



0.5 dB LSB GaAs MMIC 5-BIT DIGITAL ATTENUATOR, 0.1 - 30 GHz

Typical Applications

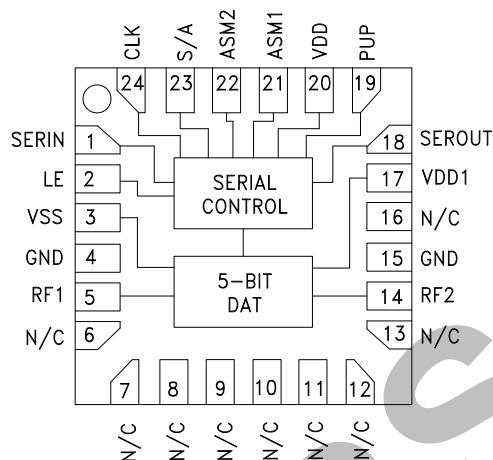
The HMC1019LP4E is ideal for:

- Fiber Optics & Broadband Telecom
- Microwave Radio & VSAT
- Military Radios, Radar & ECM
- Space Applications
- Sensors
- Test & Measurement Equipment

Features

- 0.5 dB LSB Steps to 15.5 dB
- TTL/CMOS Compatible, Serial Control
- Unique Asynchronous Mode Control Allows Immediate Attenuation Level Setting
- ±0.5 dB Typical Bit Error
- High Input IP3: +45 dBm
- 24 Lead 4x4mm SMT Package: 16mm²

Functional Diagram



General Description

The HMC1019LP4E is a broadband 5-bit GaAs IC digital attenuator in a low cost leadless surface mount package. Covering 0.1 to 30.0 GHz, the insertion loss is less than 4.0 dB typical. The attenuator bit values are 0.5 (LSB), 1, 2, 4, 8 for a total attenuation of 15.5 dB. Attenuation accuracy is excellent at ±0.3 dB typical step error with an IIP3 of +45 dBm. The control interface is CMOS/TTL compatible and accepts a three wire serial input. The HMC1019LP4E features a user selectable power up state and a serial-output port for cascading other Hittite serial controlled components.

Electrical Specifications, $T_A = +25^\circ\text{C}$, With $V_{dd} = V_{dd1} = +5\text{V}$, $V_{ss} = -5\text{V}$

Parameter	Frequency (GHz)	Min.	Typ.	Max.	Units
Insertion Loss	0.1 - 18.0 GHz		3.0	4.5	dB
	18.0 - 26.5 GHz		4.0	6.0	dB
	26.5 - 30.0 GHz		5.0	6.5	dB
Attenuation Range	0.1 - 30.0 GHz		31		dB
Return Loss (RF1 & RF2, All Atten. States)	0.1 - 30.0 GHz		12		dB
Attenuation Accuracy: (Referenced to Insertion Loss)	0.5 - 7.5 dB States	± (0.3 + 6%) of Atten. Setting Max			dB
	8 - 15.5 dB States	± (0.3 + 8%) of Atten. Setting Max			dB
Input Power for 0.1 dB Compression	0.1 - 0.5 GHz		22		dBm
	0.5 - 30.0 GHz		27		dBm
Input Third Order Intercept Point (Two-Tone Input Power= 0 dBm Each Tone)	0.1 - 0.5 GHz		42		dBm
	0.5 - 30.0 GHz		45		dBm
Switching Characteristics	0.1 - 30.0 GHz	tRISE, tFALL (10/90% RF)	60		ns
		tON/tOFF (50% CTL to 10/90% RF)	90		ns
I _{dd1}	0.1 - 30.0 GHz	2.5	4.5	6.5	mA
I _{ss}	0.1 - 30.0 GHz	-7.0	-5.0	-3.0	mA

