AMC1301 Precision, ±250-mV Input, Reinforced Isolated Amplifier

1 Features

- ±250-mV input voltage range optimized for current measurements using shunt resistors
- Fixed gain: 8.2 V/V
- Low DC errors:
  - Offset error: ±0.2 mV (max)
  - Offset drift: ±3 µV/°C (max)
  - Gain error: ±0.3% (max)
  - Gain drift: ±50 ppm/°C (max)
  - Nonlinearity: 0.03% (max)
- 3.3-V operation on high-side and low-side
- System-level diagnostic features
- Safety-related certifications:
  - 7070-V_{PK} reinforced isolation per DIN EN IEC 60747-17 (VDE 0884-17)
  - 5000-V_{RMS} isolation for 1 minute per UL1577
- Fully specified over the extended industrial temperature range: –40°C to +125°C

2 Applications

- Shunt-resistor-based current sensing in:
  - Motor drives
  - Frequency inverters
  - Uninterruptible power supplies

3 Description

The AMC1301 is a precision, isolated amplifier with an output separated from the input circuitry by an isolation barrier that is highly resistant to magnetic interference. This barrier is certified to provide reinforced isolation of up to 7070 V_{PEAK} according to the DIN EN IEC 60747-17 (VDE 0884-17) and UL1577 standards, and supports a working voltage up to 1 kV_{RMS}.

The isolation barrier separates parts of the system that operate on different common-mode voltage levels and protects the low-side from voltage levels that can cause electrical damage and are potentially harmful to an operator.

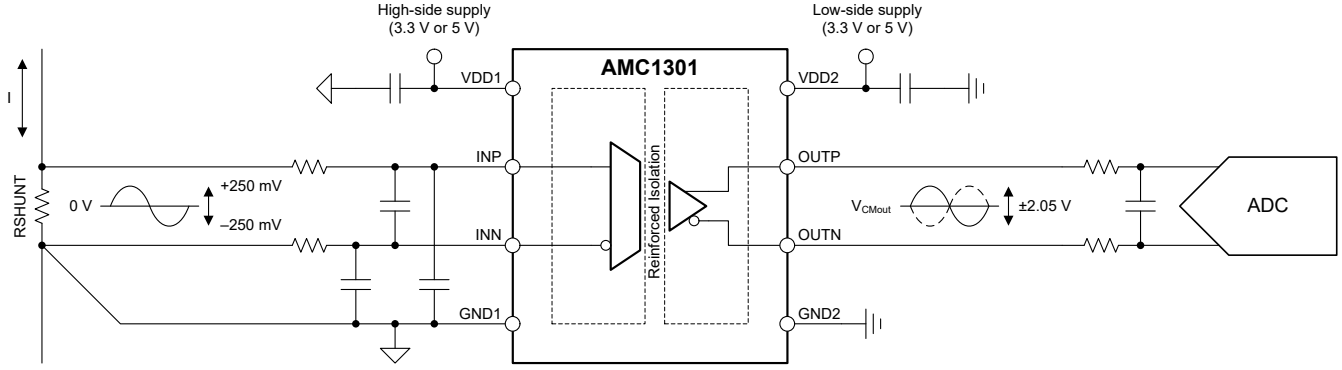
The input of the AMC1301 is optimized for direct connection to shunt resistors or other low voltage-level signal sources. The excellent DC accuracy and low temperature drift supports accurate current control in onboard chargers (OBC), DC/DC converters, frequency inverters, or other high-voltage applications. The integrated common-mode overvoltage and missing high-side supply voltage detection features of the AMC1301 simplify system-level design and diagnostics.

The AMC1301 is fully specified over the extended industrial temperature range of –40°C to +125°C and is available in a wide-body 8-pin SOIC (DWV) package. The AMC1301S is specified over the temperature range of –55°C to +125°C.

Package Information

PART NUMBER	PACKAGE(1)	BODY SIZE (NOM)
AMC1301	DWV (SOIC, 8)	5.85 mm × 7.50 mm

(1) For all available packages, see the orderable addendum at the end of the data sheet.



Simplified Schematic

An IMPORTANT NOTICE at the end of this data sheet addresses availability, warranty, changes, use in safety-critical applications, intellectual property matters and other important disclaimers. PRODUCTION DATA.

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4 Revision History

NOTE: Page numbers for previous revisions may differ from page numbers in the current version.

Changes from March 14, 2023 to April 24, 2023 (from Revision F (April 2020) to Revision G (April 2023)) **Page**

- Changed document title....1
- Changed *Features* section: Changed, deleted, and reorganized bullets....1
- Changed isolation standard from DIN VDE V 0884-11 (VDE V 0884-10) to DIN EN IEC 60747-17 (VDE 0884-17) and updated the *Insulation Specifications* and *Safety-Related Certifications* tables accordingly....1
- Deleted last bullet from *Applications* section....1
- Changed *Description* section to include common-mode decoupling capacitors as a known best practice....1
- Changed pin names VINP to INP, VINN to INN, VOUTP to OUTP, and VOUTN to OUTN throughout document....4
- Changed *Description* column and added footnotes to *Pin Functions* table....4
- Changed CDM ESD standard from JESD22-C101 to JDEC JS-002 5
- Changed PD from 81.4 mW to 99 mW....6
- Changed PD1 (VDD1 = 3.3 V) from 24.85 mW to 31 mW....6
- Changed PD1 (VDD1 = 5.5 V) from 45.65 mW to 54 mW....6
- Changed PD2 (VDD2 = 3.3 V) from 20.16 mW to 26 mW....6
- Changed PD2 (VDD2 = 5.5 V) from 35.75 mW to 45 mW....6
- Changed DTI from ≥0.027 mm to ≥0.021 mm in *Insulation Specifications* table....7
- Changed IDD1 (3.0 V ≤ VDD1 ≤ 3.6 V) from 5.0 mA (typ) / 6.9 mA (max) to 6.3 mA (typ) / 8.5 mA (max)....9
- Changed IDD1 (4.5 V ≤ VDD1 ≤ 5.5 V) from 5.9 mA (typ) / 8.3 mA (max) to 7.2 mA (typ) / 9.8 mA (max)....9
- Changed IDD2 (3.0 V ≤ VDD2 ≤ 3.6 V) from 4.4 mA (typ) / 5.6 mA (max) to 5.3 mA (typ) / 7.2 mA (max)....9
- Changed IDD2 (4.5 V ≤ VDD2 ≤ 5.5 V) from 4.8 mA (typ) / 6.5 mA (max) to 5.9 mA (typ) / 8.1 mA (max)....9
- Changed *Timing Diagram* section....10
- Changed *Overview* section....19
- Changed *Functional Block Diagram* image....19
- Changed the *Analog Input* section....19
- Added the *Isolation Channel Signal Transmission* section....20
- Added *Analog Output* section, deleted *Fail-Safe Output* section....21
- Changed *Device Functional Modes* section....21

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- Changed *Application Information* section 22
- Changed *Typical Application* section 22
- Changed *Best Design Practices* section 25
- Changed *Power Supply Recommendations* section 25
- Changed the *Recommended Layout of the AMC1301* figure 26
- Added a link to the *Isolated Voltage-Measurement Circuit* in the *Related Documentation* section 27

Changes from Revision E (March 2018) to Revision F (April 2020) **Page**

- Changed safety-related certifications details as per ISO standard 1
- Changed *IEC 60950-1 and IEC60065* to *IEC 62368-1* 1
- Changed *VDE V 0884-10* to *VDE V 0884-11* in *Description* section 1
- Changed T_A parameter from *specified* to *operating* in *Device Comparison Table* 4
- Changed CLR and CPG values from 9 mm to 8.5 mm 7
- Changed *Insulation Specifications* table per ISO standard 7
- Changed *Safety-Related Certifications* table per ISO standard 8
- Changed *Safety Limiting Values* description as per ISO standard 8
- Changed *Rise and Fall Time Test Waveforms* figure 10
- Changed *Delay Time Test Waveforms* figure 10
- Changed *Functional Block Diagram* figure 19

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Device Comparison Table

PARAMETER	AMC1301S	AMC1301
Operating ambient temperature, T_A	–55°C to +125°C	–40°C to +125°C
Input offset drift, TCV_{OS}	±4 µV/°C (max)	±3 µV/°C (max)
Gain error drift, TCE_G	±60 ppm/°C (max)	±50 ppm/°C (max)

5 Pin Configuration and Functions

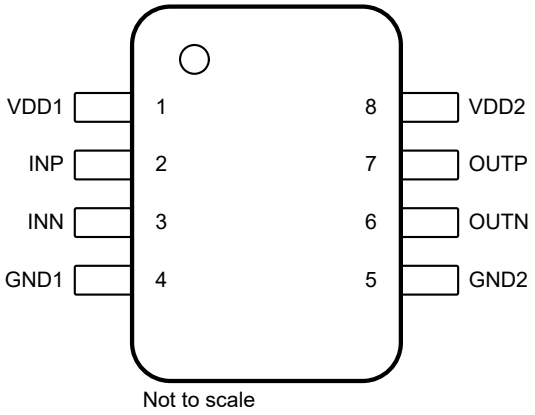


Figure 5-1. DWV Package, 8-Pin SOIC (Top View)

Table 5-1. Pin Functions

PIN		TYPE	DESCRIPTION
NO.	NAME		
1	VDD1	High-side power	High-side power supply.(1)
2	INP	Analog input	Noninverting analog input. Either INP or INN must have a DC current path to GND1 to define the common-mode input voltage.(2)
3	INN	Analog input	Inverting analog input. Either INP or INN must have a DC current path to GND1 to define the common-mode input voltage.(2)
4	GND1	High-side ground	High-side analog ground.
5	GND2	Low-side ground	Low-side analog ground.
6	OUTN	Analog output	Inverting analog output.
7	OUTP	Analog output	Noninverting analog output.
8	VDD2	Low-side power	Low-side power supply.(1)

(1) See the *Power Supply Recommendations* section for power-supply decoupling recommendations.
(2) See the *Layout* section for details.

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6 Specifications

6.1 Absolute Maximum Ratings

see(1)

		MIN	MAX	UNIT
Power-supply voltage	High-side VDD1 to GND1	–0.3	7	V
	Low-side VDD2 to GND2	–0.3	7	
Analog input voltage	INP, INN	GND1 – 6	VDD1 + 0.5	V
Input current	Continuous, any pin except power-supply pins	–10	10	mA
Temperature	Junction, T_J		150	°C
	Storage, T_{stg}	–65	150	

(1) Operation outside the *Absolute Maximum Ratings* may cause permanent device damage. *Absolute Maximum Ratings* do not imply functional operation of the device at these or any other conditions beyond those listed under *Recommended Operating Conditions*. If used outside the Recommended Operating Conditions but within the Absolute Maximum Ratings, the device may not be fully functional, and this may affect device reliability, functionality, performance, and shorten the device lifetime

6.2 ESD Ratings

			VALUE	UNIT
$V_{(ESD)}$	Electrostatic discharge	Human-body model (HBM), per ANSI/ESDA/JEDEC JS-001(1)	±2000	V
		Charged-device model (CDM), per ANSI/ESDA/JEDEC JS-002((2))	±1000	

(1) JEDEC document JEP155 states that 500-V HBM allows safe manufacturing with a standard ESD control process.
(2) JEDEC document JEP157 states that 250-V CDM allows safe manufacturing with a standard ESD control process.

6.3 Recommended Operating Conditions

over operating ambient temperature range (unless otherwise noted)

			MIN	NOM	MAX	UNIT
POWER SUPPLY						
	High-side power supply	VDD1 to GND1	3	5	5.5	V
	Low-side power supply	VDD2 to GND2	3	3.3	5.5	V
ANALOG INPUT						
$V_{Clipping}$	Differential input voltage before clipping output	$V_{IN} = V_{INP} – V_{INN}$		±302.7		mV
V_{FSR}	Specified linear differential full-scale voltage	$V_{IN} = V_{INP} – V_{INN}$	–250		250	mV
	Absolute common-mode input voltage(1)	$(V_{INP} + V_{INN}) / 2$ to GND1	–2		VDD1	V
V_{CM}	Operating common-mode input voltage	$(V_{INP} + V_{INN}) / 2$ to GND1	–0.16		VDD1 – 2.1	V
TEMPERATURE RANGE						
T_A	Specified ambient temperature	AMC1301	–40		125	°C
		AMC1301S	–55		125	

(1) Steady-state voltage supported by the device in case of a system failure. See specified common-mode input voltage V_{CM} for normal operation. Observe analog input voltage range as specified in *Absolute Maximum Ratings* table.

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6.4 Thermal Information

THERMAL METRIC(1)		DWV (SOIC) 8 PINS	UNIT
$R_{\theta JA}$	Junction-to-ambient thermal resistance	110.1	°C/W
$R_{\theta JC(top)}$	Junction-to-case (top) thermal resistance	51.7	°C/W
$R_{\theta JB}$	Junction-to-board thermal resistance	66.4	°C/W
Ψ_{JT}	Junction-to-top characterization parameter	16.0	°C/W
Ψ_{JB}	Junction-to-board characterization parameter	64.5	°C/W
$R_{\theta JC(bot)}$	Junction-to-case (bottom) thermal resistance	N/A	°C/W

(1) For more information about traditional and new thermal metrics, see the Semiconductor and IC Package Thermal Metrics application report.

