of large and small components on one board
- Reflow temperature profile; this profile includes preheat, reflow (in which the board is heated to the peak temperature) and cooling down. It is imperative that the peak temperature is high enough for the solder to make reliable solder joints (a solder paste characteristic). In addition, the peak temperature must be low enough that the packages and/or boards are not damaged. The peak temperature of the package depends on package thickness and volume and is classified in accordance with Table 9 and Table 10

Table 9. SnPb eutectic process (from J-STD-020D)

Package thickness (mm)	Package reflow temperature (°C)	
	Volume (mm³)	
	< 350	≥ 350
< 2.5	235	220
≥ 2.5	220	220

Table 10. Lead-free process (from J-STD-020D)

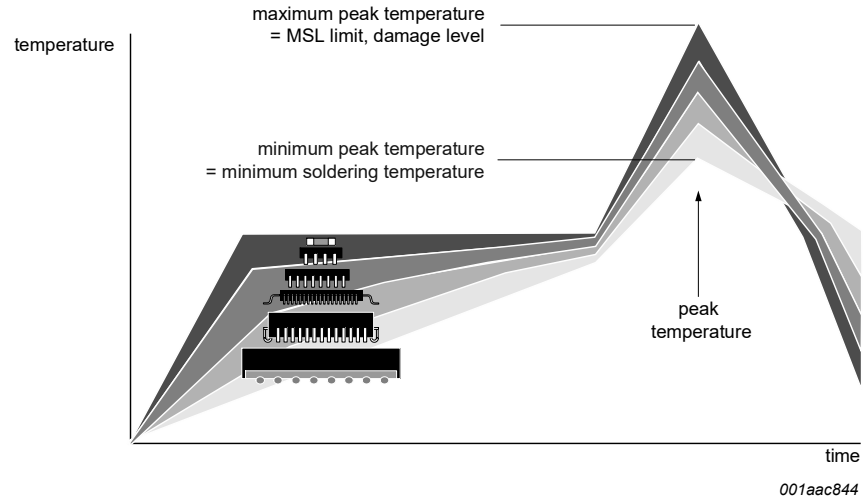
Package thickness (mm)	Package reflow temperature (°C)		
	Volume (mm³)		
	< 350	350 to 2000	> 2000
< 1.6	260	260	260
1.6 to 2.5	260	250	245
> 2.5	250	245	245

Moisture sensitivity precautions, as indicated on the packing, must be respected at all times.

Studies have shown that small packages reach higher temperatures during reflow soldering, see Figure 13.

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MSL: Moisture Sensitivity Level

Figure 13. Temperature profiles for large and small components

For further information on temperature profiles, refer to Application Note *AN10365 "Surface mount reflow soldering description"*.

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17 Appendix: ISO 11898-2:2016 parameter cross-reference list

Table 11. ISO 11898-2:2016 to NXP data sheet parameter conversion

ISO 11898-2:2016		NXP data sheet	
Parameter	**Notation**	**Symbol**	**Parameter**
HS-PMA dominant output characteristics			
Single ended voltage on CAN_H	V_{CAN_H}	$V_{O(dom)}$	dominant output voltage
Single ended voltage on CAN_L	V_{CAN_L}		
Differential voltage on normal bus load	V_{Diff}	$V_{O(dif)}$	differential output voltage
Differential voltage on effective resistance during arbitration			
Optional: Differential voltage on extended bus load range			
HS-PMA driver symmetry			
Driver symmetry	V_{SYM}	V_{TXsym}	transmitter voltage symmetry
Maximum HS-PMA driver output current			
Absolute current on CAN_H	I_{CAN_H}	$I_{O(sc)dom}$	dominant short-circuit output current
Absolute current on CAN_L	I_{CAN_L}		
HS-PMA recessive output characteristics, bus biasing active/inactive			
Single ended output voltage on CAN_H	V_{CAN_H}	$V_{O(rec)}$	recessive output voltage
Single ended output voltage on CAN_L	V_{CAN_L}		
Differential output voltage	V_{Diff}	$V_{O(dif)}$	differential output voltage
Optional HS-PMA transmit dominant timeout			
Transmit dominant timeout, long	t_{dom}	$t_{to(dom)TXD}$	TXD dominant time-out time
Transmit dominant timeout, short			
HS-PMA static receiver input characteristics, bus biasing active/inactive			
Recessive state differential input voltage range Dominant state differential input voltage range	V_{Diff}	$V_{th(RX)dif}$	differential receiver threshold voltage
		$V_{rec(RX)}$	receiver recessive voltage
		$V_{dom(RX)}$	receiver dominant voltage
HS-PMA receiver input resistance (matching)			
Differential internal resistance	R_{Diff}	$R_{i(dif)}$	differential input resistance
Single ended internal resistance	R_{CAN_H} R_{CAN_L}	R_i	input resistance
Matching of internal resistance	MR	ΔR_i	input resistance deviation
HS-PMA implementation loop delay requirement			
Loop delay	t_{Loop}	$t_{d(TXDH-RXDH)}$	delay time from TXD HIGH to RXD HIGH
		$t_{d(TXDL-RXDL)}$	delay time from TXD LOW to RXD LOW

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Table 11. ISO 11898-2:2016 to NXP data sheet parameter conversion*...continued*

