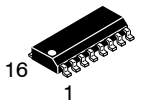
Enhanced Current Mode PWM Controller

CS51021A



SOIC−16
D SUFFIX
CASE 751B−05

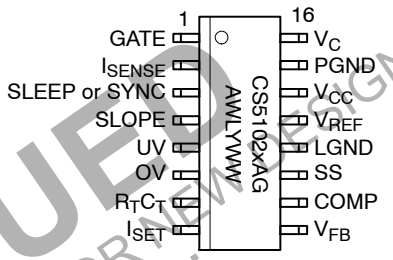
The CS51021A Fixed Frequency PWM Current Mode Controller provides all necessary features required for AC−DC or DC−DC primary side control. Several features are included eliminating the additional components needed to implement them externally. In addition to low startup current (75 μA) and high frequency operation capability, the CS51021A includes overvoltage and undervoltage monitoring, externally programmable dual threshold overcurrent protection, current sense leading edge blanking, current slope compensation, accurate duty cycle control and an externally available 5.0 V reference. The CS51021A features bidirectional synchronization capability. The CS51021A is available in a 16 lead narrow body SOIC package.

Device	Sleep/Synch	V_{CC} Start/Stop
CS51021A	Synch	8.25 V/7.7 V

Features

- 75 μA Max. Startup Current
- Fixed Frequency Current Mode Control
- 1.0 MHz Switching Frequency
- Undervoltage Protection Monitor
- Overvoltage Protection Monitor with Programmable Hysteresis
- Programmable Dual Threshold Overcurrent Protection with Delayed Restart
- Programmable Soft Start
- Accurate Maximum Duty Cycle Limit
- Programmable Slope Compensation
- Leading Edge Current Sense Blanking
- 1.0 A Sink/Source Gate Drive
- Bidirectional Synchronization
- 50 ns PWM Propagation Delay
- These Devices are Pb−Free and are RoHS Compliant

PIN CONNECTIONS AND MARKING DIAGRAM



x = Specific Device Code
A = Assembly Location
WL = Wafer Lot
Y = Year
WW = Work Week
G = Pb−Free Package

ORDERING INFORMATION

See detailed ordering and shipping information in the package dimensions section on page 9 of this data sheet.

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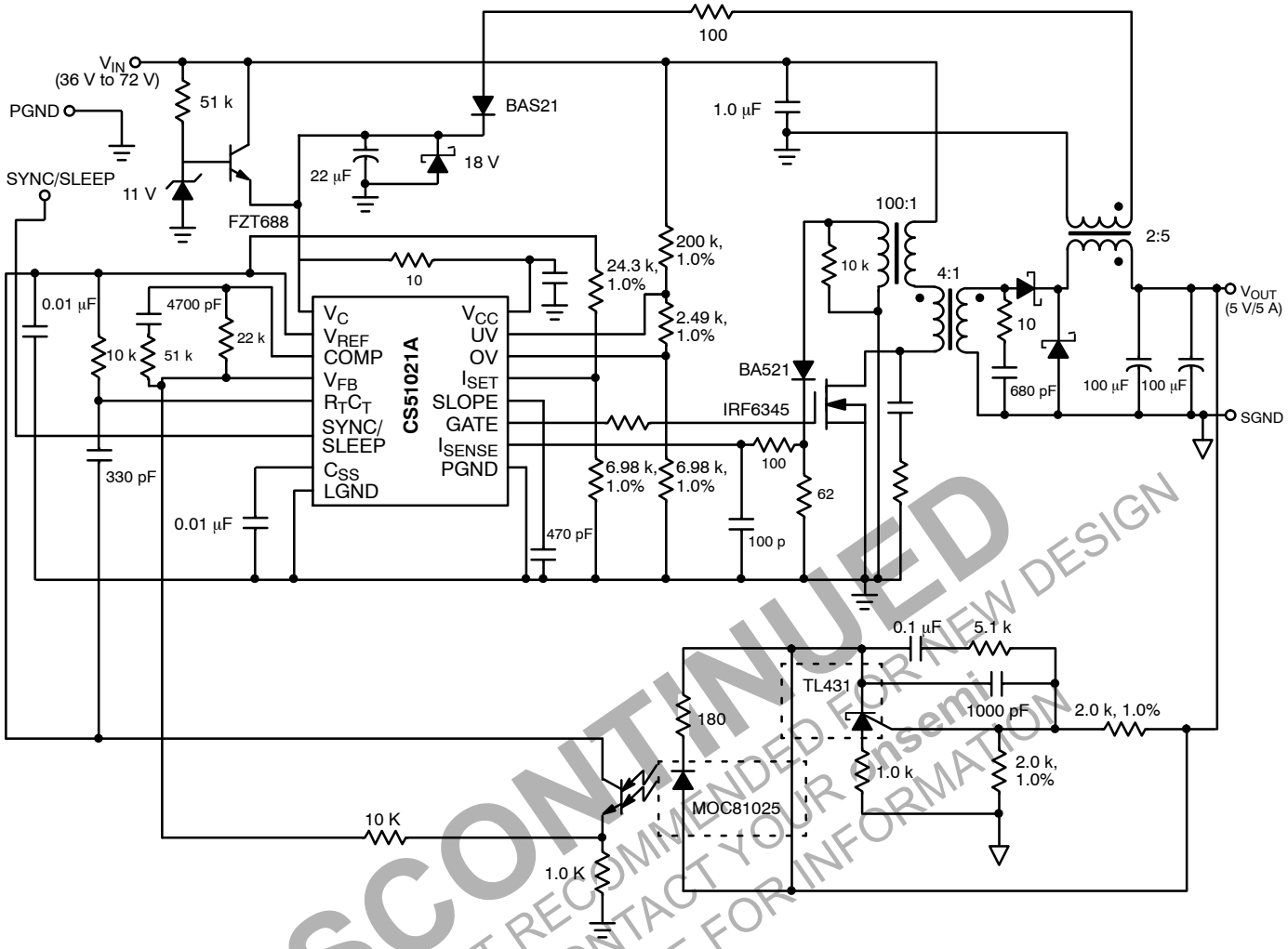