6.5 Power Ratings

PARAMETER		TEST CONDITIONS	VALUE	UNIT
P_D	Maximum power dissipation (both sides)	VDD1 = VDD2 = 5.5 V	99	mW
P_{D1}	Maximum power dissipation (high-side)	VDD1 = 3.6 V	31	mW
		VDD1 = 5.5 V	54	
P_{D2}	Maximum power dissipation (low-side)	VDD2 = 3.6 V	26	mW
		VDD2 = 5.5 V	45	

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6.6 Insulation Specifications

over operating ambient temperature range (unless otherwise noted)

PARAMETER		TEST CONDITIONS	VALUE	UNIT
GENERAL				
CLR	External clearance(1)	Shortest pin-to-pin distance through air	≥ 8.5	mm
CPG	External creepage(1)	Shortest pin-to-pin distance across the package surface	≥ 8.5	mm
DTI	Distance through insulation	Minimum internal gap (internal clearance) of the double insulation	≥ 0.021	mm
CTI	Comparative tracking index	DIN EN 60112 (VDE 0303-11); IEC 60112	≥ 600	V
	Material group	According to IEC 60664-1	I	
	Overvoltage category per IEC 60664-1	Rated mains voltage ≤ 600 V_{RMS}	I-IV	
		Rated mains voltage ≤ 1000 V_{RMS}	I-III	
DIN EN IEC 60747-17 (VDE 0884-17)(2)				
V_{IORM}	Maximum repetitive peak isolation voltage	At AC voltage	1500	V_{PK}
V_{IOWM}	Maximum-rated isolation working voltage	At AC voltage (sine wave)	1000	V_{RMS}
		At DC voltage	1500	V_{DC}
V_{IOTM}	Maximum transient isolation voltage	$V_{TEST} = V_{IOTM}$, t = 60 s (qualification test), $V_{TEST} = 1.2 \times V_{IOTM}$, t = 1 s (100% production test)	7000	V_{PK}
V_{IMP}	Maximum impulse voltage(2)	Tested in air, 1.2/50-µs waveform per IEC 62368-1	7700	V_{PK}
V_{IOSM}	Maximum surge isolation voltage(3)	Tested in oil (qualification test), 1.2/50-µs waveform per IEC 62368-1	10000	V_{PK}
q_{pd}	Apparent charge((5))	Method a, after input/output safety test subgroups 2 and 3, $V_{pd(ini)} = V_{IOTM}$, t_{ini} = 60 s, $V_{pd(m)} = 1.2 \times V_{IORM}$, t_m = 10 s	≤ 5	pC
		Method a, after environmental tests subgroup 1, $V_{pd(ini)} = V_{IOTM}$, t_{ini} = 60 s, $V_{pd(m)} = 1.6 \times V_{IORM}$, t_m = 10 s	≤ 5	
		Method b1, at preconditioning (type test) and routine test, $V_{pd(ini)} = 1.2 \times V_{IOTM}$, t_{ini} = 1 s, $V_{pd(m)} = 1.875 \times V_{IORM}$, t_m = 1 s	≤ 5	
		Method b2, at routine test (100% production)((7)), $V_{pd(ini)} = V_{pd(m)} = 1.2 \times V_{IOTM}$, $t_{ini} = t_m$ = 1 s	≤ 5	
C_{IO}	Barrier capacitance, input to output(5)	V_{IO} = 0.5 V_{PP} at 1 MHz	~1.2	pF
R_{IO}	Insulation resistance, input to output(5)	V_{IO} = 500 V at T_A = 25°C	> 10^{12}	Ω
		V_{IO} = 500 V at 100°C ≤ T_A ≤ 125°C	> 10^{11}	
		V_{IO} = 500 V at T_S = 150°C	> 10^9	
	Pollution degree		2	
	Climatic category	AMC1301	40/125/21	
		AMC1301S	55/125/21	
UL1577				
V_{ISO}	Withstand isolation voltage	$V_{TEST} = V_{ISO}$, t = 60 s (qualification test), $V_{TEST} = 1.2 \times V_{ISO}$, t = 1 s (100% production test)	5000	V_{RMS}

(1) Apply creepage and clearance requirements according to the specific equipment isolation standards of an application. Care must be taken to maintain the creepage and clearance distance of a board design to ensure that the mounting pads of the isolator on the printed circuit board (PCB) do not reduce this distance. Creepage and clearance on a PCB become equal in certain cases. Techniques such as inserting grooves, ribs, or both on a PCB are used to help increase these specifications.
(2) Testing is carried out in air to determine the surge immunity of the package.
(3) Testing is carried in oil to determine the intrinsic surge immunity of the isolation barrier.
(4) Apparent charge is electrical discharge caused by a partial discharge (pd).
(5) All pins on each side of the barrier are tied together, creating a two-pin device.
(6) Either method b1 or b2 is used in production.

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6.7 Safety-Related Certifications

VDE	UL
DIN EN IEC 60747-17 (VDE 0884-17), EN IEC 60747-17, DIN EN IEC 62368-1 (VDE 0868-1), EN IEC 62368-1, IEC 62368-1 Clause : 5.4.3 ; 5.4.4.4 ; 5.4.9	Recognized under 1577 component recognition program
Reinforced insulation	Single protection
Certificate number: 40040142	File number: E181974

6.8 Safety Limiting Values

Safety limiting(1) intends to minimize potential damage to the isolation barrier upon failure of input or output circuitry. A failure of the I/O can allow low resistance to ground or the supply and, without current limiting, dissipate sufficient power to over-heat the die and damage the isolation barrier potentially leading to secondary system failures.

PARAMETER		TEST CONDITIONS	MIN	TYP	MAX	UNIT
I_S	Safety input, output, or supply current	$R_{\theta JA}$ = 110.1°C/W, VDDx = 5.5 V, T_J = 150°C, T_A = 25°C			206	mA
I_S	Safety input, output, or supply current	$R_{\theta JA}$ = 110.1°C/W, VDDx = 3.6 V, T_J = 150°C, T_A = 25°C			315	mA
P_S	Safety input, output, or total power	$R_{\theta JA}$ = 110.1°C/W, T_J = 150°C, T_A = 25°C			1135	mW
T_S	Maximum safety temperature				150	°C

(1) The maximum safety temperature, T_S, has the same value as the maximum junction temperature, T_J, specified for the device. The I_S and P_S parameters represent the safety current and safety power, respectively. Do not exceed the maximum limits of I_S and P_S. These limits vary with the ambient temperature, T_A.
The junction-to-air thermal resistance, $R_{\theta JA}$, in the Thermal Information table is that of a device installed on a high-K test board for leaded surface-mount packages. Use these equations to calculate the value for each parameter:
$T_J = T_A + R_{\theta JA} \times P$, where P is the power dissipated in the device.
$T_{J(max)} = T_S = T_A + R_{\theta JA} \times P_S$, where $T_{J(max)}$ is the maximum junction temperature.
$P_S = I_S \times VDD_{max}$, where VDD_{max} is the maximum supply voltage for high-side and low-side.

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6.9 Electrical Characteristics

minimum and maximum specifications apply from T_A = –40°C to +125°C (for AMC1301S: T_A = –55°C to +125°C), VDD1 = 3.0 V to 5.5 V, VDD2 = 3.0 V to 5.5 V, INP = –250 mV to +250 mV, and INN = GND1; typical specifications are at T_A = 25°C, VDD1 = 5 V, and VDD2 = 3.3 V (unless otherwise noted)

PARAMETER		TEST CONDITIONS	MIN	TYP	MAX	UNIT
ANALOG INPUT						
V_{CMov}	Common-mode overvoltage detection level	(V_{INP} + V_{INN}) / 2 to GND1	VDD1 – 2			V
	Hysteresis of common-mode overvoltage detection level			60		mV
V_{OS}	Input offset voltage(1)	Initial, at T_A = 25°C, INP = INN = GND1	–0.2	±0.05	0.2	mV
TCV_{OS}	Input offset drift(1) (4)	AMC1301	–3	±1	3	µV/°C
		AMC1301S	–4	±1	4	
CMRR	Common-mode rejection ratio	f_{IN} = 0 Hz, $V_{CM\ min} \le V_{CM} \le V_{CM\ max}$		–93		dB
		f_{IN} = 10 kHz, $V_{CM\ min} \le V_{CM} \le V_{CM\ max}$		–93		
R_{IN}	Single-ended input resistance	INN = GND1		18		kΩ
R_{IND}	Differential input resistance			22		kΩ
I_{IB}	Input bias current	INP = INN = GND1; I_{IB} = (I_{IBP} + I_{IBN}) / 2	–41	–30	–24	µA
TCI_{IB}	Input bias current drift			1		nA/°C
C_{IND}	Differential input capacitance			1		pF
ANALOG OUTPUT						
	Nominal gain			8.2		V/V
E_G	Gain error(1)	at T_A = 25°C	–0.3%	±0.05%	0.3%	
TCE_G	Gain drift(1) (5)	AMC1301	–50	±15	50	ppm/°C
		AMC1301S	–60	±15	60	
	Nonlinearity(1)		–0.03%	±0.01%	0.03%	
	Nonlinearity drift			±1		ppm/°C
THD	Total harmonic distortion(3)	f_{IN} = 10 kHz		–87		dB
	Output noise	INP = INN = GND1, f_{IN} = 0 Hz, BW = 100 kHz brickwall filter		220		$µV_{RMS}$
SNR	Signal-to-noise ratio	f_{IN} = 1 kHz, BW = 10 kHz	80	84		dB
		f_{IN} = 10 kHz, BW = 100 kHz		71		
PSRR	Power-supply rejection ratio(2)	PSRR vs VDD1, at DC		–94		dB
		PSRR vs VDD1, 100-mV and 10-kHz ripple		–90		
		PSRR vs VDD2, at DC		–100		
		PSRR vs VDD2, 100-mV and 10-kHz ripple		–94		
V_{CMout}	Common-mode output voltage		1.39	1.44	1.49	V
$V_{CLIPout}$	Clipping differential output voltage	V_{OUT} = (V_{OUTP} – V_{OUTN}); $\lvert V_{IN}\rvert$ = $\lvert V_{INP} - V_{INN}\rvert$ > $\lvert V_{Clipping}\rvert$	–2.52	±2.49	2.52	V
$V_{Failsafe}$	Failsafe differential output voltage	$V_{CM} \ge V_{CMov}$, or VDD1 missing		–2.563	–2.545	V
BW	Output bandwidth		190	210		kHz
R_{OUT}	Output resistance	On OUTP or OUTN		< 0.2		Ω
	Output short-circuit current	On OUTP or OUTN, sourcing or sinking, INN = INP = GND1, outputs shorted to either GND2 or VDD2		13		mA
CMTI	Common-mode transient immunity	|GND1 – GND2| = 1 kV	15			kV/µs

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6.9 Electrical Characteristics (continued)

minimum and maximum specifications apply from T_A = –40°C to +125°C (for AMC1301S: T_A = –55°C to +125°C), VDD1 = 3.0 V to 5.5 V, VDD2 = 3.0 V to 5.5 V, INP = –250 mV to +250 mV, and INN = GND1; typical specifications are at T_A = 25°C, VDD1 = 5 V, and VDD2 = 3.3 V (unless otherwise noted)

PARAMETER		TEST CONDITIONS	MIN	TYP	MAX	UNIT
POWER SUPPLY						
IDD1	High-side supply current	3.0 V ≤ VDD1 ≤ 3.6 V		6.3	8.5	mA
		4.5 V ≤ VDD1 ≤ 5.5 V		7.2	9.8	
IDD2	Low-side supply current	3.0 V ≤ VDD2 ≤ 3.6 V		5.3	7.2	mA
		4.5 V ≤ VDD2 ≤ 5.5 V		5.9	8.1	

(1) The typical value includes one standard deviation (*sigma*) at nominal operating conditions.
(2) This parameter is input referred.
(3) THD is the ratio of the rms sum of the amplitues of first five higher harmonics to the amplitude of the fundamental.
(4) Offset error temperature drift is calculated using the box method, as described by the following equation: $TCV_{OS} = (V_{OS,MAX} - V_{OS,MIN}) / TempRange$ where $V_{OS,MAX}$ and $V_{OS,MIN}$ refer to the maximum and minimum V_{OS} values measured within the temperature range (–40 to 125°C).
(5) Gain error temperature drift is calculated using the box method, as described by the following equation: $TCE_G\ (ppm) = ((E_{G,MAX} - E_{G,MIN}) / TempRange) \times 10^4$ where $E_{G,MAX}$ and $E_{G,MIN}$ refer to the maximum and minimum E_G values (in %) measured within the temperature range (–40 to 125°C).

6.10 Switching Characteristics

over operating ambient temperature range (unless otherwise noted)

PARAMETER		TEST CONDITIONS	MIN	TYP	MAX	UNIT
t_r	Output signal rise time			2.0		µs
t_f	Output signal fall time			2.0		µs
	V_{INx} to V_{OUTx} signal delay (50% - 10%)	Unfiltered output		0.7	2.0	µs
	V_{INx} to V_{OUTx} signal delay (50% - 50%)	Unfiltered output		1.6	2.6	µs
	V_{INx} to V_{OUTx} signal delay (50% - 90%)	Unfiltered output		2.5	3	µs

6.11 Timing Diagram

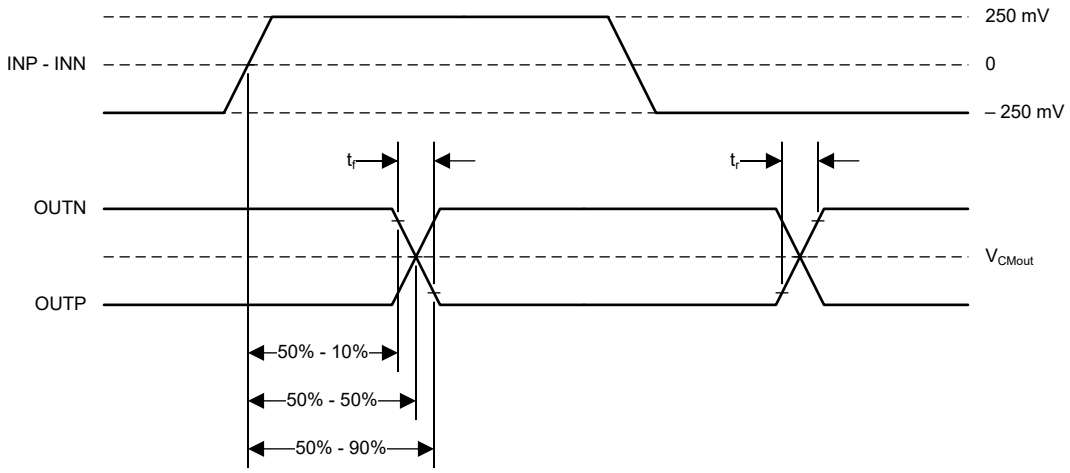


Figure 6-1. Rise, Fall, and Delay Time Definition

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6.12 Insulation Characteristics Curves