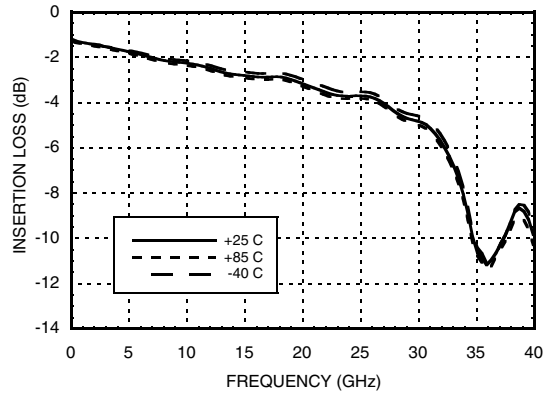
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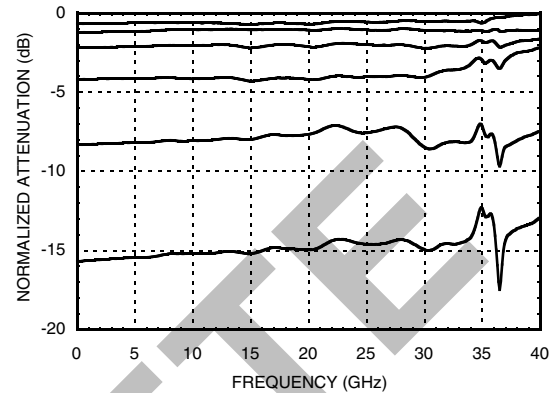


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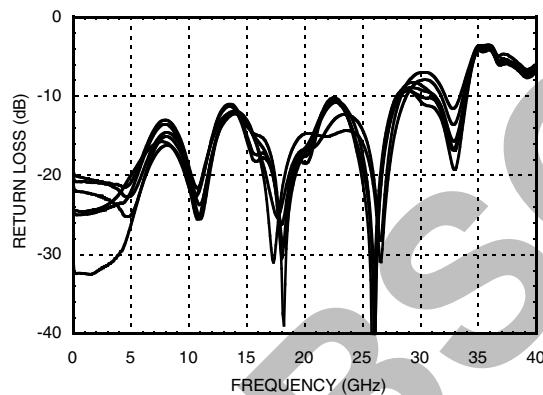
Insertion Loss vs. Temperature



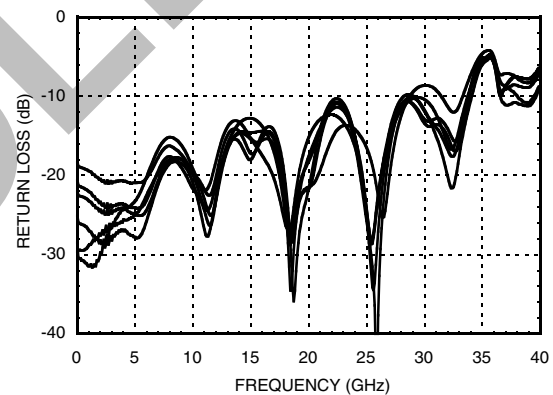
Normalized Attenuation
(Only Major States are Shown)



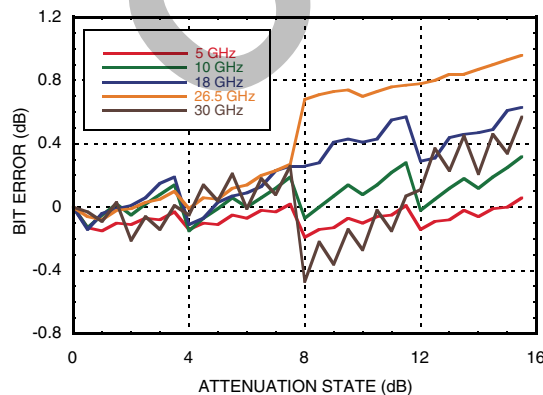
Input Return Loss
(Only Major States are Shown)