Figure 1. Typical Application Diagram, 36−72 V to 5.0 V, 5.0 A DC−DC Converter

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MAXIMUM RATINGS*

Rating	Value	Unit
Power Supply Voltage, V_{CC}	−0.3, 20	V
Driver Supply Voltage, V_C	−0.3, 20	V
SYNC, SLEEP, R_TC_T, SOFT−START, V_{FB}, SLOPE, I_{SENSE}, UV, OV, I_{SET} (Logic Pins)	0.25 to V_{REF}	V
Peak GATE Output Current	1.0	A
Steady State Output Current	±0.2	A
Operating Junction Temperature, T_J	150	°C
Storage Temperature Range, T_S	−65 to +150	°C
ESD (Human Body Model)	2.0	kV
Lead Temperature Soldering: Reflow: (SMD styles only) (Note 1)	230 peak	°C

Stresses exceeding those listed in the Maximum Ratings table may damage the device. If any of these limits are exceeded, device functionality should not be assumed, damage may occur and reliability may be affected.

*The maximum package power dissipation must be observed.

1. 60 second maximum above 183°C.

ELECTRICAL CHARACTERISTICS (Unless otherwise stated, specifications apply for −40°C < T_A < 85°C, −40°C < T_J < 150°C, 3.0 V < V_C < 20 V, 8.2 V < V_{CC} < 20 V, R_T = 12 kΩ, C_T = 390 pF)

Characteristic	Test Conditions	Min	Typ	Max	Unit
Under Voltage Lockout					
START Threshold	–	7.95	8.25	8.8	V
STOP Threshold	–	7.4	7.7	8.2	V
Hysteresis	–	0.50	0.75	1.00	V
I_{CC} @ Startup	V_{CC} < UV_{START} Threshold	–	40	75	μA
I_{CC} Operating	–	–	7.0	9.0	mA
I_{CC} Operating	Includes 1.0 nF Load	–	7.0	12	mA
Voltage Reference					
Initial Accuracy	T_A = 25°C, I_{REF} = 2.0 mA, V_{CC} = 14 V, (Note 2)	4.95	5.0	5.05	V
Total Accuracy	1.0 mA < I_{REF} < 10 mA	4.9	5.0	5.15	V
Line Regulation	8.2 V < V_{CC} < 18 V, I_{REF} = 2.0 mA	–	6.0	20	mV
Load Regulation	1.0 mA < I_{REF} < 10 mA	–	6.0	15	mV
NOISE Voltage	(Note 2)	–	50	–	μV
OP Life Shift	T = 1000 Hours, (Note 2)	–	4.0	20	mV
FAULT Voltage	Force V_{REF}	0.90 × V_{REF}	0.93 × V_{REF}	0.95 × V_{REF}	V
OK Voltage	Force V_{REF}	0.94 × V_{REF}	0.96 × V_{REF}	0.985 × V_{REF}	V
OK Hysteresis	Force V_{REF}	75	165	250	mV
Current Limit	Force V_{REF}	−20	–	–	mA
Error Amplifier					
Initial Accuracy	T_A = 25°C, I_{REF} = 2.0 mA, V_{CC} = 14 V, V_{FB} = COMP, (Note 2)	2.465	2.515	2.565	V
Reference Voltage	V_{FB} = COMP	2.440	2.515	2.590	V
V_{FB} Leakage Current	V_{FB} = 0 V	–	−0.2	−2.0	μA
Open Loop Gain	1.4 V < COMP < 4.0 V, (Note 2)	60	90	–	dB
Unity Gain Bandwidth	(Note 2)	1.5	2.5	–	MHz
COMP Sink Current	COMP = 1.5 V, V_{FB} = 2.7 V	2.0	6.0	–	mA
COMP Source Current	COMP = 1.5 V, V_{FB} = 2.3 V	−0.2	−0.5	–	mA
COMP High Voltage	V_{FB} = 2.3 V	4.35	4.8	5.0	V
COMP Low Voltage	V_{FB} = 2.7 V	0.4	0.8	1.2	V
PS Ripple Rejection	FREQ = 120 Hz, (Note 2)	60	85	–	dB
SS Clamp, V_{COMP}	V_{SS} = 2.5 V, V_{FB} = 0 V, I_{SET} = 2.0 V	2.4	2.5	2.6	V
$I_{LIM(SET)}$ Clamp	(Note 2)	0.95	1.0	1.15	V