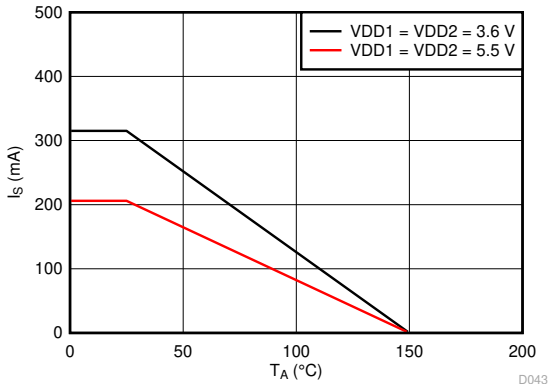


Figure 6-2. Thermal Derating Curve for Safety-Limiting Current per VDE

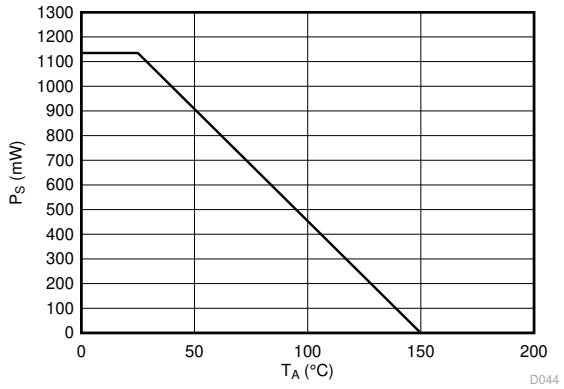
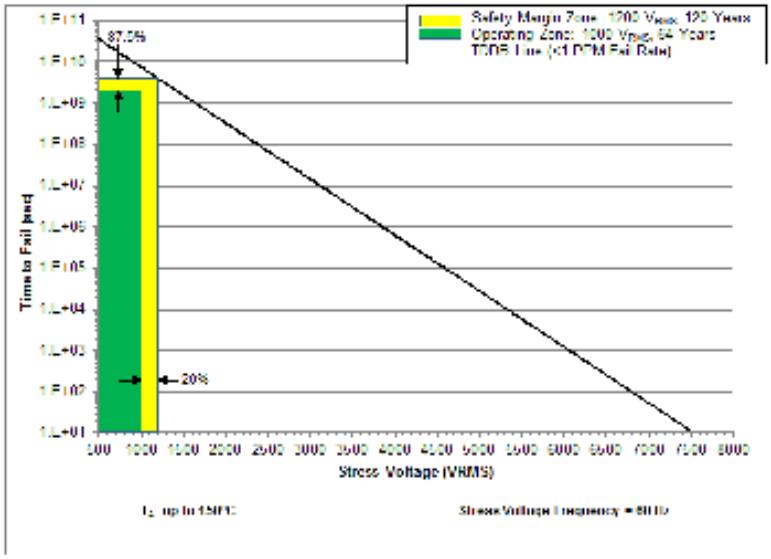


Figure 6-3. Thermal Derating Curve for Safety-Limiting Power per VDE



T_A up to 150°C, stress voltage frequency = 60 Hz

Figure 6-4. Reinforced Isolation Capacitor Lifetime Projection

6.13 Typical Characteristics

at VDD1 = 5 V, VDD2 = 3.3 V, INP = –250 mV to 250 mV, INN = 0 V, and f_{IN} = 10 kHz (unless otherwise noted)

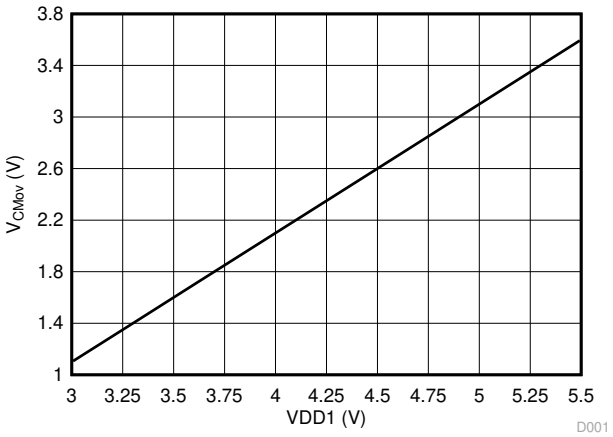
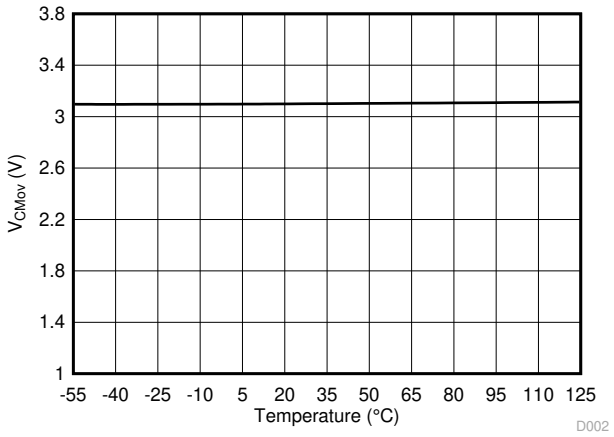
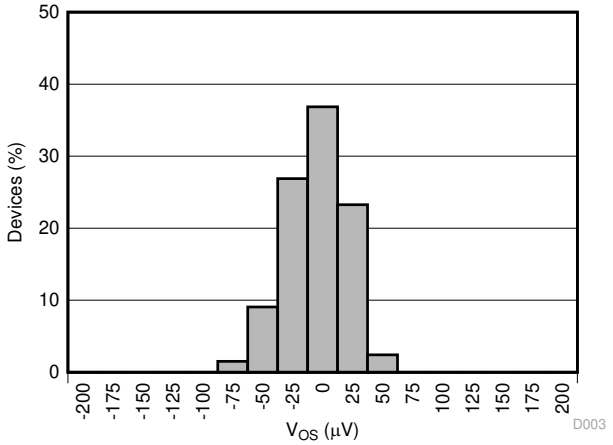


Figure 6-5. Common-Mode Overvoltage Detection Level vs High-Side Supply Voltage



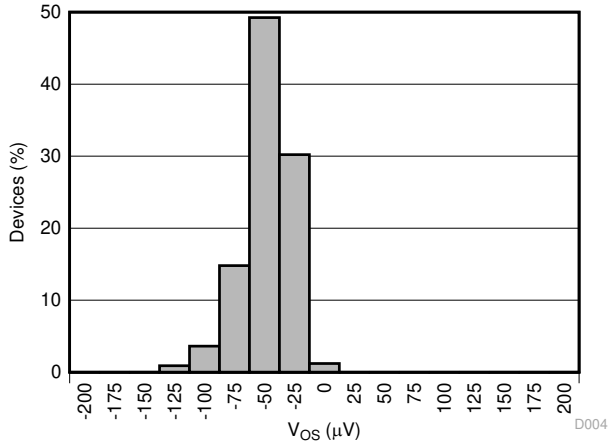
–55°C ≤ T_A < 40°C valid for the AMC1301S only

Figure 6-6. Common-Mode Overvoltage Detection Level vs Temperature



VDD1 = 3.3 V

Figure 6-7. Input Offset Voltage Histogram



VDD1 = 5 V

Figure 6-8. Input Offset Voltage Histogram

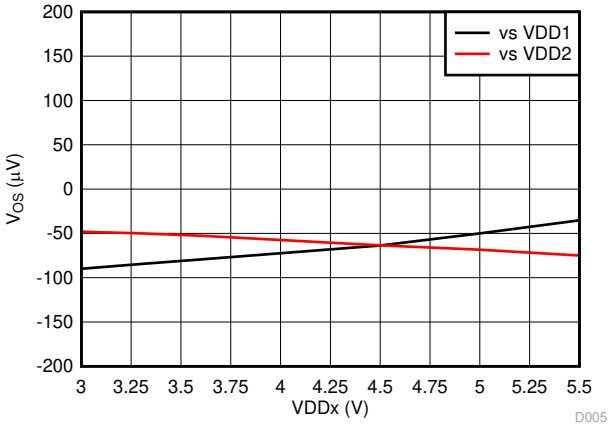
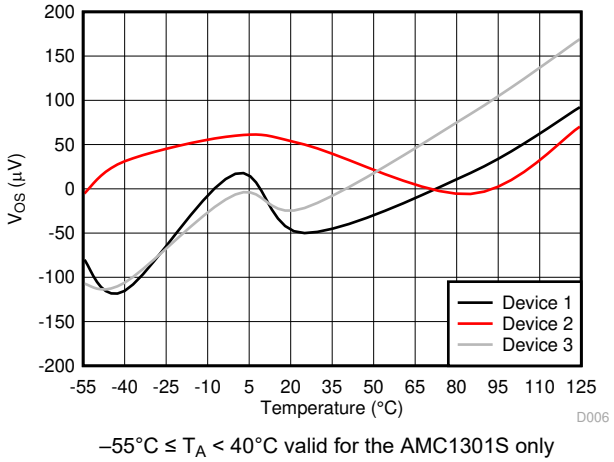


Figure 6-9. Input Offset Voltage vs Supply Voltage



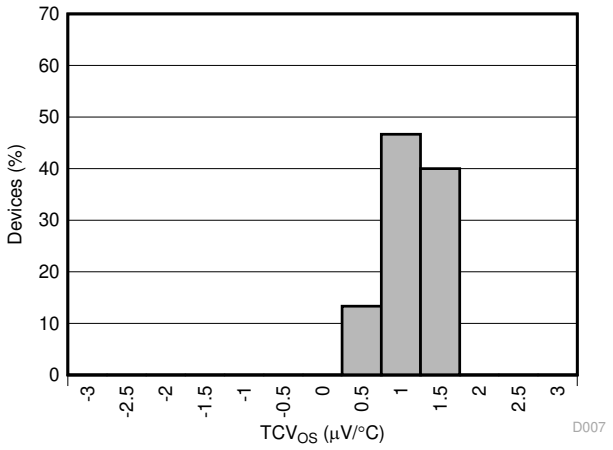
–55°C ≤ T_A < 40°C valid for the AMC1301S only

Figure 6-10. Input Offset Voltage vs Temperature

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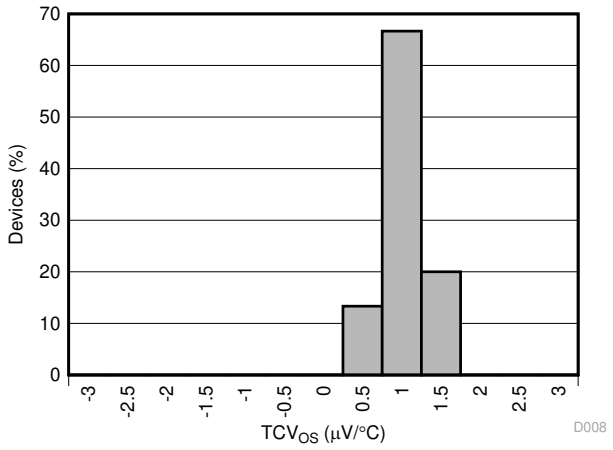
6.13 Typical Characteristics (continued)

at VDD1 = 5 V, VDD2 = 3.3 V, INP = –250 mV to 250 mV, INN = 0 V, and f_{IN} = 10 kHz (unless otherwise noted)



VDD1 = 3.3 V

Figure 6-11. Input Offset Drift Histogram



VDD1 = 5 V

Figure 6-12. Input Offset Drift Histogram

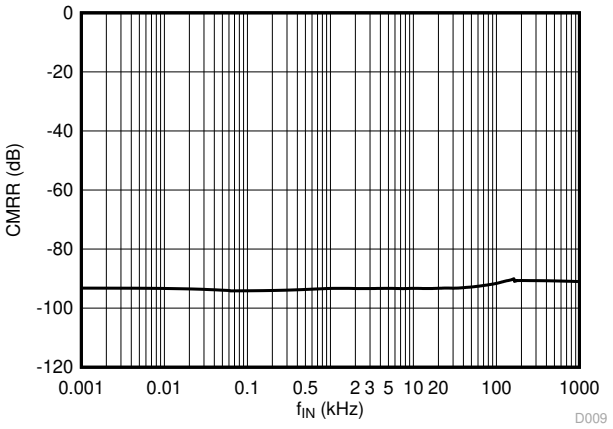
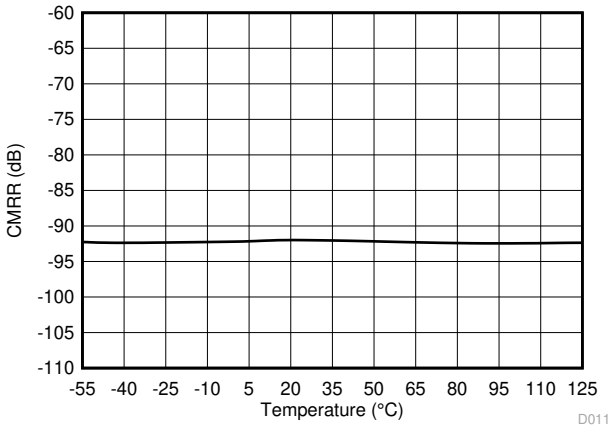