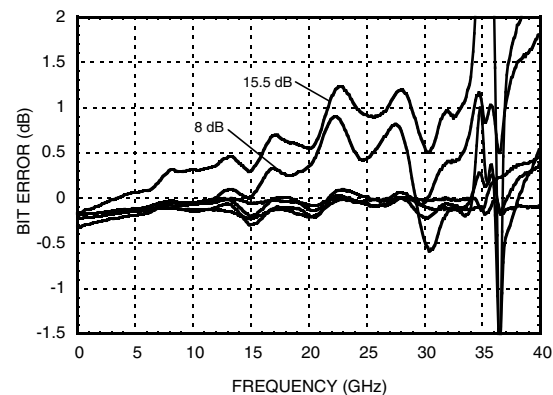
Output Return Loss
(Only Major States are Shown)



Bit Error vs. Attenuation State

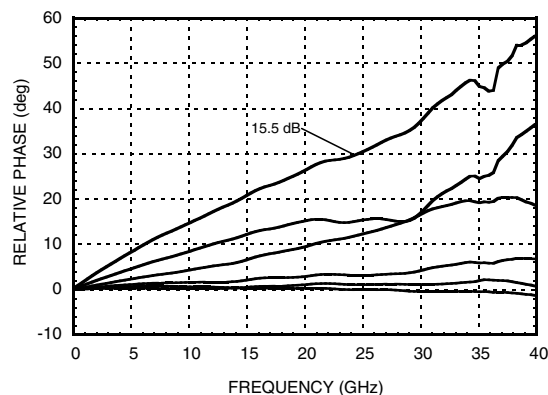


Bit Error vs. Frequency
(Only Major States are Shown)



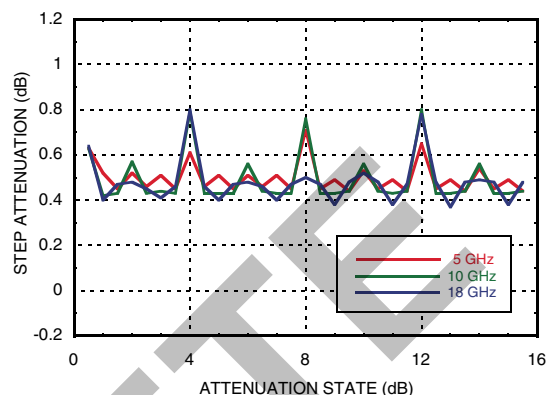


Relative Phase vs. Frequency
(Only Major States are Shown)

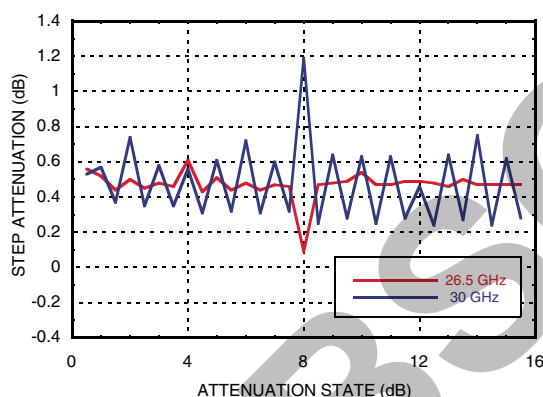


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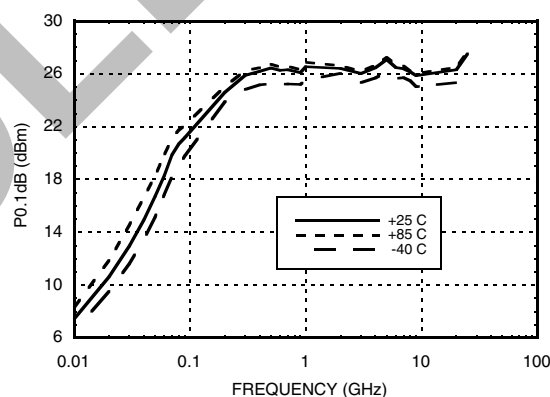
Step Attenuation vs. Attenuation State
0.1 - 18 GHz