2. Guaranteed by design, not 100% tested in production.

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ELECTRICAL CHARACTERISTICS (Unless otherwise stated, specifications apply for −40°C < T_A < 85°C, −40°C < T_J < 150°C, 3.0 V < V_C < 20 V, 8.2 V < V_{CC} < 20 V, R_T = 12 kΩ, C_T = 390 pF)

Characteristic	Test Conditions	Min	Typ	Max	Unit
Oscillator					
Accuracy	R_T = 12 k, C_T = 390 pF	230	255	280	kHz
Voltage Stability	Delta Frequency 8.2 V < V_{CC} < 20 V	–	2.0	3.0	%
Temperature Stability	T_{MIN} < T_A < T_{MAX}, (Note 3)	–	8.0	–	%
Min Charge & Discharge Time	(Note 3)	0.333	–	–	μs
Duty Cycle Accuracy	R_T = 12 k, C_T = 390 pF	70	77	83	%
Peak Voltage	(Note 3)	–	3.0	–	V
Valley Voltage	(Note 3)	–	1.5	–	V
Valley Clamp Voltage	10 k Resistor to ground on R_TC_T	1.2	1.4	1.6	V
Discharge Current	–	0.8	1.0	1.2	mA
Discharge Current	TA = 25°C, Note 3	0.925	1.0	1.075	mA
Synchronization (CS51021A/3A)					
Input Threshold	–	1.0	1.5	2.7	V
Output Pulsewidth	–	160	260	400	ns
Output High Voltage	I_{SYNC} = 100 μA	3.5	4.3	4.8	V
Input Resistance	(Note 3)	35	70	140	kΩ
Drive Delay	SYNC to GATE RESET	80	120	150	ns
Output Drive Current	1.0 k Load	1.25	2.0	3.5	mA
SLEEP (CS51022A/4A)					
SLEEP Input Threshold	Active High	1.0	1.5	2.7	V
SLEEP Input Current	V_{SLEEP} = 4.0 V	11	25	46	μA
I_{CC} @ SLEEP	V_{CC} ≤ 15 V	–	50	100	μA
GATE Driver					
HIGH Voltage	Measure V_C – GATE, V_C = 10 V, 150 mA Load	–	1.5	2.2	V
LOW Voltage	Measure GATE – PGND, 150 mA SINK	–	1.2	1.5	V
HIGH Voltage Clamp	V_C = 20 V, 1.0 nF	11	13.5	16	V
LOW Voltage Clamp	Measured at 10 mA Output Current	–	0.6	0.8	V
Peak Current	V_C = 20 V, 1.0 nF, (Note 3)	–	1.0	–	A
UVL Leakage	V_C = 20 V measured at 0 V	–	−1.0	−50	μA
RISE Time	Load = 1.0 nF, 1.0 V < GATE < 9.0 V, V_C = 20 V, T_A = 25°C	–	60	100	ns
FALL Time	Load = 1.0 nF, 9.0 V > GATE > 1 .0 V, V_C = 20 V	–	15	40	ns
SLOPE Compensation					
Charge Current	SLOPE = 2.0 V	−63	−53	−43	μA
COMP Gain	Fraction of slope voltage added to I_{SENSE}, (Note 3)	0.095	0.100	0.105	V/V
Discharge Voltage	SYNC = 0 V	–	0.1	0.2	V

3. Guaranteed by design, not 100% tested in production.

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ELECTRICAL CHARACTERISTICS (Unless otherwise stated, specifications apply for −40°C < T_A < 85°C, −40°C < T_J < 150°C, 3.0 V < V_C < 20 V, 8.2 V < V_{CC} < 20 V, R_T = 12 kΩ, C_T = 390 pF)