Figure 6-13. Common-Mode Rejection Ratio vs Input Frequency



–55°C ≤ T_A < 40°C valid for the AMC1301S only

Figure 6-14. Common-Mode Rejection Ratio vs Temperature

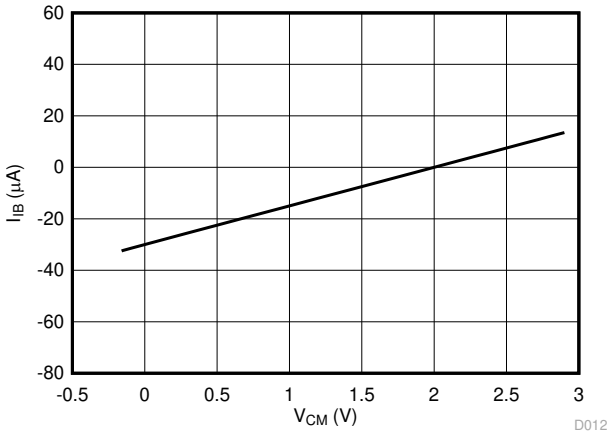


Figure 6-15. Input Bias Current vs Common-Mode Input Voltage

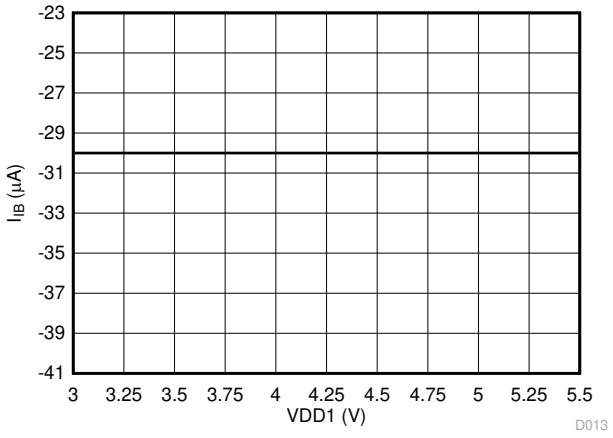
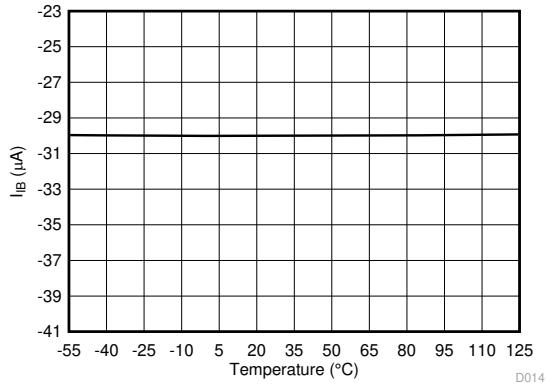


Figure 6-16. Input Bias Current vs High-Side Supply Voltage

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6.13 Typical Characteristics (continued)

at VDD1 = 5 V, VDD2 = 3.3 V, INP = –250 mV to 250 mV, INN = 0 V, and f_{IN} = 10 kHz (unless otherwise noted)



–55°C ≤ T_A < 40°C valid for the AMC1301S only

Figure 6-17. Input Bias Current vs Temperature

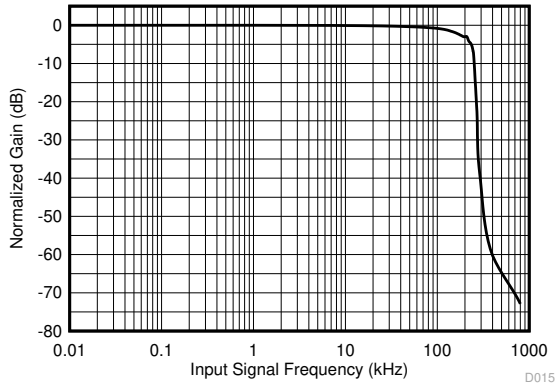
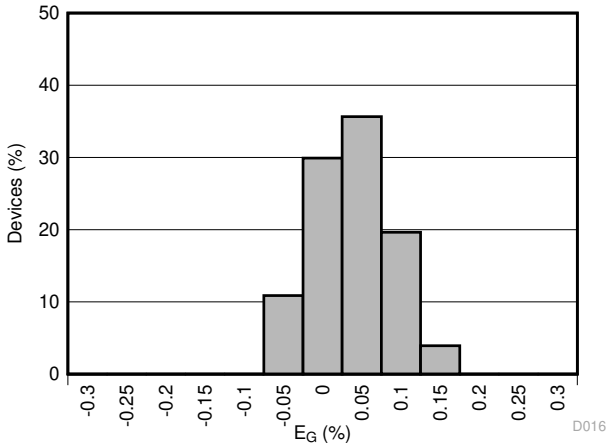
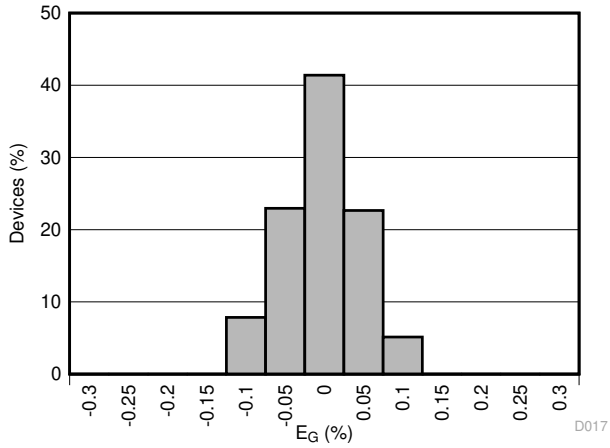


Figure 6-18. Normalized Gain vs Input Frequency



VDD1 = 3.3 V

Figure 6-19. Gain Error Histogram



VDD1 = 5 V

Figure 6-20. Gain Error Histogram

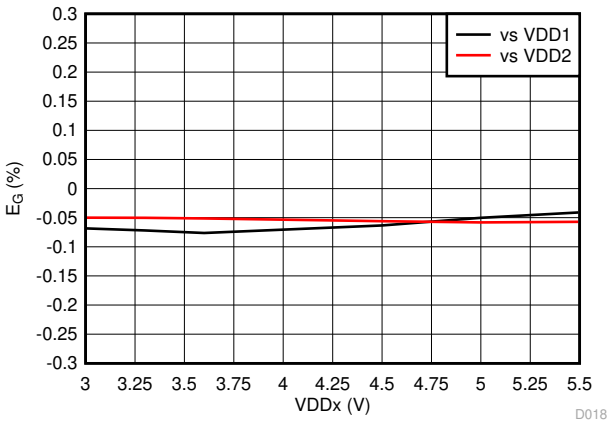
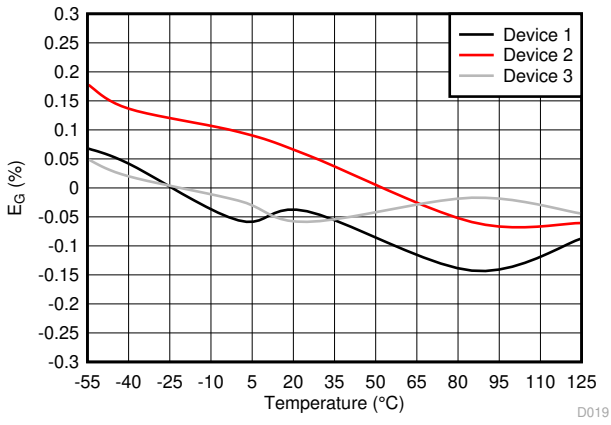


Figure 6-21. Gain Error vs Supply Voltage



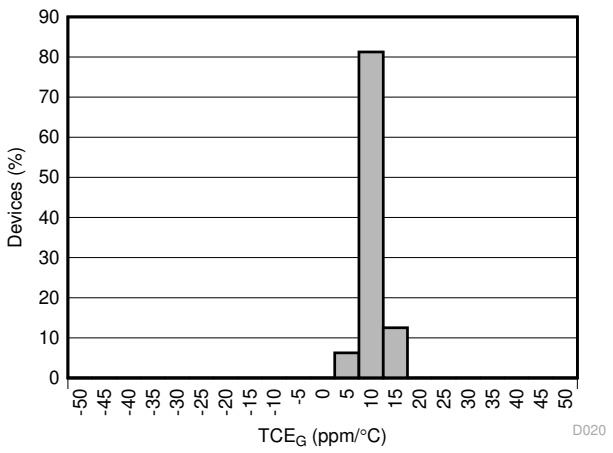
–55°C ≤ T_A < 40°C valid for the AMC1301S only

Figure 6-22. Gain Error vs Temperature

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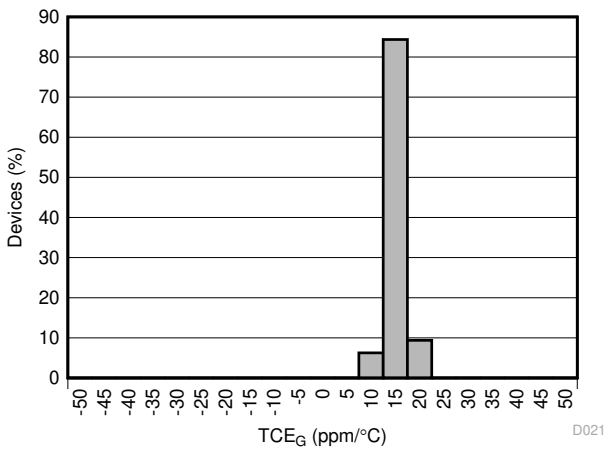
6.13 Typical Characteristics (continued)

at VDD1 = 5 V, VDD2 = 3.3 V, INP = –250 mV to 250 mV, INN = 0 V, and f_{IN} = 10 kHz (unless otherwise noted)



VDD1 = 3.3 V

Figure 6-23. Gain Error Drift Histogram



VDD1 = 5 V

Figure 6-24. Gain Error Drift Histogram

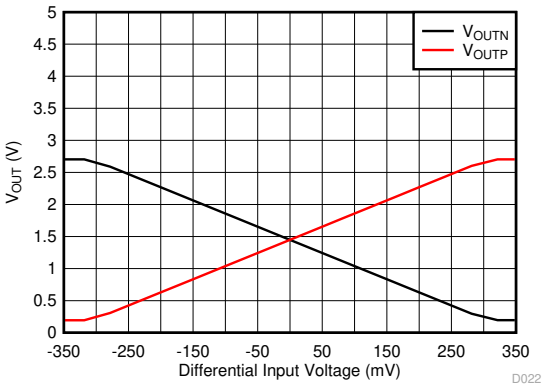


Figure 6-25. Output Voltage vs Input Voltage

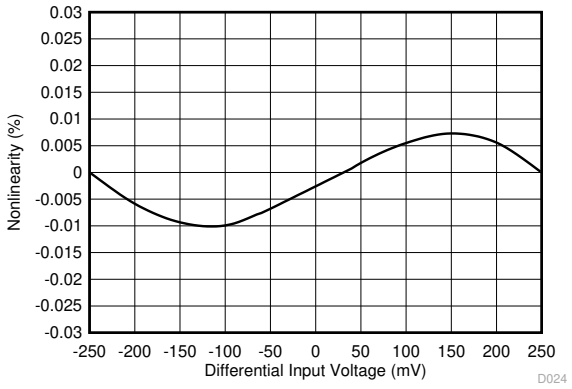


Figure 6-26. Nonlinearity vs Input Voltage

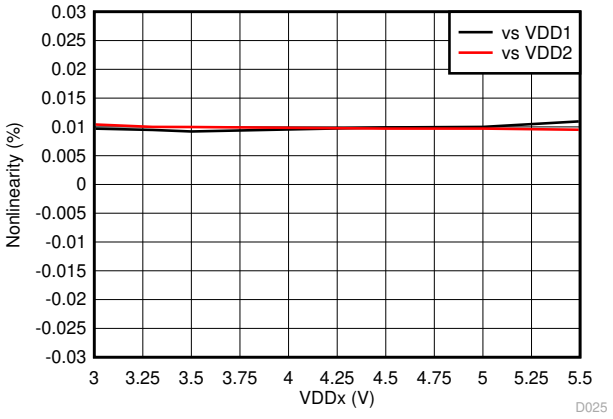
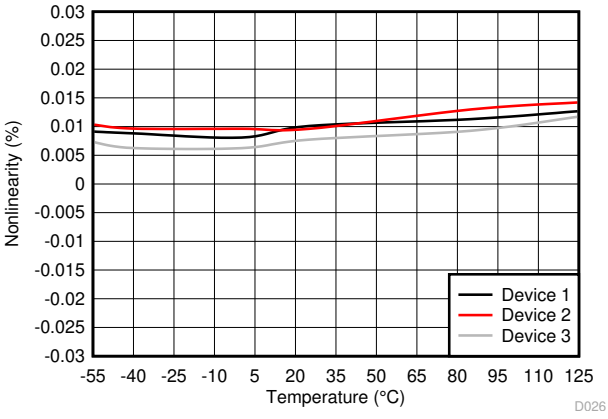


Figure 6-27. Nonlinearity vs Supply Voltage



–55°C ≤ T_A < 40°C valid for the AMC1301S only

Figure 6-28. Nonlinearity vs Temperature

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6.13 Typical Characteristics (continued)

at VDD1 = 5 V, VDD2 = 3.3 V, INP = –250 mV to 250 mV, INN = 0 V, and f_{IN} = 10 kHz (unless otherwise noted)

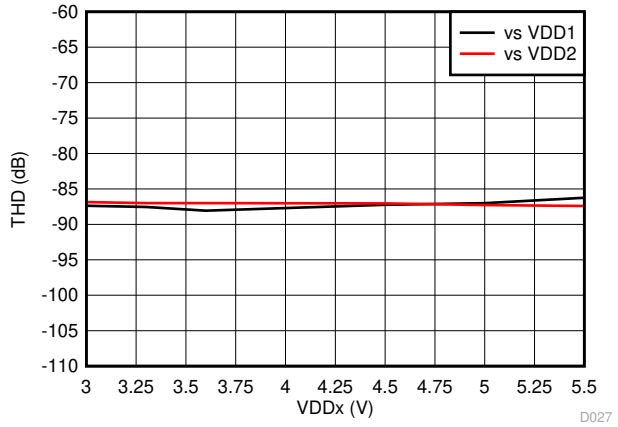
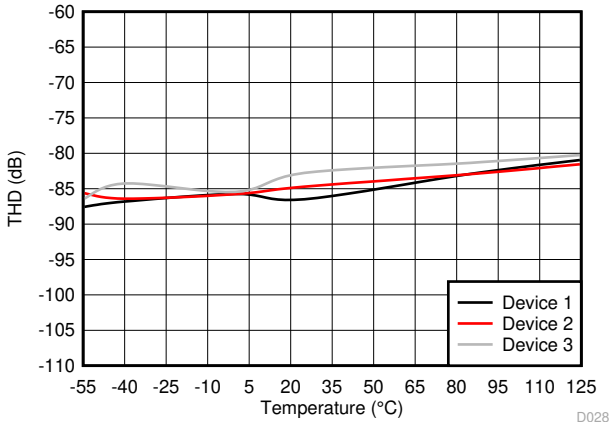