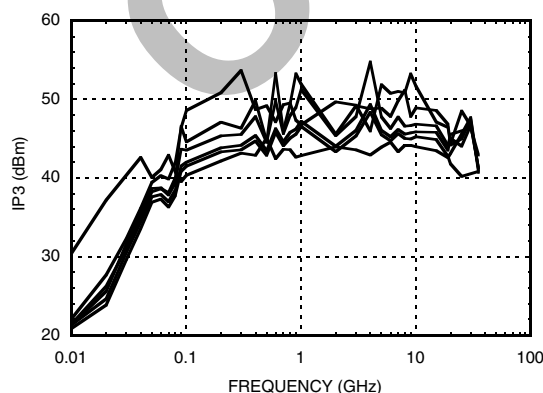
Step Attenuation vs. Attenuation State
18 - 30 GHz



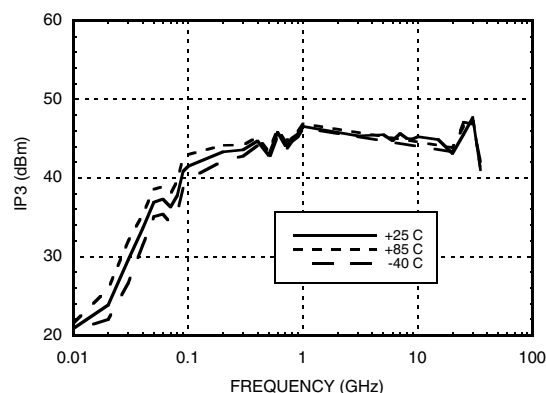
Input Power for 0.1 dB Compression



Input IP3 Over Major Attenuation States



Input IP3 vs. Temperature
(Minimum Attenuation State)

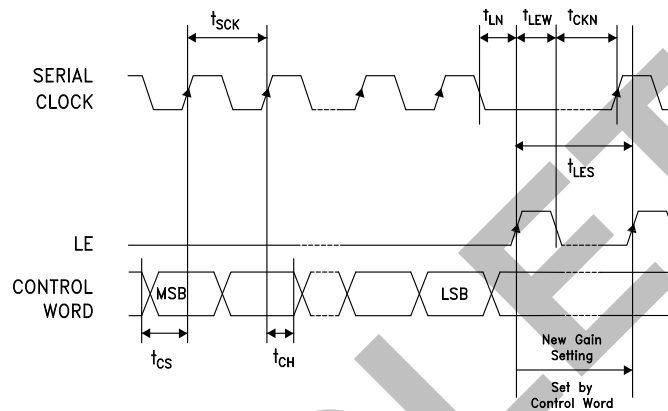




Serial Control Interface

The HMC1019LP4E contains a 3-wire SPI compatible digital interface (SERIN, CLK, LE). The serial control interface is activated when S/A is kept high. The 5-bit serial word must be loaded MSB first as a 6-bit word with the first bit ignored. The positive-edge sensitive CLK and LE requires clean transitions. If mechanical switches are used, sufficient debouncing should be provided. When LE is high, 5-bit data in the serial input register is transferred to the attenuator. When LE is high CLK is masked to prevent data transition during output loading.

For all modes of operations, the state will stay constant while LE is kept low.



Serial Mode Truth Table

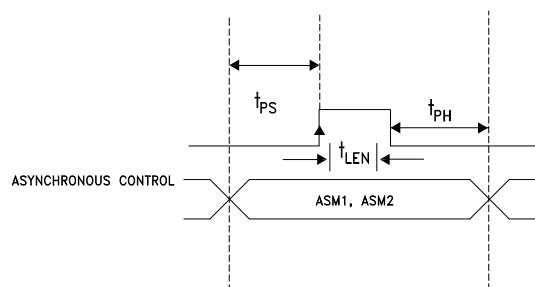
Control Voltage Input					Attenuation State
P4 8 dB	P3 4 dB	P2 2 dB	P1 1 dB	P0 0.5 dB	RF1 - RF2
High	High	High	High	High	Reference I.L.
High	High	High	High	Low	0.5 dB
High	High	High	Low	High	1 dB
High	High	Low	High	High	2 dB
High	Low	High	High	High	4 dB
Low	High	High	High	High	8 dB
Low	Low	Low	Low	Low	15.5 dB

Any combination of the above states will provide an attenuation approximately equal to the sum of the bits selected.