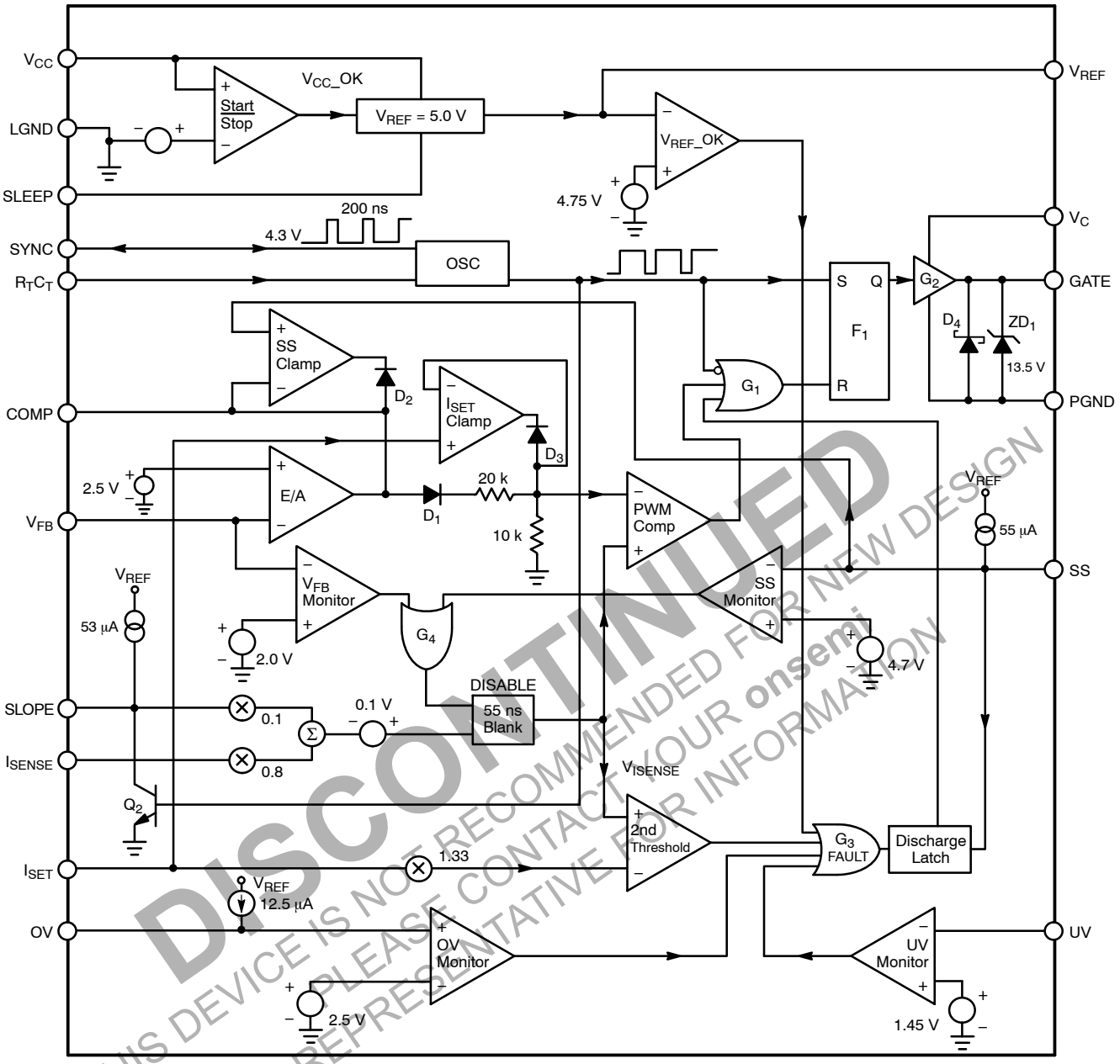
Characteristic	Test Conditions	Min	Typ	Max	Unit
Current Sense					
OFFSET Voltage	(Note 4)	0.09	0.10	0.11	V
Blanking Time	–	–	55	160	ns
Blanking Disable Voltage	Adjust V_{FB}	1.8	2.0	2.2	V
Second Current Threshold Gain	–	1.21	1.33	1.45	V/V
I_{SENSE} Input Resistance	–	–	5.0	–	kΩ
Minimum On Time	GATE High to Low	30	70	110	ns
Gain	(Note 4)	0.78	0.80	0.82	V/V
OV & UV Voltage Monitors					
OV Monitor Threshold	–	2.4	2.5	2.6	V
OV Hysteresis Current	–	−10	−12.5	−15	μA
UV Monitor Threshold	–	1.38	1.45	1.52	V
UV Monitor Hysteresis	–	25	75	100	mV
SOFT START (SS)					
Charge Current	SS = 2.0 V	−70	−55	−40	μA
Discharge Current	SS = 2.0 V	250	1000	–	μA
Charge Voltage, V_{SS}	–	4.4	4.7	5.0	V
Discharge Voltage, V_{SS}	–	0.25	0.27	0.30	V

4. Guaranteed by design, not 100% tested in production.

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PACKAGE PIN DESCRIPTION

PIN #	PIN SYMBOL	FUNCTION
16 Lead SO Narrow		
1	GATE	External power switch driver with 1.0 A peak capability.
2	I_{SENSE}	Current sense amplifier input.
3	SYNC	Bi−directional synchronization. Locks to the highest frequency.
4	SLOPE	Additional slope to the current sense signal. Internal current source charges the external capacitor.
5	UV	Undervoltage protection monitor.
6	OV	Overvoltage protection monitor.
7	R_TC_T	Timing resistor R_T and capacitor C_T determine oscillator frequency and maximum duty cycle, $D_{MAX.}$
8	I_{SET}	Voltage at this pin sets pulse−by−pulse overcurrent threshold, and second threshold (1.33 times higher) with Soft Start retrigger (hiccup mode).
9	V_{FB}	Feedback voltage input. Connected to the error amplifier inverting input.
10	COMP	Error amplifier output. Frequency compensation network is usually connected between COMP and V_{FB} pins.
11	SS	Charging external capacitor restricts error amplifier output voltage during the start or fault conditions (hiccup).
12	LGND	Logic ground.
13	V_{REF}	5.0 V reference voltage output.
14	V_{CC}	Logic supply voltage.
15	PGND	Output power stage ground connection.
16	V_C	Output power stage supply voltage.