Figure 6-29. Total Harmonic Distortion vs Supply Voltage



–55°C ≤ T_A < 40°C valid for the AMC1301S only

Figure 6-30. Total Harmonic Distortion vs Temperature

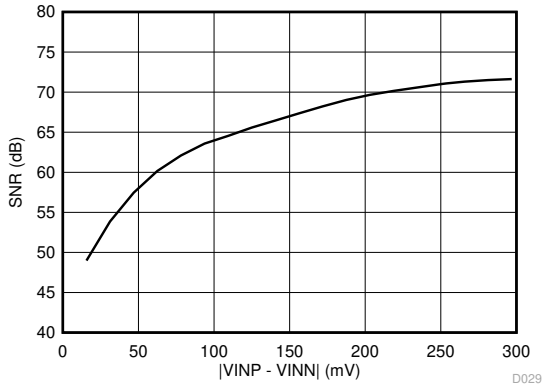


Figure 6-31. Signal-to-Noise Ratio vs Input Voltage

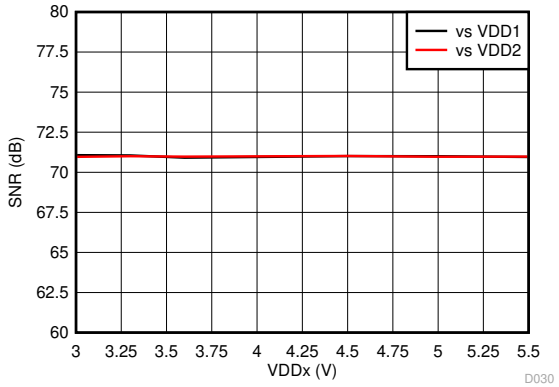
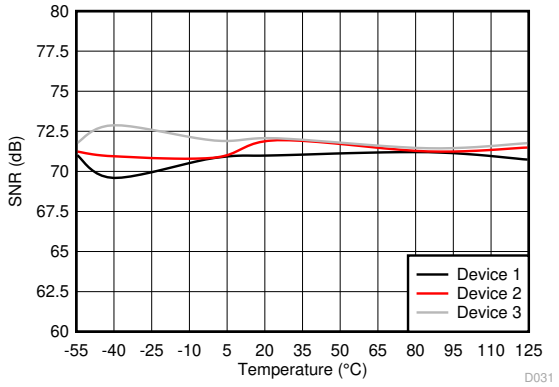


Figure 6-32. Signal-to-Noise Ratio vs Supply Voltage



–55°C ≤ T_A < 40°C valid for the AMC1301S only

Figure 6-33. Signal-to-Noise Ratio vs Temperature

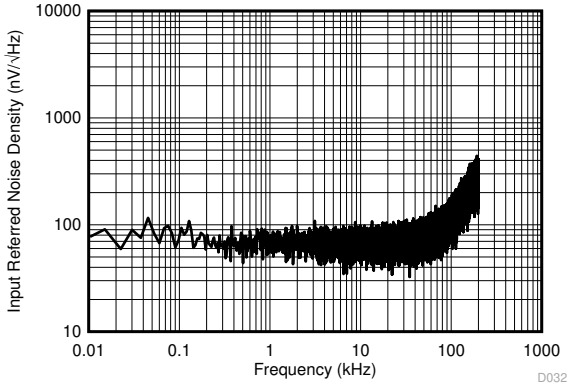
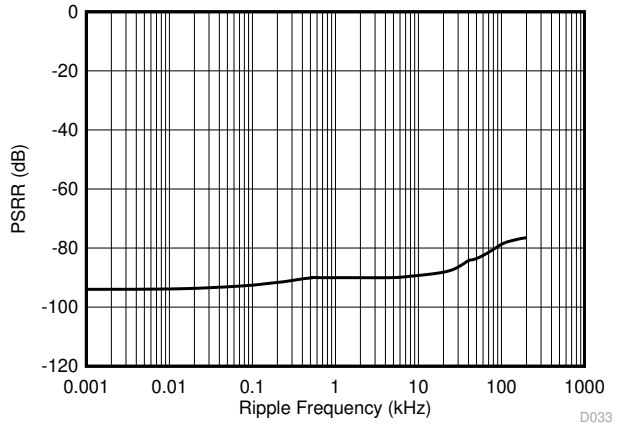


Figure 6-34. Input-Referred Noise Density vs Frequency

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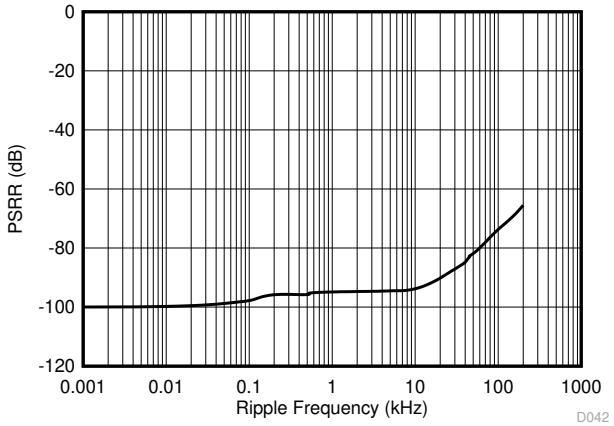
6.13 Typical Characteristics (continued)

at VDD1 = 5 V, VDD2 = 3.3 V, INP = –250 mV to 250 mV, INN = 0 V, and f_{IN} = 10 kHz (unless otherwise noted)



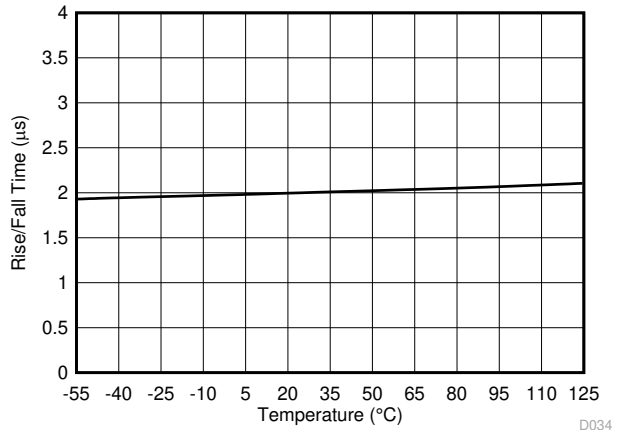
vs VDD1

Figure 6-35. Power-Supply Rejection Ratio vs Ripple Frequency



vs VDD2

Figure 6-36. Power-Supply Rejection Ratio vs Ripple Frequency



–55°C ≤ T_A < 40°C valid for the AMC1301S only

Figure 6-37. Output Rise and Fall Time vs Temperature

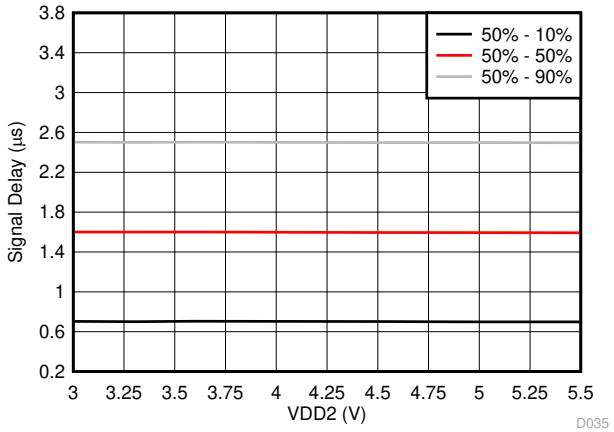
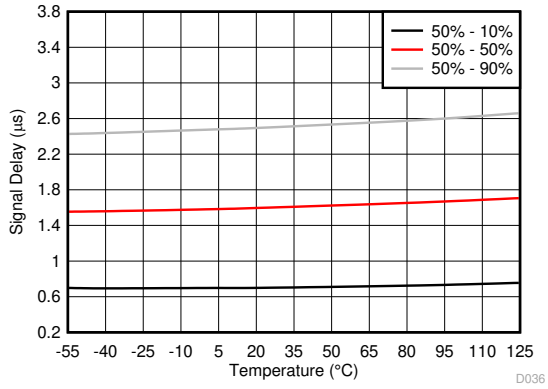


Figure 6-38. V_{IN} to V_{OUT} Signal Delay vs Low-Side Supply Voltage



–55°C ≤ T_A < 40°C valid for the AMC1301S only

Figure 6-39. V_{IN} to V_{OUT} Signal Delay vs Temperature

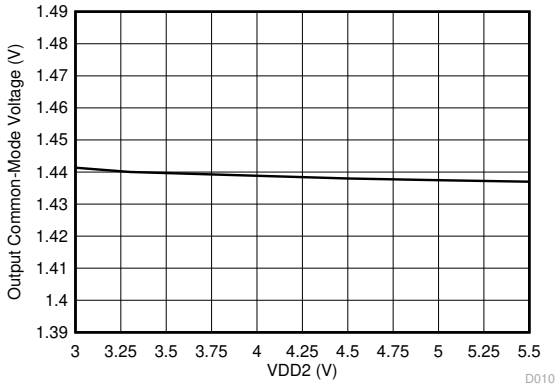
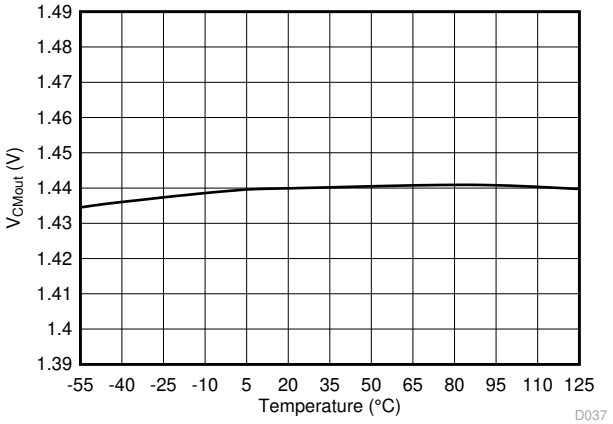


Figure 6-40. Output Common-Mode Voltage vs Low-Side Supply Voltage

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6.13 Typical Characteristics (continued)

at VDD1 = 5 V, VDD2 = 3.3 V, INP = –250 mV to 250 mV, INN = 0 V, and f_{IN} = 10 kHz (unless otherwise noted)



–55°C ≤ T_A < 40°C valid for the AMC1301S only

Figure 6-41. Output Common-Mode Voltage vs Temperature

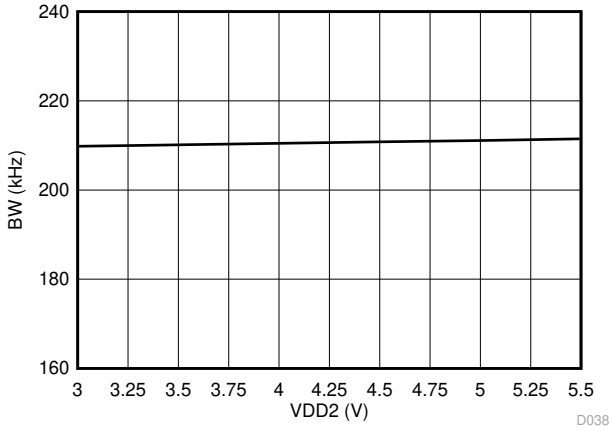
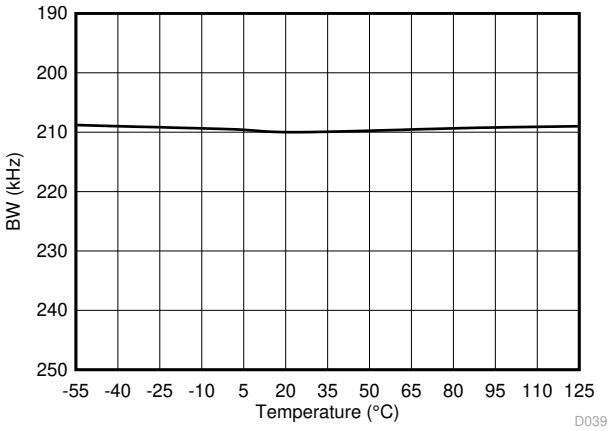


Figure 6-42. Output Bandwidth vs Low-Side Supply Voltage



–55°C ≤ T_A < 40°C valid for the AMC1301S only

Figure 6-43. Output Bandwidth vs Temperature

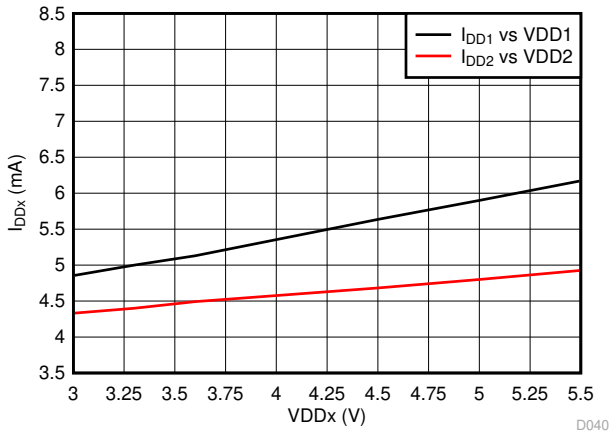
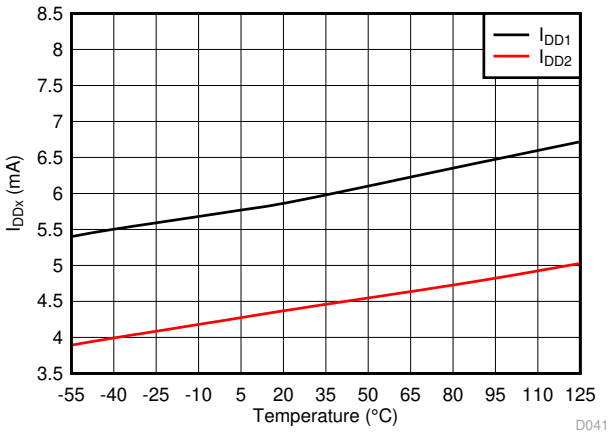