Parameter	Typ.
Min. serial period, t_{SCK}	100 ns
Control set-up time, t_{CS}	20 ns
Control hold-time, t_{CH}	20 ns
LE setup-time, t_{LN}	10 ns
Min. LE pulse width, t_{LEW}	10 ns
Min LE pulse spacing, t_{LES}	630 ns
Serial clock hold-time from LE, t_{CKN}	10 ns
Hold Time, t_{PH}	0 ns
Latch Enable Minimum Width, t_{LEN}	10 ns
Setup Time, t_{PS}	2 ns

Asynchronous Mode

The HMC1019LP4E can be switched to an asynchronous mode to change the attenuation state rapidly to one of four predefined states. The logic state of ASM1-ASM2 determines one of the four attenuation states in the asynchronous mode per truth table. The asynchronous mode works either directly or latched. To activate the direct-asynchronous-mode, S/A needs to be at logic low and LE needs to be at logic high. In the direct-asynchronous-mode, any change in the logic state of ASM1-ASM2 directly affects the attenuation state. In the latched-asynchronous-mode, the attenuation state changes per the asynchronous mode truth table when S/A is at logic low and LE is pulsed per the timing diagram. The attenuation stays constant (latched) as long as LE stays low. In the asynchronous mode, the inputs SERIN and CLK do not affect the attenuation state.


Timing Diagram (Latched Asynchronous Mode)

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Asynchronous Mode Truth Table

ASM1	ASM2	Attenuation State RF1-RF2
High	High	Reference I.L.
High	Low	1.5 dB
Low	High	14 dB
Low	Low	15.5 dB

Power-Up States

If LE is set to logic LOW at power-up, the logic state of PUP determines the power-up state of the part per PUP truth table. If the LE is set to logic HIGH at power-up, the logic state of ASM1-ASM2 determines the power-up state of the part per truth table for the asynchronous mode. The attenuator latches in the desired power-up state approximately 200 ms after power-up.

PUP Truth Table

PUP	Attenuation State
High	Reference I.L.
Low	15.5 dB

Note: The logic state of ASM1-ASM2 determines the power-up state of the part per truth table for the asynchronous mode when LE is high at power-up.

Bias Voltages & Currents

Vdd	+5V @ 0.2 mA
Vdd1	+5V @ 4.5 mA
Vss	-5V @ 5 mA

Control Voltage

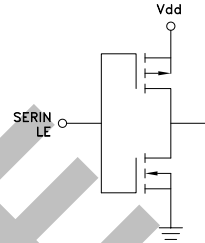
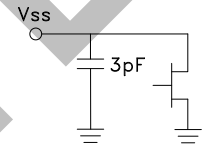
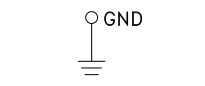
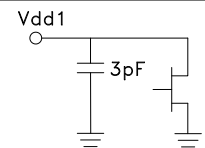
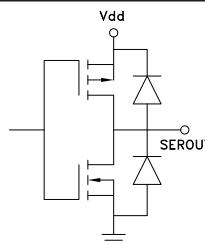
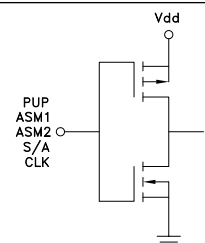
State	Bias Condition
Low	0 to 0.8V @ 1 μ A
High	2 to 5V @ 1 μ A