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Figure 2. Block Diagram

CIRCUIT DESCRIPTION

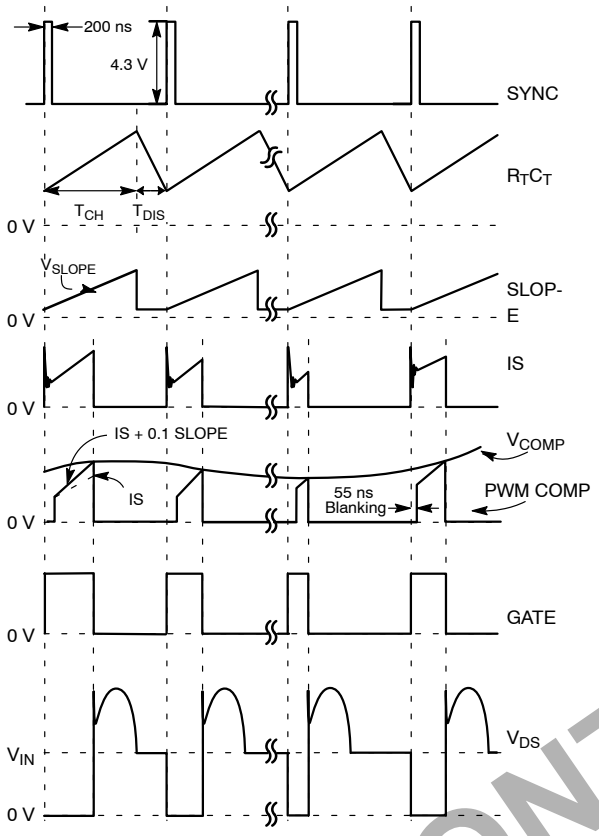


Figure 3. Typical Waveforms

THEORY OF OPERATION

Powering the IC

The IC has two supply and two ground pins. V_C and PGND pins provide high speed power drive for the external power switch. V_{CC} and LGND pins power the control portion of the IC. The internal logic monitors the supply voltage, V_{CC}. During abnormal operating conditions, the output is held low. The CS51021A requires only 75 μA of startup current.

Voltage Feedback

The output voltage is monitored via the V_{FB} pin and is compared with the internal 2.5 V reference. The error amplifier output minus one diode drop is divided by 3 and connected to the negative input of the PWM comparator. The positive input of the PWM comparator is connected to the modified current sense signal. The oscillator turns the external power switch on at the beginning of each cycle. When current sense ramp voltage exceeds the reference side of PWM comparator, the output stage latches off. It is turned on again at the beginning of the next oscillator cycle.

Current Sense and Protection

The current is monitored at the I_{SENSE} pin. The CS51021A has leading edge blanking circuitry that ignores the first 55 ns of each switching period. Blanking is disabled when V_{FB} is less than 2.0 V so that the minimum on−time of the controller does not have an additional 55 ns of delay time during fault conditions. For the remaining portion of the switching period, the current sense signal, combined with a fraction of the slope compensation voltage, is applied to the positive input of the PWM comparator where it is compared with the divided by three error amplifier output voltage. The pulse−by−pulse overcurrent protection threshold is set by the voltage at the I_{SET} pin. This voltage is passed through the I_{SET} Clamp and appears at the non−inverting input of the PWM comparator, limiting its dynamic range according to the following formula:

$$\text{Overcurrent Threshold} = 0.8 \times V_{I(SENSE)} + 0.1\ V + 0.1\ V_{SLOPE}$$

where

$V_{I(SENSE)}$ is voltage at the I_{SENSE} pin.

and

V_{SLOPE} is voltage at the SLOPE pin.

During extreme overcurrent or short circuit conditions, the slope of the current sense signal will become much steeper than during normal operation. Due to loop propagation delay, the sensed signal will overshoot the pulse−by−pulse threshold eventually reaching the second overcurrent protection threshold which is 1.33 times higher than the first threshold and is described by the following equation:

$$\text{2nd Threshold} = 1.33 \times V_{I(SET)}$$

Exceeding the second threshold will reset the Soft Start capacitor C_{SS} and reinitiate the Soft Start sequence, repeating for as long as the fault condition persists.

Soft Start

During power up, when the output filter capacitor is discharged and the output voltage is low, the voltage across the Soft Start capacitor (V_{SS}) controls the duty cycle. An internal current source of 55 μA charges C_{SS}. The maximum error amplifier output voltage is clamped by the SS Clamp. When the Soft Start capacitor voltage exceeds the error amplifier output voltage, the feedback loop takes over the duty cycle control. The Soft Start time can be estimated with the following formula:

$$t_{SS} = 9 \times 10^4 \times C_{SS}$$

The Soft Start voltage, V_{SS}, charges and discharges between 0.25 V and 4.7 V.

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Slope Compensation

DC−DC converters with current mode control require a current sense signal with slope compensation to avoid instability at duty cycles greater than 50%. Slope capacitor C_S is charged by an internal 53 μA current source and is discharged during the oscillator discharge time. The slope compensation voltage is divided by 10 and is added to the current sense voltage, $V_{I(SENSE)}$. The signal applied to the input of the PWM comparator is a combination of these two voltages. The slope compensation, dV_{SLOPE}/dt, is calculated using the following formula:

$$\frac{dV_{SLOPE}}{dt} = 0.1 \times \frac{53\ \mu A}{C_S}$$

It should be noted that internal capacitance of the IC will cause an error when determining slope compensation capacitance C_S. This error is typically small for large values of C_S, but increases as C_S becomes small and comparable to the internal capacitance. The effect is apparent as a reduction in charging current due to the need to charge the internal capacitance in parallel with C_S. Figure 4 shows a typical curve indicating this decrease in available charging current.