Figure 6-44. Supply Current vs Supply Voltage



–55°C ≤ T_A < 40°C valid for the AMC1301S only

Figure 6-45. Supply Current vs Temperature

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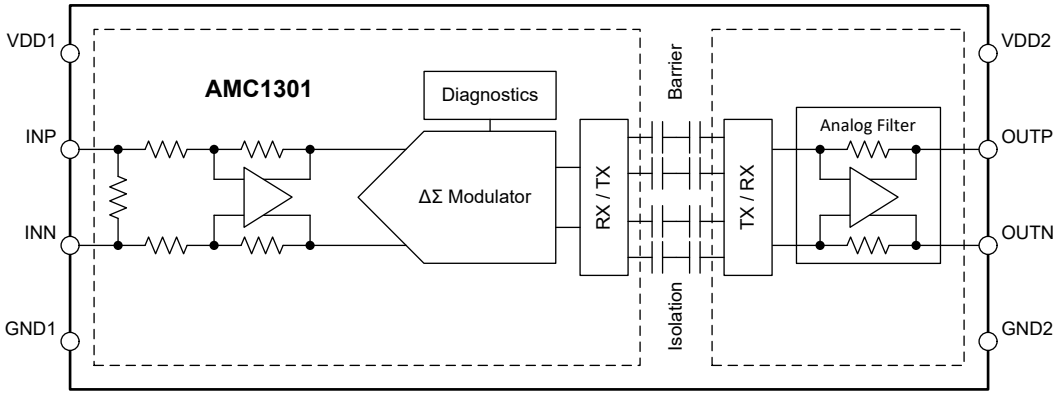
7 Detailed Description

7.1 Overview

The AMC1301 is a fully differential, precision, isolated amplifier. The input stage of the device consists of a fully differential amplifier that drives a second-order, delta-sigma (ΔΣ) modulator. The modulator converts the analog input signal into a digital bitstream that is transferred across the isolation barrier that separates the high-side from the low-side. On the low-side, the received bitstream is processed by a fourth-order analog filter that outputs a differential signal at the OUTP and OUTN pins that is proportional to the input signal.

The SiO_2-based, capacitive isolation barrier supports a high level of magnetic field immunity, as described in the *ISO72x Digital Isolator Magnetic-Field Immunity* application note. The digital modulation used in the AMC1301 to transmit data across the isolation barrier, and the isolation barrier characteristics, result in high reliability and common-mode transient immunity.

7.2 Functional Block Diagram



7.3 Feature Description

7.3.1 Analog Input

The differential amplifier input stage of the AMC1301 feeds a second-order, switched-capacitor, feed-forward ΔΣ modulator. The gain of the differential amplifier is set by internal precision resistors with a differential input impedance of R_{IND}. The modulator converts the analog input signal into a bitstream that is transferred across the isolation barrier, as described in the *Isolation Channel Signal Transmission* section.

There are two restrictions on the analog input signals (INP and INN). First, if the input voltages V_{INP} or V_{INN} exceed the range specified in the *Absolute Maximum Ratings* table, the input currents must be limited to the absolute maximum value, because the electrostatic discharge (ESD) protection turns on. In addition, the linearity and parametric performance of the device are ensured only when the analog input voltage remains within the linear full-scale range (V_{FSR}) and within the common-mode input voltage range (V_{CM}), as specified in the *Recommended Operating Conditions* table.

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7.3.2 Isolation Channel Signal Transmission

The AMC1301 uses an on-off keying (OOK) modulation scheme, as shown in Figure 7-1, to transmit the modulator output bitstream across the SiO_2-based isolation barrier. The transmit driver (TX) shown in the *Functional Block Diagram* transmits an internally generated, high-frequency carrier across the isolation barrier to represent a digital *one* and does not send a signal to represent a digital *zero*. The nominal frequency of the carrier used inside the AMC1301 is 480 MHz.

The receiver (RX) on the other side of the isolation barrier recovers and demodulates the signal and provides the input to the fourth-order analog filter. The AMC1301 transmission channel is optimized to achieve the highest level of common-mode transient immunity (CMTI) and lowest level of radiated emissions caused by the high-frequency carrier and RX/TX buffer switching.

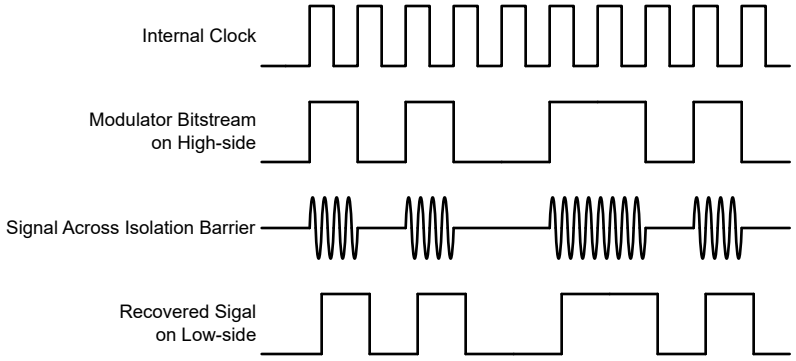


Figure 7-1. OOK-Based Modulation Scheme

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7.3.3 Analog Output

The AMC1301 offers a differential analog output comprised of the OUTP and OUTN pins. For differential input voltages (V_{INP} – V_{INN}) in the range from –250 mV to 250 mV, the device provides a linear response with a nominal gain of 8.2. For example, for a differential input voltage of 250 mV, the differential output voltage (V_{OUTP} – V_{OUTN}) is 2.05 V. At zero input (INP shorted to INN), both pins output the same common-mode output voltage V_{CMout}, as specified in the *Electrical Characteristics* table. For absolute differential input voltages greater than 250 mV but less than 320 mV, the differential output voltage continues to increase in magnitude but with reduced linearity performance. The outputs saturate at a differential output voltage of $V_{CLIPout}$, as shown in Figure 7-2, if the differential input voltage exceeds the $V_{Clipping}$ value.

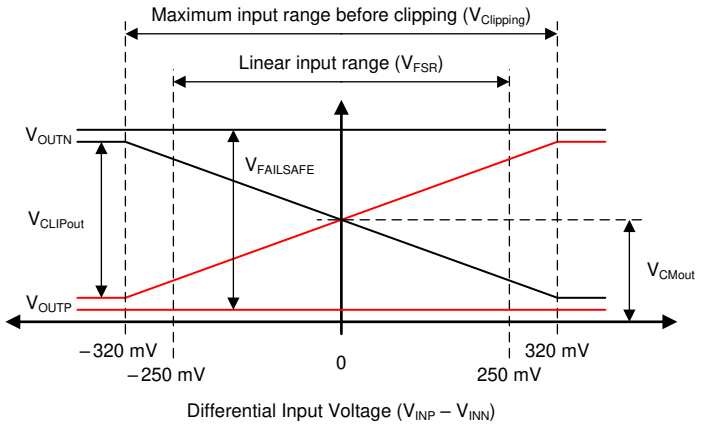


Figure 7-2. Output Behavior of the AMC1301

The AMC1301 offers a fail-safe feature that simplifies diagnostics on a system level. Figure 7-2 shows the fail-safe mode, in which the AMC1301 outputs a negative differential output voltage that does not occur under normal operating conditions. The fail-safe output is active in two cases:

- When the high-side supply is missing or below the $VDD1_{UV}$ threshold
- When the common-mode input voltage, that is V_{CM} = (V_{INP} + V_{INN}) / 2, exceeds the common-mode overvoltage detection level V_{CMov}

Use the maximum $V_{FAILSAFE}$ voltage specified in the *Electrical Characteristics* table as a reference value for fail-safe detection on a system level.

7.4 Device Functional Modes

The AMC1301 assumes normal operation as soon as VDD1, VDD2, and the input common-mode voltage (V_{CM}) are within the operational ranges, as specified in *Electrical Characteristics* table. In this mode, the output voltage is proportional to the input voltage.

The AMC1301 enters fail-safe mode whenever the high-side supply (VDD1) is missing or the input common-mode voltage (V_{CM}) exceeds the specified input-overvoltage detection level V_{CMov}. In this mode, the differential output voltage is a fixed, negative value ($V_{FAILSAFE}$). See the *Analog Output* section for details.

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8 Application and Implementation

Note

Information in the following applications sections is not part of the TI component specification, and TI does not warrant its accuracy or completeness. TI's customers are responsible for determining suitability of components for their purposes, as well as validating and testing their design implementation to confirm system functionality.

8.1 Application Information

With a low analog input voltage range, high DC accuracy, and low temperature drift, the AMC1301 is designed for precision, shunt-based current sensing in applications requiring high voltage isolation.

8.2 Typical Application

Figure 8-1 shows the AMC1301 in a typical application of an AC motor drive. The load current flowing through an external shunt resistor RSHUNT produces a voltage drop that is sensed by the AMC1301. The AMC1301 digitizes the analog input signal on the high-side, transfers the data across the isolation barrier to the low-side, reconstructs the analog signal, and presents that signal as a differential voltage on the output pins.

The differential input, differential output, and the high common-mode transient immunity (CMTI) of the AMC1301 provide reliable and accurate operation even in high-noise environments.

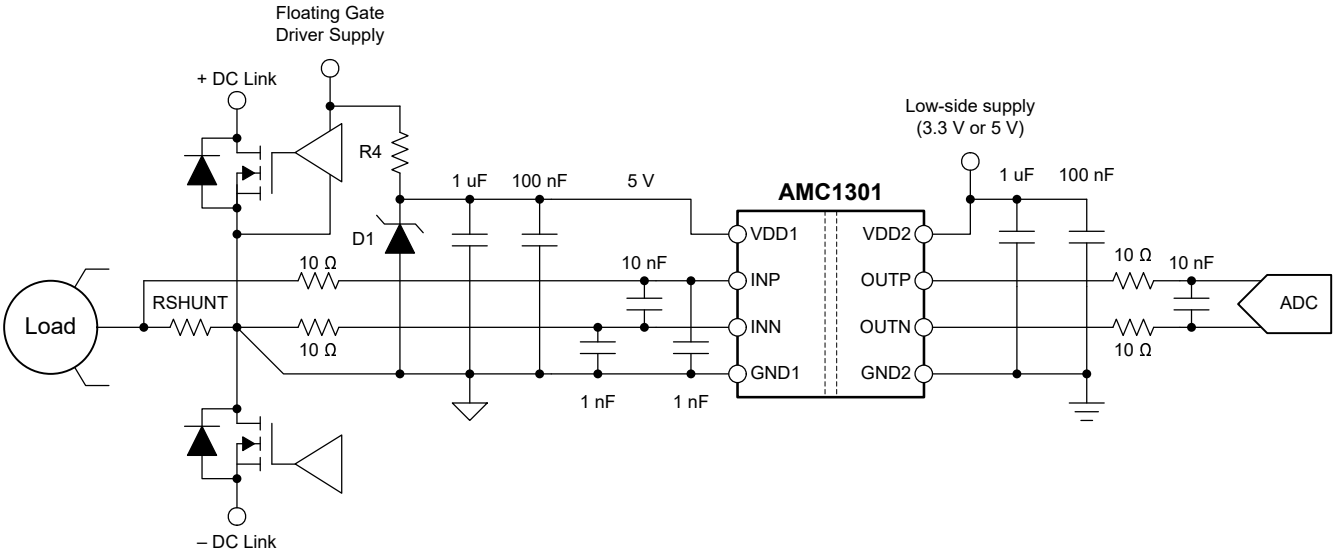


Figure 8-1. Using the AMC1301 for Current Sensing in a Typical Application

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8.2.1 Design Requirements

Table 8-1 lists the parameters for this typical application.

Table 8-1. Design Requirements

PARAMETER	VALUE
High-side supply voltage	3.3 V or 5 V
Low-side supply voltage	3.3 V or 5 V
Voltage drop across RSHUNT for a linear response	±250 mV (maximum)
Signal delay (50% V_{IN} to 90% OUTP, OUTN)	3 µs (maximum)

8.2.2 Detailed Design Procedure

In Figure 8-1, the high-side power supply (VDD1) for the AMC1301 is derived from the floating power supply of the upper gate driver.

The floating ground reference (GND1) is derived from the end of the shunt resistor that is connected to the negative input of the AMC1301 (INN). If a four-pin shunt is used, the inputs of the AMC1301 are connected to the inner leads and GND1 is connected to the outer lead on the INN-side of the shunt. To minimize offset and improve accuracy, route the ground connection as a separate trace that connects directly to the shunt resistor rather than shorting GND1 to INN directly at the input to the device. See the *Layout* section for more details.

8.2.2.1 Shunt Resistor Sizing

Use Ohm's Law to calculate the voltage drop across the shunt resistor (V_{SHUNT}) for the desired measured current: $V_{SHUNT} = I \times RSHUNT$.

Consider the following two restrictions when selecting the value of the shunt resistor, RSHUNT:

- The voltage drop caused by the nominal current range must not exceed the recommended differential input voltage range for a linear response: $|V_{SHUNT}| \leq |V_{FSR}|$
- The voltage drop caused by the maximum allowed overcurrent must not exceed the input voltage that causes a clipping output: $|V_{SHUNT}| \leq |V_{Clipping}|$

8.2.2.2 Input Filter Design

Place a differential RC filter (R1, R2, C5) in front of the isolated amplifier to improve signal-to-noise performance of the signal path. Design the input filter such that:

- The cutoff frequency of the filter is at least one order of magnitude lower than the sampling frequency of the ΔΣ modulator (20 MHz)
- The input bias current does not generate significant voltage drop across the DC impedances (R1, R2) of the input filter
- The impedances measured from the analog inputs are equal (R1 equals R2)

Capacitors C6 and C7 are optional and improve common-mode rejection at high frequencies (>1 MHz). For best performance, C6 must match the value of C7 and both capacitors must be 10 to 20 times lower in value than C5. For most applications, the structure shown in Figure 8-2 achieves excellent performance.