ISO 11898-2:2016		NXP data sheet	
Parameter	**Notation**	**Symbol**	**Parameter**
Optional HS-PMA implementation data signal timing requirements for use with bit rates above 1 Mbit/s up to 2 Mbit/s and above 2 Mbit/s up to 5 Mbit/s			
Transmitted recessive bit width @ 2 Mbit/s / @ 5 Mbit/s, intended	$t_{Bit(Bus)}$	$t_{bit(bus)}$	transmitted recessive bit width
Received recessive bit width @ 2 Mbit/s / @ 5 Mbit/s	$t_{Bit(RXD)}$	$t_{bit(RXD)}$	bit time on pin RXD
Receiver timing symmetry @ 2 Mbit/s / @ 5 Mbit/s	Δt_{Rec}	Δt_{rec}	receiver timing symmetry
HS-PMA maximum ratings of V_{CAN_H}, V_{CAN_L} and V_{Diff}			
Maximum rating V_{Diff}	V_{Diff}	$V_{(CANH-CANL)}$	voltage between pin CANH and pin CANL
General maximum rating V_{CAN_H} and V_{CAN_L}	V_{CAN_H} V_{CAN_L}	V_x	voltage on pin x
Optional: Extended maximum rating VCAN_H and VCAN_L			
HS-PMA maximum leakage currents on CAN_H and CAN_L, unpowered			
Leakage current on CAN_H, CAN_L	I_{CAN_H} I_{CAN_L}	I_L	leakage current
HS-PMA bus biasing control timings			
CAN activity filter time, long	t_{Filter}	$t_{wake(busdom)}$ [1]	bus dominant wake-up time
CAN activity filter time, short		$t_{wake(busrec)}$ [1]	bus recessive wake-up time
Wake-up timeout, short	t_{Wake}	$t_{to(wake)bus}$	bus wake-up time-out time
Wake-up timeout, long			
Timeout for bus inactivity	$t_{Silence}$	$t_{to(silence)}$	bus silence time-out time
Bus Bias reaction time	t_{Bias}	$t_{d(busact-bias)}$	delay time from bus active to bias

[1] $t_{fltr(wake)bus}$ - bus wake-up filter time, in devices with basic wake-up functionality

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18 Revision history

Table 12. Revision history

Document ID	Release date	Data sheet status	Change notice	Supersedes
TJA1042 v.11	20230116	Product data sheet	-	TJA1042 v.10
Modifications:	• Added variants TJA1042BT(K) and TJA1042CT with shorter propagation delay • Section 2.1: SAE J1939-14 compliance added • Section 2.1: EMC compliance updated to latest standards IEC 62228-3 and SAE J2962-2 • Section 2.2: updated text describing supply undervoltage behavior • Table 3: pin type column added • Table 5: format and footnotes revised; no specification changes • Table 6: parameter definitions and specifications updated • Table 7: footnotes updated/added; parameter values changed: $I_{O(sc)dom}$, I_{OH} for pin RXD (min value) • Table 8: delay time parameter values revised and footnotes updated/added • Figure 5 and Figure 6: timing diagrams revised • Section 12: introductory paragraph added • Figure 9 and Figure 10: drawings revised • Section 17: 'Soldering of HVSON packages' removed • Section 19: legal information updated			
TJA1042 v.10	20171124	Product data sheet	-	TJA1042 v.9
TJA1042 v.9	20160523	Product data sheet	-	TJA1042 v.8
TJA1042 v.8	20150115	Product data sheet	-	TJA1042 v.7
TJA1042 v.7	20120508	Product data sheet	-	TJA1042 v.6
TJA1042 v.6	20110323	Product data sheet	-	TJA1042 v.5
TJA1042 v.5	20110118	Product data sheet	-	TJA1042 v.4
TJA1042 v.4	20091006	Product data sheet	-	TJA1042 v.3
TJA1042 v.3	20090825	Product data sheet	-	TJA1042 v.2
TJA1042 v.2	20090708	Product data sheet	-	TJA1042 v.1
TJA1042 v.1	20090309	Product data sheet	-	-

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19 Legal information

19.1 Data sheet status

Document status[1][2]	Product status[3]	Definition
Objective [short] data sheet	Development	This document contains data from the objective specification for product development.
Preliminary [short] data sheet	Qualification	This document contains data from the preliminary specification.
Product [short] data sheet	Production	This document contains the product specification.

[1] Please consult the most recently issued document before initiating or completing a design.
[2] The term 'short data sheet' is explained in section "Definitions".
[3] The product status of device(s) described in this document may have changed since this document was published and may differ in case of multiple devices. The latest product status information is available on the Internet at URL http://www.nxp.com.

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Contents

1 General description 1
2 Features and benefits 1
2.1 General 1
2.2 Predictable and fail-safe behavior 2
2.3 Protections 2
3 Quick reference data 2
4 Ordering information 3
5 Block diagram 3
6 Pinning information 4
6.1 Pinning 4
6.2 Pin description 4
7 Functional description 5
7.1 Operating modes 5
7.1.1 Normal mode 5
7.1.2 Standby mode 5
7.2 Fail-safe features 6
7.2.1 TXD dominant time-out function 6
7.2.2 Bus dominant time-out function 6
7.2.3 Internal biasing of TXD and STB input pins 6
7.2.4 Undervoltage detection on pins VCC and VIO 6
7.2.5 Overtemperature protection 7
7.3 SPLIT output pin and VIO supply pin 7
7.3.1 SPLIT pin 7
7.3.2 VIO supply pin 7
8 Limiting values 8
9 Thermal characteristics 9
10 Static characteristics 9
11 Dynamic characteristics 13
12 Application information 15
12.1 Application diagrams 15
12.2 Application hints 15
13 Test information 16
13.1 Quality information 16
14 Package outline 17
15 Handling information 19
16 Soldering of SMD packages 19
16.1 Introduction to soldering .....
16.2 Wave and reflow soldering .....
16.3 Wave soldering .....
16.4 Reflow soldering .....
17 Appendix: ISO 11898-2:2016 parameter cross-reference list 22
18 Revision history 24
19 Legal information 25

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