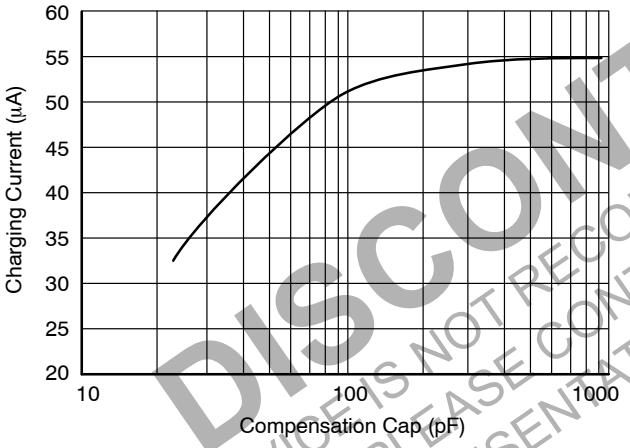


Figure 4. The Slope Compensation Pin Charge Current Reduces When a Small Capacitor Is Used.

Undervoltage (UV) and Overvoltage (OV) Monitor

Two independent comparators monitor OV and UV conditions. A string of three resistors is connected in series between the monitored voltage (usually the input voltage) and ground (see Figure 5). When voltage at the OV pin exceeds 2.5 V, an overvoltage condition is detected and GATE shuts down. An internal 12.5 μA current source turns on and feeds current into the external resistor, R_3, creating a hysteresis determined by the value of this resistor (the higher the value, the greater the hysteresis). The hysteresis voltage of the OV monitor is determined by the following formula:

$$V_{OV(HYST)} = 12.5\ \mu A \times R_3$$

where R_3 is a resistor connected from the OV pin to ground.

When the monitored voltage is low and the UV pin is less than 1.45 V, GATE shuts down. The UV pin has fixed 75 mV hysteresis.

Both OV and UV conditions are latched until the Soft Start capacitor is discharged. This way, every time a fault condition is detected the controller goes through the power up sequence.

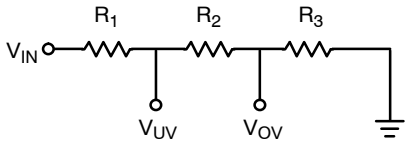


Figure 5. UV/OV Monitor Divider

To calculate the OV?UV resistor divider :

1. Solve for R_3, based on OV hysteresis requirements.

$$R_3 = \frac{V_{OV(HYST)} \times 2.5\ V}{V_{MAX} \times 12.5\ \mu A}$$

where $V_{OV(HYST)}$ is the desired amount of overvoltage hysteresis, and V_{MAX} is the input voltage at which the supply will shut down.

2. Find the total impedance of the divider.

$$R_{TOT} = R_1 + R_2 + R_3 = \frac{V_{MAX} \times R_3}{2.5}$$

3. Determine the value of R_2 from the UV threshold conditions.

$$R_2 = \frac{1.45 \times R_{TOT}}{V_{MIN}} - R_3$$

where V_{MIN} is the UV voltage at which the supply will shut down.

4. Calculate R_1.

$$R_1 = R_{TOT} - R_2 - R_3$$

5. The undervoltage hysteresis is given by :

$$V_{UV(HYST)} = \frac{V_{MIN} \times 0.075}{1.45}$$

V_{REF} Monitor

The 5.0 V reference voltage is internally monitored to ensure that it remains within specifications. The monitor, which outputs a fault, can be tripped by two methods:

- If the reference voltage drops below 4.75 V
- If V_{CC} falls below the STOP threshold

As indicated in the block diagram, any fault causes the output to stop switching and begins the discharge of the Soft Start capacitor C_{SS}.

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Synchronization

A bi−directional synchronization is provided to synchronize several controllers. When SYNC pins are connected together, the converters will lock to the highest switching frequency. The fastest controller becomes the master, producing a 4.3 V, 200 ns pulse train. Only one, the highest frequency SYNC signal, will appear on the SYNC line.

Sleep

The sleep input is an active high input. The CS51022A/4A is placed in sleep mode when SLEEP is driven high. In sleep mode, the controller and MOSFET are turned off. Connect to GND for normal operation. The sleep mode operates at VCC ≤ 15 V.

Oscillator and Duty Cycle Limit

The switching frequency is set by R_T and C_T connected to the R_TC_T pin. C_T charges and discharges between 3.0 V and 1.5 V.

The maximum duty cycle is set by the ratio of the on time, t_{ON}, and the whole period, $\mathbf{T = t_{ON} + t_{OFF}}$. Because the timing capacitor's discharge current is trimmed, the maximum duty cycle is well defined. It is determined by the ratio between the timing resistor R_T and the timing capacitor C_T. Refer to figures 6 and 7 to select appropriate values for R_T and C_T.