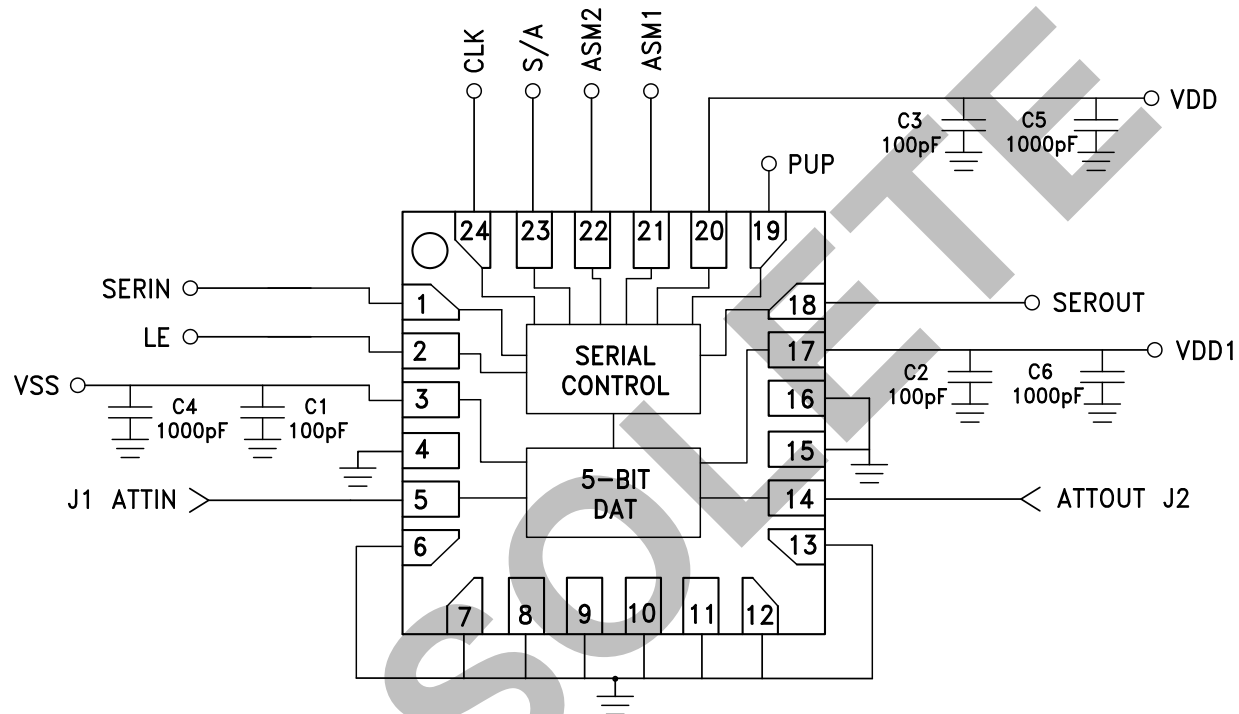
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Pin Descriptions

Pad Number	Function	Description	Interface Schematic
1 2	SERIN LE	See truth table, control voltage table and timing diagram.	
3	Vss	Negative Bias -5V	
4, 15	GND	These pins and package bottom must be connected to RF/DC ground.	
6-13, 16	N/C	The pins are not connected internally; however, all data shown herein was measured with these pins connected to RF/DC ground externally.	
5, 14	RF1, RF2	These pins are DC coupled and matched to 50 Ohm. Blocking capacitors are required if RF line potential is not equal to 0V.	
17	Vdd1	Positive Bias +5V	
18	SEROUT	Serial input data delayed by 6 clock cycles.	
19 21 22 23 24	PUP ASM1 ASM2 S/A CLK	See truth table, control voltage table and timing diagram.	
20	Vdd	Serial Controller Bias +5V	

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Application Circuit





Hittite
600-00196-00-2

THRU CAL

Item	Description
J1, J2	2.9 mm PC Mount RF Connector
J3, J4, J6	DC Connector
J5	2mm DC Header
C1-C3	100 pF Capacitor, 0402 Pkg.
C4-C6	1000 pF Capacitor, 0402 Pkg.
U1	HMC1019LP4E Digital Attenuator
PCB ^[2]	600-00196-00-2 Evaluation Board

[1] Reference this number when ordering complete evaluation PCB

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**Notes:**

v00.0911

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