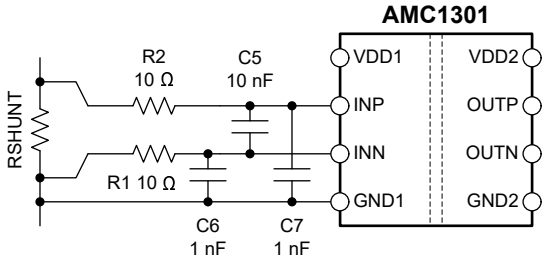


Figure 8-2. Differential Input Filter

8.2.2.3 Differential to Single-Ended Output Conversion

Figure 8-3 shows an example of a TLV900x-based signal conversion and filter circuit for systems using single-ended input ADCs to convert the analog output voltage into digital. For R1 = R3 and R2 = R4, the output voltage equals (R2 / R1) × (V_{OUTP} – V_{OUTN}) + V_{REF}. Tailor the bandwidth of this filter stage to the bandwidth requirement of the system and use NP0-type capacitors for best performance. For most applications, R1 = R2 = R3 = R4 = 3.3 kΩ and C1 = C2 = 330 pF yields good performance.

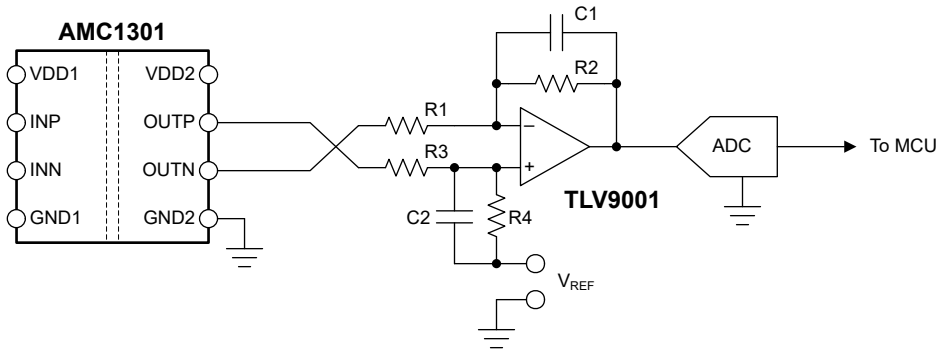


Figure 8-3. Connecting the AMC1301 Output to a Single-Ended Input ADC

For more information on the general procedure to design the filtering and driving stages of SAR ADCs, see the *18-Bit, 1MSPS Data Acquisition Block (DAQ) Optimized for Lowest Distortion and Noise* and *18-Bit Data Acquisition Block (DAQ) Optimized for Lowest Power* reference guides, available for download at www.ti.com.

8.2.3 Application Curve

One important aspect of power-stage design is the effective detection of an overcurrent condition to protect the switching devices and passive components from damage. To power off the system quickly in the event of an overcurrent condition, a low delay caused by the isolated amplifier is required. Figure 8-4 shows the typical full-scale step response of the AMC1301.



Figure 8-4. Step Response of the AMC1301

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8.3 Best Design Practices

Do not leave the inputs of the AMC1301 unconnected (floating) when the device is powered up. If the device inputs are left floating, the input bias current can possibly drive the inputs to a positive value that exceeds the operating common-mode input voltage, thus causing the device to output the fail-safe voltage as described in the *Analog Output* section.

Connect the high-side ground (GND1) to INN, either by a hard short or through a resistive path. A DC current path between INN and GND1 is required to define the input common-mode voltage. Take care not to exceed the input common-mode range as specified in the *Recommended Operating Conditions* table. For best accuracy, route the ground connection as a separate trace that connects directly to the shunt resistor rather than shorting GND1 to INN directly at the input to the device. See the *Layout* section for more details.

8.4 Power Supply Recommendations

The AMC1301 does not require any specific power-up sequencing. The high-side power supply (AVDD) is decoupled with a low-ESR, 100-nF capacitor (C1) parallel to a low-ESR, 1-µF capacitor (C2). The low-side power supply (DVDD) is equally decoupled with a low-ESR, 100-nF capacitor (C3) parallel to a low-ESR, 1-µF capacitor (C4). Place all four capacitors (C1, C2, C3, and C4) as close to the device as possible.

The ground reference for the high-side (AGND) is derived from the end of the shunt resistor that is connected to the negative input (INN) of the device. For best DC accuracy, use a separate trace to make this connection instead of shorting AGND to INN directly at the device input. If a four-terminal shunt is used, the device inputs are connected to the inner leads and AGND is connected to the outer lead on the INN side of the shunt. Figure 8-5 shows a decoupling diagram of the AMC1301.

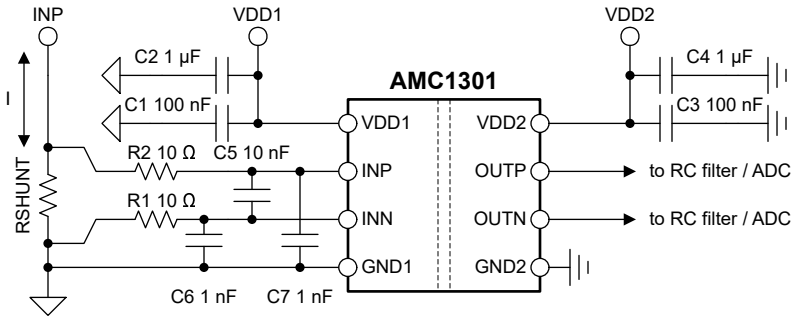


Figure 8-5. Decoupling of the AMC1301

8.5 Layout

8.5.1 Layout Guidelines

Figure 8-6 shows a layout recommendation with the critical placement of the decoupling capacitors (as close as possible to the AMC1301 supply pins) and placement of the other components required by the device. For best performance, place the shunt resistor close to the INP and INN inputs of the AMC1301 and keep the layout of both connections symmetrical.

8.5.2 Layout Example

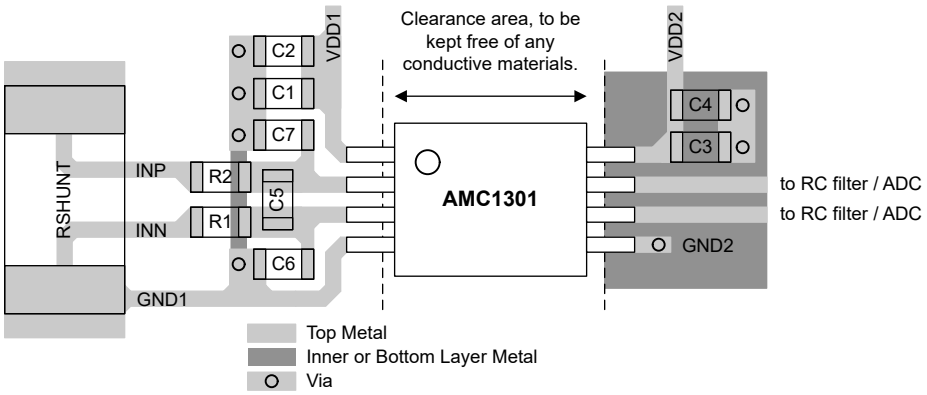


Figure 8-6. Recommended Layout of the AMC1301

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9 Device and Documentation Support

9.1 Documentation Support

9.1.1 Related Documentation

For related documentation, see the following:

- Texas Instruments, *Isolation Glossary* application note
- Texas Instruments, *Semiconductor and IC Package Thermal Metrics* application note
- Texas Instruments, *ISO72x Digital Isolator Magnetic-Field Immunity* application note
- Texas Instruments, *TLV900x Low-Power, RRIO, 1-MHz Operational Amplifier for Cost-Sensitive Systems* data sheet
- Texas Instruments, *18-Bit, 1-MSPS Data Acquisition Block (DAQ) Optimized for Lowest Distortion and Noise* reference guide
- Texas Instruments, *18-Bit, 1-MSPS Data Acquisition Block (DAQ) Optimized for Lowest Power* reference guide
- Texas Instruments, *Isolated Amplifier Voltage Sensing Excel Calculator* design tool
- Texas Instruments, *Best in Class Radiated Emissions EMI Performance with the AMC1300B-Q1 Isolated Amplifier* technical white paper
- Texas Instruments, *Isolated Voltage-Measurement Circuit With ±250-mV Input and Differential Output* application note

9.2 Receiving Notification of Documentation Updates

To receive notification of documentation updates, navigate to the device product folder on ti.com. Click on *Subscribe to updates* to register and receive a weekly digest of any product information that has changed. For change details, review the revision history included in any revised document.

9.3 Support Resources

TI E2E™ support forums are an engineer's go-to source for fast, verified answers and design help — straight from the experts. Search existing answers or ask your own question to get the quick design help you need.

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This integrated circuit can be damaged by ESD. Texas Instruments recommends that all integrated circuits be handled with appropriate precautions. Failure to observe proper handling and installation procedures can cause damage.

ESD damage can range from subtle performance degradation to complete device failure. Precision integrated circuits may be more susceptible to damage because very small parametric changes could cause the device not to meet its published specifications.

9.6 Glossary

TI Glossary	This glossary lists and explains terms, acronyms, and definitions.

10 Mechanical, Packaging, and Orderable Information

The following pages include mechanical, packaging, and orderable information. This information is the most current data available for the designated devices. This data is subject to change without notice and revision of this document. For browser-based versions of this data sheet, refer to the left-hand navigation.

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PACKAGING INFORMATION

Orderable part number	Status (1)	Material type (2)	Package | Pins	Package qty | Carrier	RoHS (3)	Lead finish/ Ball material (4)	MSL rating/ Peak reflow (5)	Op temp (°C)	Part marking (6)
AMC1301DWV	Active	Production	SOIC (DWV) | 8	64 | TUBE	Yes	NIPDAU	Level-3-260C-168 HR	-40 to 125	AMC1301
AMC1301DWVR	Active	Production	SOIC (DWV) | 8	1000 | LARGE T&R	Yes	NIPDAU	Level-3-260C-168 HR	-40 to 125	AMC1301
AMC1301DWVRG4	Active	Production	SOIC (DWV) | 8	1000 | LARGE T&R	Yes	NIPDAU	Level-3-260C-168 HR	-55 to 125	AMC1301
AMC1301SDWV	Active	Production	SOIC (DWV) | 8	64 | TUBE	Yes	NIPDAU	Level-3-260C-168 HR	-55 to 125	AMC1301S
AMC1301SDWVR	Active	Production	SOIC (DWV) | 8	1000 | LARGE T&R	Yes	NIPDAU	Level-3-260C-168 HR	-55 to 125	AMC1301S
AMC1301SDWVRG4	Active	Production	SOIC (DWV) | 8	1000 | LARGE T&R	Yes	NIPDAU	Level-3-260C-168 HR	-55 to 125	AMC1301S

(1) **Status:** For more details on status, see our product life cycle.

(2) **Material type:** When designated, preproduction parts are prototypes/experimental devices, and are not yet approved or released for full production. Testing and final process, including without limitation quality assurance, reliability performance testing, and/or process qualification, may not yet be complete, and this item is subject to further changes or possible discontinuation. If available for ordering, purchases will be subject to an additional waiver at checkout, and are intended for early internal evaluation purposes only. These items are sold without warranties of any kind.

(3) **RoHS values:** Yes, No, RoHS Exempt. See the TI RoHS Statement for additional information and value definition.

(4) **Lead finish/Ball material:** Parts may have multiple material finish options. Finish options are separated by a vertical ruled line. Lead finish/Ball material values may wrap to two lines if the finish value exceeds the maximum column width.

(5) **MSL rating/Peak reflow:** The moisture sensitivity level ratings and peak solder (reflow) temperatures. In the event that a part has multiple moisture sensitivity ratings, only the lowest level per JEDEC standards is shown. Refer to the shipping label for the actual reflow temperature that will be used to mount the part to the printed circuit board.

(6) **Part marking:** There may be an additional marking, which relates to the logo, the lot trace code information, or the environmental category of the part.

Multiple part markings will be inside parentheses. Only one part marking contained in parentheses and separated by a "~" will appear on a part. If a line is indented then it is a continuation of the previous line and the two combined represent the entire part marking for that device.