$$f_{SW} = \frac{1}{T_{SW}};\ T_{SW} = t_{CH} + t_{DIS}$$

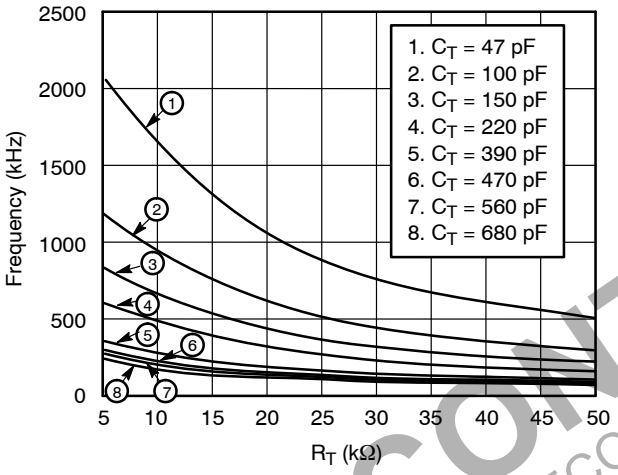


Figure 6. Frequency vs. R_T for Discrete Capacitor Values

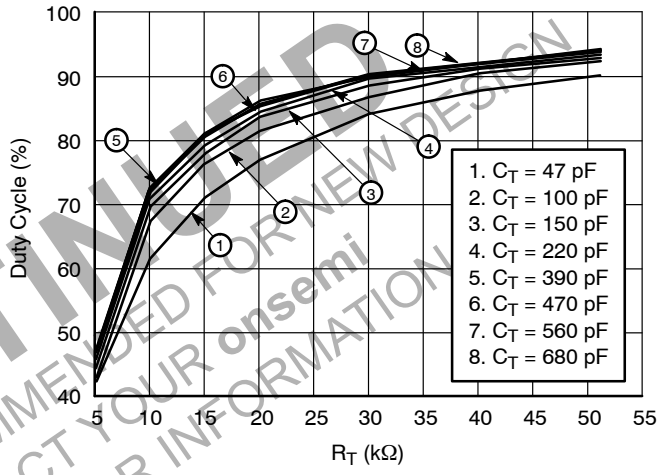


Figure 7. Duty Cycle vs. R_T for Discrete Capacitor Values

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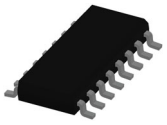
PACKAGE THERMAL DATA

Parameter		SOIC−16	Unit
$R_{\theta JC}$	Typical	28	°C/W
$R_{\theta JA}$	Typical	115	°C/W

ORDERING INFORMATION

Device	Package	Shipping†
CS51021AEDR16G	SOIC−16 (Pb−Free)	2500 Tape & Reel

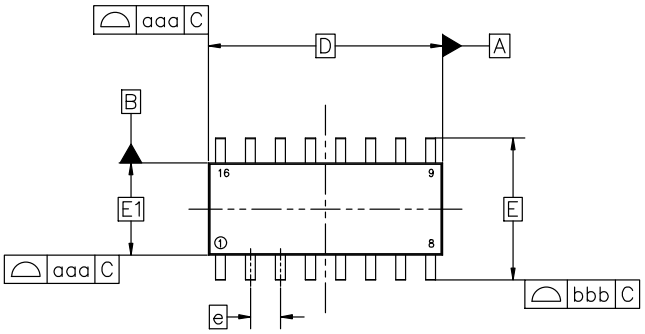
†For information on tape and reel specifications, including part orientation and tape sizes, please refer to our Tape and Reel Packaging Specifications Brochure, BRD8011/D.



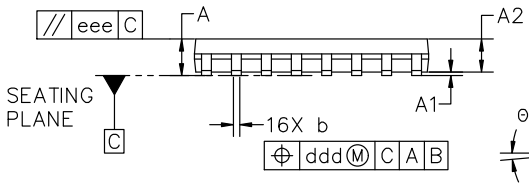
SOIC−16 9.90x3.90x1.37 1.27P
CASE 751B
ISSUE M

DATE 18 OCT 2024

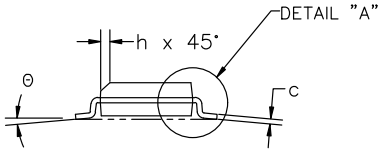
NOTES:
1. DIMENSIONING AND TOLERANCING PER ASME Y14.5M, 2018.
2. DIMENSION IN MILLIMETERS. ANGLE IN DEGREES.
3. DIMENSIONS D AND E1 DO NOT INCLUDE MOLD PROTRUSION.
4. MAXIMUM MOLD PROTRUSION 0.15mm PER SIDE.
5. DIMENSION b DOES NOT INCLUDE DAMBAR PROTRUSION. ALLOWABLE DAMBAR PROTRUSION SHALL BE 0.127mm TOTAL IN EXCESS OF THE b DIMENSION AT MAXIMUM MATERIAL CONDITION.



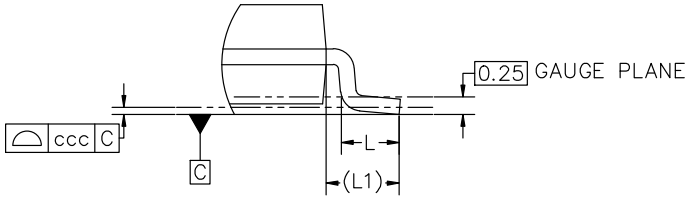
TOP VIEW



SIDE VIEW

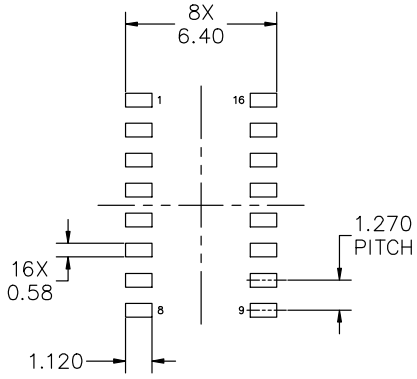


END VIEW



DETAIL "A"
Scale 3:1

MILLIMETERS			
DIM	MIN	NOM	MAX
A	1.35	1.55	1.75
A1	0.10	0.18	0.25
A2	1.25	1.37	1.50
b	0.35	0.42	0.49
c	0.19	0.22	0.25
D	9.90 BSC		
E	6.00 BSC		
E1	3.90 BSC		
e	1.27 BSC		
h	0.25	−−−	0.50
L	0.40	0.83	1.25
L1	1.05 REF		
Θ	0°	−−−	7°
TOLERANCE OF FORM AND POSITION			
aaa	0.10		
bbb	0.20		
ccc	0.10		
ddd	0.25		
eee	0.10		



RECOMMENDED MOUNTING FOOTPRINT

*FOR ADDITIONAL INFORMATION ON OUR PB−FREE STRATEGY AND SOLDERING DETAILS, PLEASE DOWNLOAD THE onsemi SOLDERING AND MOUNTING TECHNIQUES REFERENCE MANUAL, SOLDERRM/D

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DESCRIPTION:	**SOIC−16 9.90X3.90X1.37 1.27P**		**PAGE 1 OF 2**

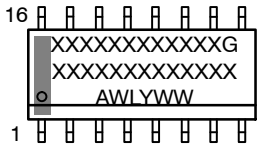
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SOIC−16 9.90x3.90x1.37 1.27P
CASE 751B
ISSUE M

DATE 18 OCT 2024

GENERIC MARKING DIAGRAM*



XXXXX = Specific Device Code
A = Assembly Location
WL = Wafer Lot
Y = Year
WW = Work Week
G = Pb−Free Package

*This information is generic. Please refer to device data sheet for actual part marking. Pb−Free indicator, “G” or microdot “▪”, may or may not be present. Some products may not follow the Generic Marking.

STYLE 1:

PIN	
1.	COLLECTOR
2.	BASE
3.	EMITTER
4.	NO CONNECTION
5.	EMITTER
6.	BASE
7.	COLLECTOR
8.	COLLECTOR
9.	BASE
10.	EMITTER
11.	NO CONNECTION
12.	EMITTER
13.	BASE
14.	COLLECTOR
15.	EMITTER
16.	COLLECTOR

STYLE 2:

PIN	
1.	CATHODE
2.	ANODE
3.	NO CONNECTION
4.	CATHODE
5.	CATHODE
6.	NO CONNECTION
7.	ANODE
8.	CATHODE
9.	CATHODE
10.	ANODE
11.	NO CONNECTION
12.	CATHODE
13.	CATHODE
14.	NO CONNECTION
15.	ANODE
16.	CATHODE

STYLE 3:

PIN	
1.	COLLECTOR, DYE #1
2.	BASE, #1
3.	EMITTER, #1
4.	COLLECTOR, #1
5.	COLLECTOR, #2
6.	BASE, #2
7.	EMITTER, #2
8.	COLLECTOR, #2
9.	COLLECTOR, #3
10.	BASE, #3
11.	EMITTER, #3
12.	COLLECTOR, #3
13.	COLLECTOR, #4
14.	BASE, #4
15.	EMITTER, #4
16.	COLLECTOR, #4

STYLE 4:

PIN	
1.	COLLECTOR, DYE #1
2.	COLLECTOR, #1
3.	COLLECTOR, #2
4.	COLLECTOR, #2
5.	COLLECTOR, #3
6.	COLLECTOR, #3
7.	COLLECTOR, #4
8.	COLLECTOR, #4
9.	BASE, #4
10.	EMITTER, #4
11.	BASE, #3
12.	EMITTER, #3
13.	BASE, #2
14.	EMITTER, #2
15.	BASE, #1
16.	EMITTER, #1

STYLE 5:

PIN	
1.	DRAIN, DYE #1
2.	DRAIN, #1
3.	DRAIN, #2
4.	DRAIN, #2
5.	DRAIN, #3
6.	DRAIN, #3
7.	DRAIN, #4
8.	DRAIN, #4
9.	GATE, #4
10.	SOURCE, #4
11.	GATE, #3
12.	SOURCE, #3
13.	GATE, #2
14.	SOURCE, #2
15.	GATE, #1
16.	SOURCE, #1

STYLE 6:

PIN	
1.	CATHODE
2.	CATHODE
3.	CATHODE
4.	CATHODE
5.	CATHODE
6.	CATHODE
7.	CATHODE
8.	CATHODE
9.	ANODE
10.	ANODE
11.	ANODE
12.	ANODE
13.	ANODE
14.	ANODE
15.	ANODE
16.	ANODE

STYLE 7:

PIN	
1.	SOURCE N-CH
2.	COMMON DRAIN (OUTPUT)
3.	COMMON DRAIN (OUTPUT)
4.	GATE P-CH
5.	COMMON DRAIN (OUTPUT)
6.	COMMON DRAIN (OUTPUT)
7.	COMMON DRAIN (OUTPUT)
8.	SOURCE P-CH
9.	SOURCE P-CH
10.	COMMON DRAIN (OUTPUT)
11.	COMMON DRAIN (OUTPUT)
12.	COMMON DRAIN (OUTPUT)
13.	GATE N-CH
14.	COMMON DRAIN (OUTPUT)
15.	COMMON DRAIN (OUTPUT)
16.	SOURCE N-CH

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