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OTHER QUALIFIED VERSIONS OF AMC1301 :

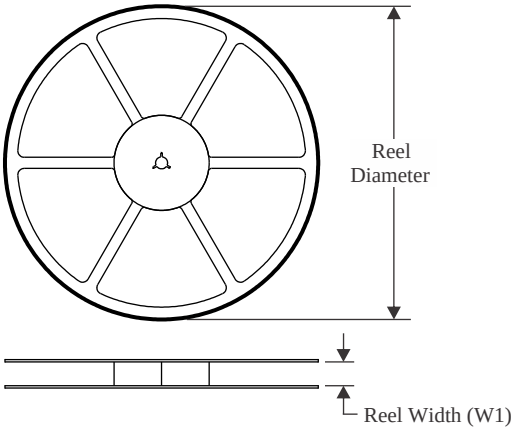
- Automotive : AMC1301-Q1

NOTE: Qualified Version Definitions:

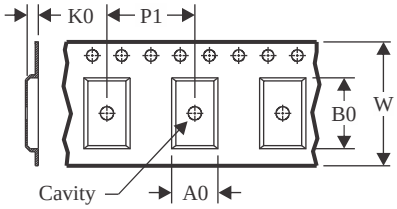
- Automotive - Q100 devices qualified for high-reliability automotive applications targeting zero defects

TAPE AND REEL INFORMATION

REEL DIMENSIONS

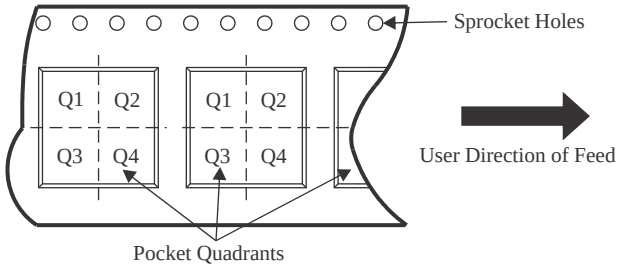


TAPE DIMENSIONS



A0	Dimension designed to accommodate the component width
B0	Dimension designed to accommodate the component length
K0	Dimension designed to accommodate the component thickness
W	Overall width of the carrier tape
P1	Pitch between successive cavity centers

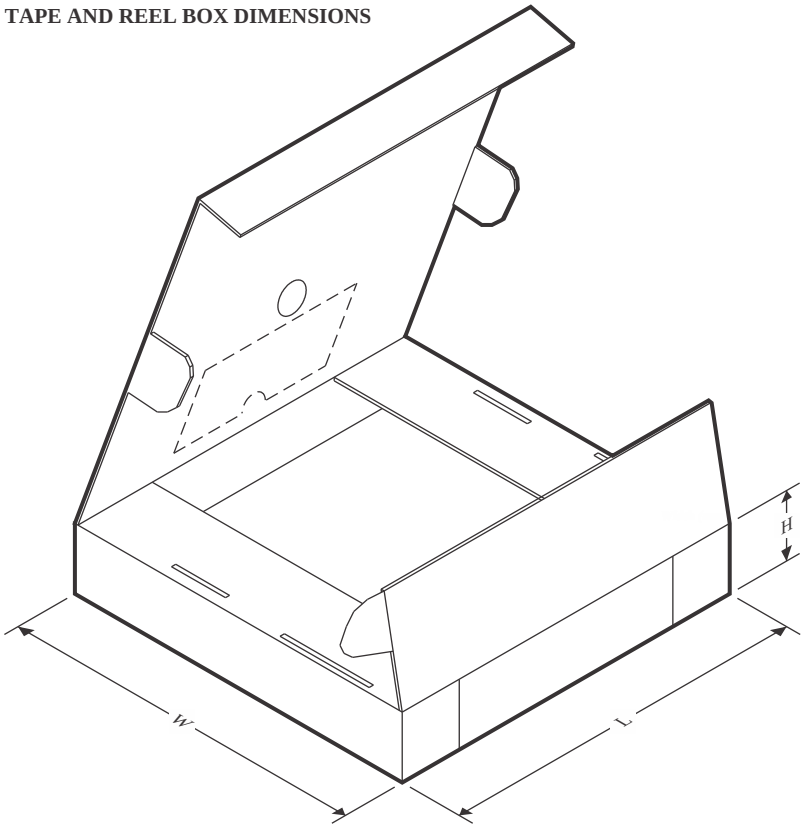
QUADRANT ASSIGNMENTS FOR PIN 1 ORIENTATION IN TAPE



*All dimensions are nominal

Device	Package Type	Package Drawing	Pins	SPQ	Reel Diameter (mm)	Reel Width W1 (mm)	A0 (mm)	B0 (mm)	K0 (mm)	P1 (mm)	W (mm)	Pin1 Quadrant
AMC1301DWVR	SOIC	DWV	8	1000	330.0	16.4	12.15	6.2	3.05	16.0	16.0	Q1
AMC1301DWVRG4	SOIC	DWV	8	1000	330.0	16.4	12.15	6.2	3.05	16.0	16.0	Q1
AMC1301SDWVR	SOIC	DWV	8	1000	330.0	16.4	12.15	6.2	3.05	16.0	16.0	Q1
AMC1301SDWVRG4	SOIC	DWV	8	1000	330.0	16.4	12.15	6.2	3.05	16.0	16.0	Q1

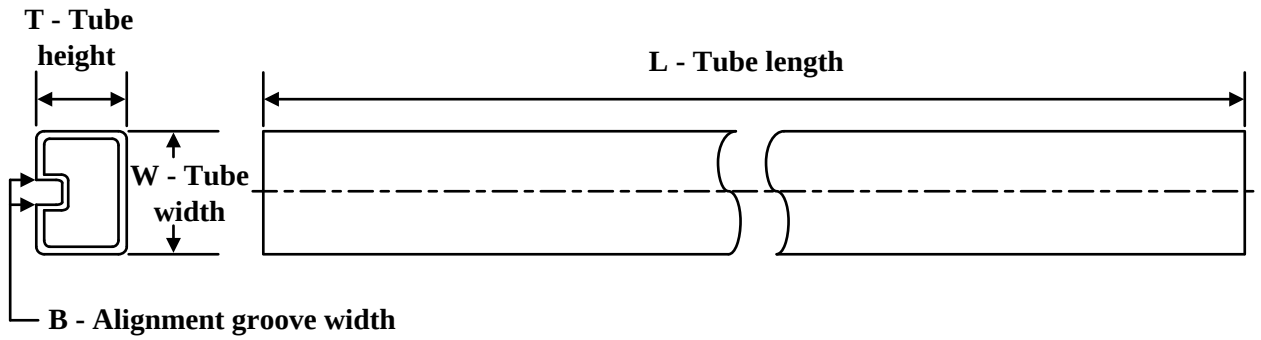
TAPE AND REEL BOX DIMENSIONS



*All dimensions are nominal

Device	Package Type	Package Drawing	Pins	SPQ	Length (mm)	Width (mm)	Height (mm)
AMC1301DWVR	SOIC	DWV	8	1000	353.0	353.0	32.0
AMC1301DWVRG4	SOIC	DWV	8	1000	353.0	353.0	32.0
AMC1301SDWVR	SOIC	DWV	8	1000	353.0	353.0	32.0
AMC1301SDWVRG4	SOIC	DWV	8	1000	353.0	353.0	32.0

TUBE



*All dimensions are nominal

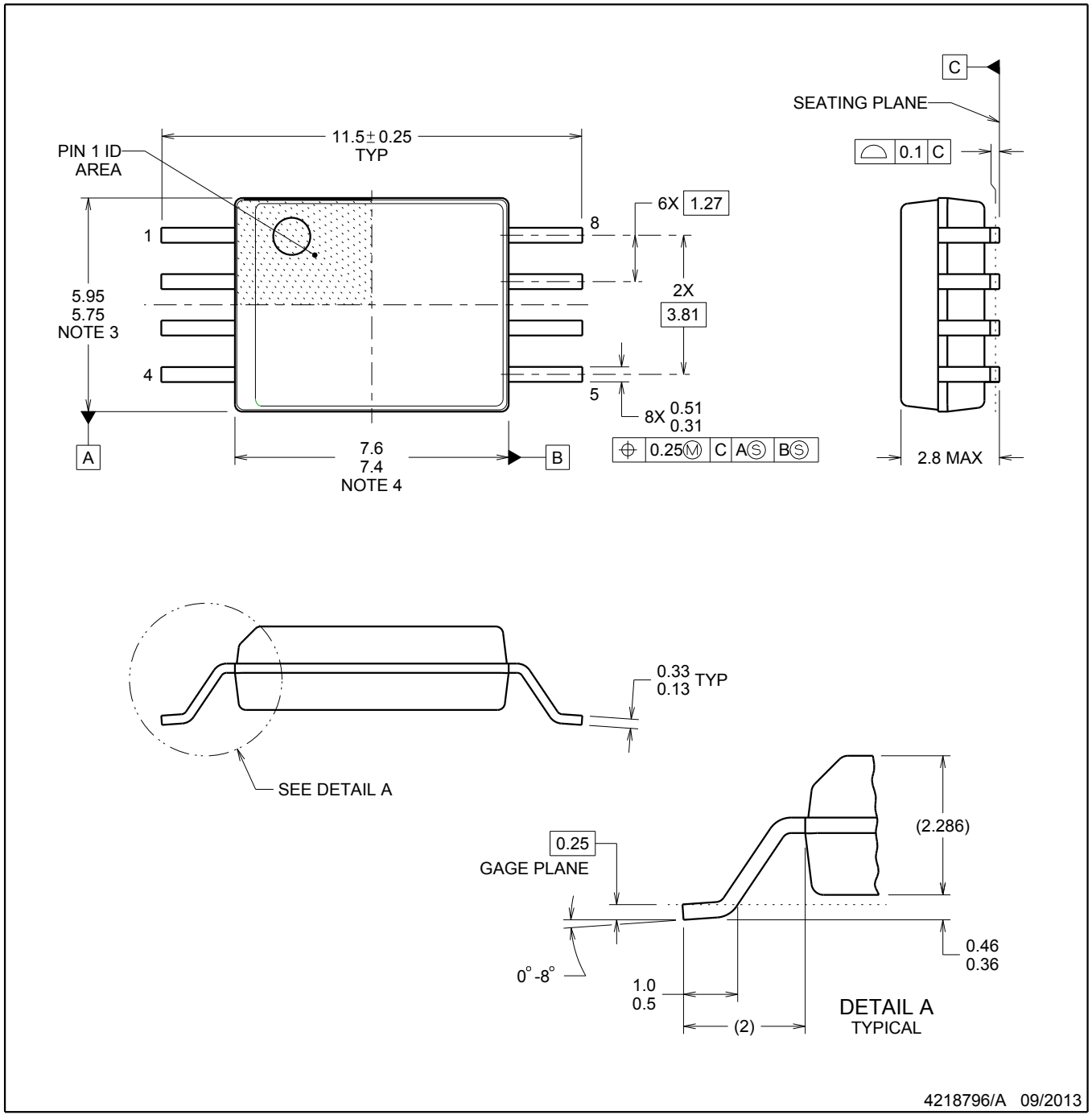
Device	Package Name	Package Type	Pins	SPQ	L (mm)	W (mm)	T (µm)	B (mm)
AMC1301DWV	DWV	SOIC	8	64	505.46	13.94	4826	6.6
AMC1301SDWV	DWV	SOIC	8	64	505.46	13.94	4826	6.6



DWV0008A

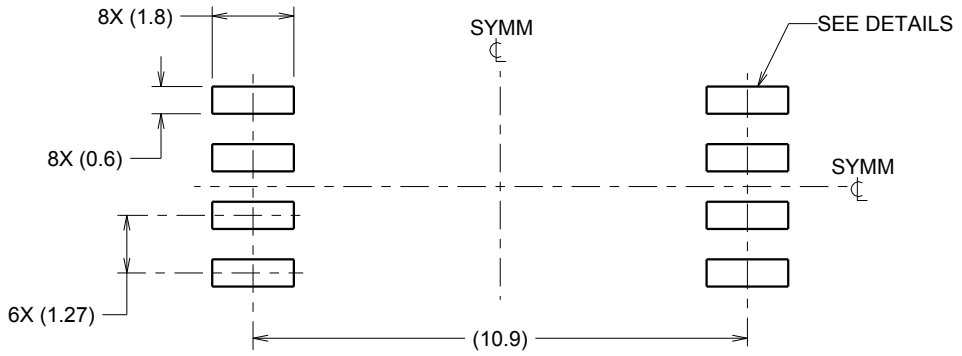
SOIC - 2.8 mm max height

SOIC

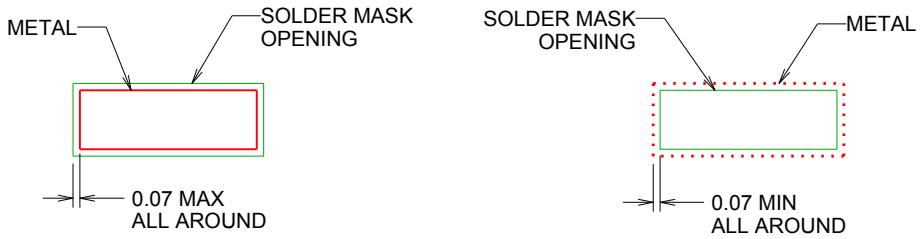


NOTES:

1. All linear dimensions are in millimeters. Dimensions in parenthesis are for reference only. Dimensioning and tolerancing per ASME Y14.5M.
2. This drawing is subject to change without notice.
3. This dimension does not include mold flash, protrusions, or gate burrs. Mold flash, protrusions, or gate burrs shall not exceed 0.15 mm, per side.
4. This dimension does not include interlead flash. Interlead flash shall not exceed 0.25 mm, per side.



LAND PATTERN EXAMPLE
9.1 mm NOMINAL CLEARANCE/CREEPAGE
SCALE:6X



SOLDER MASK DETAILS

4218796/A 09/2013

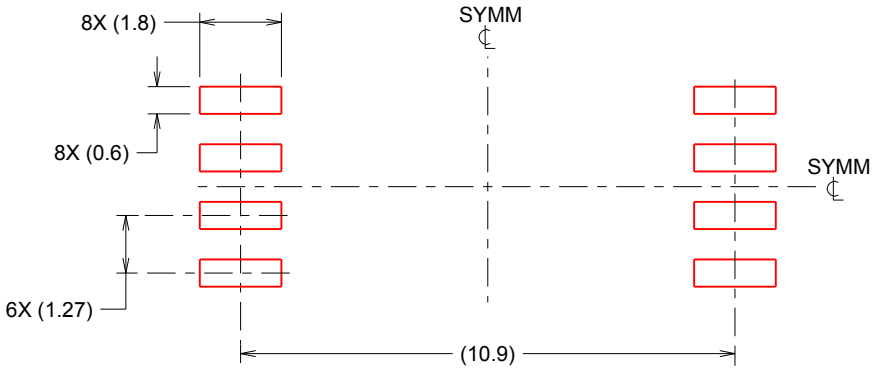
NOTES: (continued)

5. Publication IPC-7351 may have alternate designs.
6. Solder mask tolerances between and around signal pads can vary based on board fabrication site.

DWV0008A

SOIC - 2.8 mm max height

SOIC



SOLDER PASTE EXAMPLE
BASED ON 0.125 mm THICK STENCIL
SCALE:6X

4218796/A 09/2013

NOTES: (continued)

7. Laser cutting apertures with trapezoidal walls and rounded corners may offer better paste release. IPC-7525 may have alternate design recommendations.
8. Board assembly site may have different recommendations for stencil design.

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